

# RSX-11M Operating System Internals

Student Workbook

# RSX-11M Operating System Internals

Student Workbook

Prepared by Educational Services  
of  
Digital Equipment Corporation

Copyright © 1983 by Digital Equipment Corporation  
All Rights Reserved

The reproduction of this material, in part or whole, is strictly prohibited.  
For copy information, contact the Educational Services Department,  
Digital Equipment Corporation, Bedford, Massachusetts 01730.

Printed in U.S.A.

The information in this document is subject to change without notice  
and should not be construed as a commitment by Digital Equipment  
Corporation. Digital Equipment Corporation assumes no responsibility  
for any errors that may appear in this document.

The software described in this document is furnished under a license  
and may not be used or copied except in accordance with the terms of  
such license.

Digital Equipment Corporation assumes no responsibility for the use  
or reliability of its software on equipment that is not supplied by Digital.

**The manuscript for this book was created using DIGITAL Standard  
Runoff. Book production was done by Educational Services  
Development and Publishing in South Lawrence, MA.**

The following are trademarks of Digital Equipment Corporation:

<b>digital</b>	DECTape	Rainbow
DATATRIEVE	DECUS	RSTS
DEC	DECwriter	RSX
DECmate	DIBOL	UNIBUS
DECnet	MASSBUS	VAX
DECset	PDP	VMS
DECsystem-10	P/OS	VT
DECSYSTEM-20	Professional	Work Processor

# CONTENTS

## SG STUDENT GUIDE

INTRODUCTION . . . . .	3
COURSE GOALS . . . . .	3
NON-GOALS. . . . .	4
PREREQUISITES. . . . .	4
COURSE ORGANIZATION. . . . .	4
Modules. . . . .	5
RESOURCES. . . . .	7

## 1 OVERVIEW OF RSX-11M

DESIGN GOALS . . . . .	13
CHARACTERISTICS OF RSX-11M . . . . .	14
System Features. . . . .	14
Major Components of RSX-11M. . . . .	15
THE EXECUTIVE. . . . .	16
Components . . . . .	16
Use of Physical Memory . . . . .	16
THE FILE SYSTEM. . . . .	18
Design Goals . . . . .	18
Components . . . . .	18
THE UTILITIES. . . . .	20

## 2 THE SYSTEM DATA BASE

STATIC AND DYNAMIC DATA STRUCTURES . . . . .	25
The Dynamic Storage Region . . . . .	25
TASK-RELATED DATA STRUCTURES AND LISTS . . . . .	29
The Task Control Block (TCB) . . . . .	29
The System Task Directory (STD). . . . .	33
The Active Task List (ATL) . . . . .	35
PARTITION-RELATED DATA STRUCTURES AND LISTS. . . . .	37
The Partition Control Block (PCB). . . . .	37
The Partition List . . . . .	40
DEVICE-RELATED DATA STRUCTURES AND LISTS . . . . .	43
The Device Control Block (DCB) . . . . .	43
The Device List. . . . .	44
Other Structures . . . . .	45
THE CLOCK QUEUE. . . . .	46
The Clock Queue Control Block. . . . .	46
The Clock Queue. . . . .	47

### 3 EXECUTIVE MODULES

OVERVIEW . . . . .	53
PRINCIPAL EXECUTIVE MODULES. . . . .	54
System Common (SYSCM). . . . .	54
System Entrance and Exit Routines (SYSXT). . . . .	55
DSR Allocation Routines (CORAL). . . . .	55
I/O Related Routines (IOSUB) . . . . .	56
PLAS Routines (PLSUB). . . . .	56
Queue Manipulation Routines (QUEUE). . . . .	56
Task Request Related Routines (REQSB). . . . .	57
SST Service Routines (SSTSR) . . . . .	57
Time Dependent Scheduling (TDSCH). . . . .	58
System Initialization (INITL). . . . .	58
DIRECTIVE MODULES. . . . .	61
Resident Directive Module (DRSUB). . . . .	61
Directive Dispatches (DRDSP) . . . . .	61
DEVICE DRIVER MODULES. . . . .	64
System Device Tables (SYSTB) . . . . .	64
RK05 Driver (DKDRV). . . . .	64

### 4 FILE SYSTEM OVERVIEW

CONCEPTS . . . . .	71
FILES-11 . . . . .	71
Files. . . . .	73
Retrieval Pointers . . . . .	78
File Directories . . . . .	80
FILES-11 VOLUMES . . . . .	81
The Standard Files . . . . .	81
The Index File . . . . .	82
The Bitmap File. . . . .	85
The Master File Directory. . . . .	86
The Badblock File. . . . .	86
The System Checkpoint File . . . . .	87
FUNCTIONS OF THE FILE SYSTEM . . . . .	88
Creating a FILES-11 Volume . . . . .	88
Creating a File. . . . .	89
Accessing a File . . . . .	90
THE FILE PROCESSOR . . . . .	91
File Control Processors. . . . .	91
Logical Units. . . . .	92
Data Structures. . . . .	94
Mounting a Volume. . . . .	99
Opening a File . . . . .	100

## 5 SYSTEM GENERATION

OVERVIEW . . . . .	107
SYSGEN Functions . . . . .	107
The SYSGEN Process . . . . .	108
Types of SYSGEN. . . . .	109
New Features for Version 4.0 . . . . .	110
PREPARING FOR SYSGEN . . . . .	111
Distribution Kits. . . . .	111
Autopatch. . . . .	111
Individual Patches . . . . .	112
DETAILS OF SYSGEN. . . . .	113
Phase 1. . . . .	113
Phase 2. . . . .	114
Phase 3. . . . .	115
EXECUTIVE OPTIONS. . . . .	116
Standard Feature Executive . . . . .	116
The Terminal Driver. . . . .	117
Choosing a File Processor. . . . .	118
USING VMR. . . . .	119
Overview of VMR. . . . .	119
On a Mapped System . . . . .	120
On an Unmapped System. . . . .	121
SAVING THE NEW SYSTEM. . . . .	124

## 6 PHYSICAL AND VIRTUAL MEMORY

CONCEPTS . . . . .	131
Physical Address . . . . .	131
Virtual Addresses. . . . .	131
Unmapped Systems . . . . .	131
Mapped Systems . . . . .	133
MEMORY MANAGEMENT. . . . .	136
Overview . . . . .	136
Memory Management Hardware . . . . .	137
Software Use of Memory Management. . . . .	141
ALLOCATING PHYSICAL MEMORY . . . . .	145
Partitions . . . . .	145
The Partition Wait Queue . . . . .	147
USING PHYSICAL MEMORY. . . . .	149
Loading Tasks. . . . .	149
Checkpointing. . . . .	150
Shuffling. . . . .	153
USING VIRTUAL MEMORY . . . . .	155
Attaching. . . . .	155
Mapping. . . . .	157

## 7 TASK MANAGEMENT

THE TASK IMAGE . . . . .	165
The Task Image File . . . . .	165
The Checkpoint Area . . . . .	165
The Task Header . . . . .	167
The Task Image . . . . .	168
RUNNING A TASK . . . . .	170
Installing . . . . .	171
Activating . . . . .	172
Allocating Memory . . . . .	172
Loading . . . . .	172
Context Switching . . . . .	174
SCHEDULING A TASK . . . . .	177
Priority . . . . .	177
Round Robin . . . . .	177
Disk Swapping . . . . .	180
Clock Scheduling . . . . .	181
AST Processing . . . . .	183
TASK TERMINATION . . . . .	187
Synchronous System Traps . . . . .	188

## 8 SYSTEM SYNCHRONIZATION

OVERVIEW . . . . .	195
System Synchronization Functions . . . . .	196
Software States . . . . .	196
Software Processes . . . . .	197
The Stack Depth Indicator . . . . .	198
Traps and Interrupts . . . . .	198
TRAP PROCESSING . . . . .	200
The Directive Save Routine . . . . .	201
The Directive Exit Routine . . . . .	201
INTERRUPT PROCESSING . . . . .	205
The Interrupt Save Routine . . . . .	205
Device Driver Processing . . . . .	207
The Interrupt Exit Routine . . . . .	207
FORK PROCESSING . . . . .	210
The FORK Block . . . . .	210
The FORK List . . . . .	210
PRIVILEGED TASKS . . . . .	216
Processing a Privileged Task . . . . .	217

## 9 WRITING PRIVILEGED TASKS

OVERVIEW . . . . .	227
Why Write a Privileged Task . . . . .	227
Privileged Task Structure . . . . .	228

Restrictions on Privileged Tasks . . . . .	230
CREATING A PRIVILEGED TASK . . . . .	231
Assembling a Privileged Task . . . . .	231
Taskbuilding a Privileged Task . . . . .	232
SAMPLE PRIVILEGED TASKS. . . . .	233
Tracing Through System Lists . . . . .	233
Calling Executive Routines . . . . .	238

## 10 SYSTEM CRASHES

CRASH PROCESSING . . . . .	251
Causes of Crashes. . . . .	251
Crash Sequences. . . . .	251
Obtaining a Crash Dump Analysis. . . . .	253
CRASH DUMP ANALYSIS. . . . .	254
Finding the Cause of a System Crash. . . . .	254
Basic Information Provided in a CDA. . . . .	256
AN EXAMPLE . . . . .	262

## 11 DIRECTIVE PROCESSING

THE USER TASK INTERFACE. . . . .	291
Directive Parameter Block. . . . .	291
Directive Status Word. . . . .	296
THE DIRECTIVE DISPATCHER . . . . .	297
The Directive Dispatch Table . . . . .	297
DIRECTIVE PROCESSING ROUTINES. . . . .	301
The Interface. . . . .	301
The Directive Commons. . . . .	303
Send/Receive Processing. . . . .	307
Parent/Offspring Tasking . . . . .	309
Memory Management Processing . . . . .	313
ADDING A USER-WRITTEN DIRECTIVE. . . . .	315
Structuring the Directive Parameter Block. . . . .	315
Changes to the Directive Dispatcher. . . . .	316
The Directive Processing Routine and Macros. . . . .	318
Adding a Directive to the System . . . . .	320

## 12 I/O PROCESSING

OVERVIEW . . . . .	327
Components of the I/O System . . . . .	327
Initiating I/O From a User Task. . . . .	330
Processing I/O Request in DRQIO. . . . .	331
QIO PROCESSING . . . . .	332
Logical Units. . . . .	332
Processing Within DRQIO. . . . .	333



The ACP Function Checks . . . . .	334
Queuing I/O Requests . . . . .	338
ANCILLARY CONTROL PROCESSORS . . . . .	339
Types of ACPS . . . . .	339
The FILES-11 (F11ACP) . . . . .	343

### 13 DEVICE DRIVER PROCESSING

OVERVIEW . . . . .	349
Methods of Performing I/O . . . . .	349
Design Philosophy . . . . .	350
General Flow . . . . .	351
DRIVER DATA BASE . . . . .	352
Device Control Block (DCB) . . . . .	352
Unit Control Block (UCB) . . . . .	353
Status Control Block (SCB) . . . . .	357
I/O Packet . . . . .	359
DRIVER STRUCTURE . . . . .	364
Driver Entry Points . . . . .	364
Driver Dispatch Table . . . . .	365
DRIVER PROCESSING . . . . .	369
Initiate I/O . . . . .	369
Kill I/O . . . . .	370
Device Timeout . . . . .	371
Powerfail . . . . .	372
Interrupt Processing . . . . .	372
ADVANCED DRIVER FEATURES . . . . .	375
Loadable Drivers . . . . .	375
The Interrupt Control Block . . . . .	375
Resident and Loadable Data Base . . . . .	378
UNIBUS Mapping Registers . . . . .	378
Connect-to-Interrupt . . . . .	382

### FIGURES

1-1	Typical Use of Physical Memory . . . . .	17
1-2	The File System . . . . .	19
2-1	The List of Free Space in DSR . . . . .	26
2-2	Allocating DSR . . . . .	27
2-3	Deallocating DSR . . . . .	28
2-4	The Task Control Block . . . . .	30
2-5	The System Task Directory . . . . .	34
2-6	The Active Task List . . . . .	36
2-7	The Partition Control Block . . . . .	38
2-8	The Partition List . . . . .	41

2-9	Relationship Between Task and Partition Structures. . . . .	42
2-10	The Device Control Block. . . . .	43
2-11	The Device List . . . . .	44
2-12	Other Data Structures . . . . .	45
2-13	The Clock Queue Control Block . . . . .	46
2-14	The Clock Queue . . . . .	47
4-1	The File System . . . . .	72
4-2	The File Header for a Task Image. . . . .	75
4-3	Retrieval Pointer . . . . .	78
4-4	Mapping Virtual to Logical Blocks . . . . .	79
4-5	Directory Record . . . . .	80
4-6	Structure of the Index File . . . . .	84
4-7	The Bitmap File . . . . .	85
4-8	Two Level Directory Structure . . . . .	86
4-9	Creating a File . . . . .	89
4-10	Accessing a File. . . . .	90
4-11	The Logical Unit Table. . . . .	93
4-12	The Volume Control Block. . . . .	95
4-13	The File Control Block. . . . .	97
4-14	FILES-11 Window Block . . . . .	98
4-15	Mounting a Volume . . . . .	99
4-16	Opening a File. . . . .	101
4-17	Shared Access . . . . .	102
5-1	Partition Structure on Mapped Systems . . . . .	120
5-2	Partition Structure on Unmapped 24K to 28K Systems. . . . .	122
5-3	Partition Structure on Unmapped 16K to 24K Systems. . . . .	123
5-4	Saved System Image. . . . .	125
6-1	Typical Unmapped System . . . . .	132
6-2	Typical Mapped System with 18-bit Addressing. . . . .	134
6-3	Typical Mapped System with 22-bit Addressing. . . . .	135
6-4	Registers Used by Memory Management . . . . .	138
6-5	Active Page Registers . . . . .	139
6-6	Page Address Registers. . . . .	140
6-7	Use of Memory Management by a Nonprivileged Task. . . . .	142
6-8	Use of Memory Management by the Executive . . . . .	143
6-9	Use of Memory Management by a Privileged Task . . . . .	144
6-10	Subpartitions of a Task Partition . . . . .	146
6-11	The Partition Wait Queue. . . . .	148
6-12	Steps in Checkpointing a Task . . . . .	150
6-13	System Checkpoint Files . . . . .	151
6-14	Shuffling Tasks . . . . .	154
6-15	The Attachment Descriptor Block . . . . .	155
6-16	Attaching a Task to a Region. . . . .	156
6-17	Task Virtual Address Window Blocks. . . . .	158
6-18	Mapping a Task Address Window to a Region . . . . .	159



# **STUDENT GUIDE**

7-1	Task Image File . . . . .	166
7-2	The Task Header . . . . .	169
7-3	The Loader Queue . . . . .	173
7-4	Context Switching . . . . .	174
7-5	The Data Structures for an Active Task . . . . .	176
7-6	Round Robin Scheduling . . . . .	178
7-7	Time Dependent Scheduling . . . . .	182
7-8	AST Processing . . . . .	184
7-9	SST Processing . . . . .	189
8-1	Handling Traps and Interrupts by the Hardware . . . . .	199
8-2	EMT Instruction Execution . . . . .	200
8-3	The Directive Save Routine . . . . .	202
8-4	Common Processing in the Directive Dispatcher . . . . .	203
8-5	The Directive Exit Routine . . . . .	204
8-6	Interrupt Processing . . . . .	206
8-7	The Interrupt Save Routine . . . . .	208
8-8	The Interrupt Exit Routine . . . . .	209
8-9	The FORK Block in the SCB . . . . .	211
8-10	The FORK List . . . . .	211
8-11	Interrupting a Task . . . . .	212
8-12	Interrupt Executive Processing a Directive . . . . .	213
8-13	Interrupt Executive Processing an Interrupt . . . . .	214
8-14	Interrupt Executive in an Idle Loop . . . . .	215
8-15	Privileged Task Processing . . . . .	218
8-16	Privileged Task Switches Stack and Returns . . . . .	219
8-17	System Synchronization Logic . . . . .	220
10-1	The Stack After a System Crash - IOT . . . . .	257
10-2	The Stack After a System Crash - EMT . . . . .	258
10-3	The Stack After a System Crash - SST . . . . .	259
11-1	Directive Macros . . . . .	292
11-2	The Directive Parameter Block . . . . .	295
11-3	The Directive Dispatch Table . . . . .	298
11-4	Processing in DRDSP . . . . .	299
11-5	The Directive Commons . . . . .	304
11-6	Send/Receive Processing . . . . .	307
11-7	Parent/Offspring Tasking . . . . .	310
11-8	Memory Management Processing . . . . .	314
11-9	Directive Parameter Block for New Directive . . . . .	315
11-10	Assembling and Taskbuilding the Processing Routine . . . . .	321
12-1	The I/O Process . . . . .	329
12-2	Logical Units . . . . .	332
12-3	Standard ACP . . . . .	340
12-4	User ACP . . . . .	341
12-5	Foreign ACP . . . . .	342

13-1	Unit Control Block for LP: . . . . .	355
13-2	Unit Control Block for DK: . . . . .	356
13-3	Status Control Block. . . . .	358
13-4	I/O Packet. . . . .	360
13-5	A Simple Configuration. . . . .	361
13-6	A Configuration with Multiple Units . . . . .	362
13-7	A Configuration with Multiple Controllers . . . . .	363
13-8	Driver Flow . . . . .	366
13-9	Interrupt Processing - Non DMA Device . . . . .	373
13-10	Interrupt Processing - DMA Device . . . . .	374
13-11	A Loadable Driver . . . . .	376
13-12	The Interrupt Control Block . . . . .	377
13-13	UNIBUS Mapping Registers. . . . .	379
13-14	Mapping Assignment Block List . . . . .	381
13-15	UMR Wait Queue. . . . .	381
13-16	Connect-to-Interrupt Processing . . . . .	383
13-17	The Interrupt Transfer Block. . . . .	384

## TABLES

2-1	Task Status Words . . . . .	32
2-2	Partition Status Words. . . . .	39
3-1	Executive Modules by Function . . . . .	59
3-2	Directive Processing Modules. . . . .	62
3-3	Standard Device Drivers . . . . .	65
7-1	Synchronous System Traps. . . . .	188
9-1	Pointers to System Lists. . . . .	234
9-2	Pointers to Data Structures . . . . .	235
9-3	Executive Pool Routines . . . . .	238
9-4	Executive Queuing Routines. . . . .	239
9-5	Other Executive Routines. . . . .	240
10-1	CDA Switches. . . . .	255
10-2	Fault Codes for SSTs. . . . .	260
11-1	Register Usage. . . . .	302
11-2	Directive Processing Routines . . . . .	306
12-1	Function Code Dispatch Vector . . . . .	335
12-2	Polish Routines . . . . .	336
13-1	Important Entries in the UCB. . . . .	354

## EXAMPLES

4-1	The File Header for a Data File . . . . .	76
4-2	The File Header for a Task Image. . . . .	77
9-1	Tracing Through System Lists. . . . .	236
9-2	Calling Executive Routines. . . . .	241
10-1	A Sample KERNEL Stack . . . . .	261
10-2	CDA - Volatile Registers. . . . .	264
10-3	CDA - KERNEL Stack. . . . .	265
10-4	CDA - System Common . . . . .	266
10-5	CDA - System Common Alphabetized Dump . . . . .	269
10-6	CDA - POOL Statistics . . . . .	270
10-7	CDA - Active Tasks: TT2. . . . .	272
10-8	CDA - Task Headers: TT2. . . . .	273
10-9	CDA - POOL Dump . . . . .	275
10-10	Listing of Task TT2 (DUMP). . . . .	277
10-11	Map of Task TT2 . . . . .	282
10-12	CDA of Task TT2 . . . . .	283
11-1	Macro Expansions for SEND DATA. . . . .	294
11-2	New Entry in the Directive Dispatch Table . . . . .	317
11-3	Processing Routine for New Directive. . . . .	318
11-4	Macros for New Directive. . . . .	319
13-1	A Skeleton Driver . . . . .	367
13-2	A Skeleton Driver Data Base . . . . .	368
13-3	UMR Address Relocation. . . . .	380
13-4	A Sample Connect-to-Interrupt Routine . . . . .	385

## INTRODUCTION

This course is designed for the programmer of an RSX-11M system. A system programmer must troubleshoot system problems and write needed privileged code.

As a system programmer, your responsibilities will include the following:

- Determining features needed on system.
- Performing System Generations (SYSGENS).
- Maintaining the software by installing patches.
- Determining the cause(s) of system crashes.
- Providing needed privileged tasks.
- Writing new directive code.
- Assisting application programmers with system problems.

This course is designed to give you the knowledge and skills necessary to carry out these tasks.

## COURSE GOALS

Upon completing this course, you should be able to:

1. Install and maintain RSX-11M software.
2. Use output from CDA to solve system problems.
3. Write privileged tasks which access the system data base.
4. Write privileged tasks which call system routines.
5. Write a new directive processing routine and add the directive to the system.
6. Determine system status by examining the system data base.
7. Use knowledge of the operating system to improve performance of applications software.

## STUDENT GUIDE

### NON-GOALS

The following are not goals of this course:

1. The course does not teach you how to write a device driver.
2. The course does not teach you how to create a user-written Command Line Interpreter.
3. The course does not teach you how to make any modifications to system source code. Specifically, it will not teach you how to modify DCL in any way.

### PREREQUISITES

You should have already taken RSX-11M Programming in FORTRAN/MACRO, or have equivalent experience using RSX-11M. You should also be able to read and understand MACRO-11 code.

### COURSE ORGANIZATION

The student workbook handout is organized into modules which correspond to the major topics covered by the instructor during the course. Each module is designed to support the lecture by providing you with notes and exercises to guide your study.

A module is composed of five parts:

1. An Introduction which provides an overview of the module. It explains in general terms what the module covers and how the material within the module is related to your needs. Often, it introduces some of the important concepts detailed in the module.
2. Objectives which list the knowledge and skills you should obtain as a result of studying the module. Read these before the corresponding lecture, and review them after completion of the module and its exercises.
3. Resources which provide a list of reference materials for further information about the topics of the module and related topics. You should familiarize yourself with the reference materials because they are your primary source of information after you complete the course.

Your instructor may suggest selected readings as preparation for a lecture, or for review and study after the lecture.



## STUDENT GUIDE

4. The module text which provides brief notes on topics covered in the lecture, with printed copies of lists, tables, diagrams, etc. your instructor may use in class. The texts provide you with notes to review after the lecture, and reduces somewhat the note-taking you must do during lecture.

Note that the module text is a supplement to the lecture. It is not intended to be tutorial reading for learning the material on your own. Nor is it intended to replace the function of reference manuals which fully document the software. You are strongly encouraged to supplement these notes with notes of your own and with references to the system documentation.

5. Module Exercises which are designed to help you practice and test the knowledge acquired during lecture and study. If you can perform all of the written and/or lab exercises at the end of the module, you have mastered the objectives of that module.

Your instructor may suggest particular lab exercises to concentrate on, if time or equipment limitations make it impossible to perform all of them. In addition, your instructor may provide additional suggestions for lab activities.

### Modules

There are thirteen modules of this course. The following is a brief list of their major topics:

1. OVERVIEW OF RSX-11M describes the operating system and its goals.
2. THE SYSTEM DATA BASE describes the most important data structures and lists in the system data base.
3. EXECUTIVE MODULES describes the most important Executive modules.
4. FILE SYSTEM OVERVIEW describes the structure of a FILES-11 volume and the data structures needed to process it.
5. SYSTEM GENERATION describes the system generation process. (For reference only; this module is optional.)
6. PHYSICAL AND VIRTUAL MEMORY describes partitions, allocation of memory to tasks, checkpointing, function and use of memory management.

## STUDENT GUIDE

7. TASK MANAGEMENT describes the life cycle of a task.
8. SYSTEM SYNCHRONIZATION describes trap and interrupt processing, and access to the system data base.
9. WRITING PRIVILEGED TASKS describes writing, assembling, and building privileged tasks.
10. SYSTEM CRASHES uses CDA to troubleshoot system problems.
11. DIRECTIVE PROCESSING describes the directive dispatcher, the directive dispatch table, and directive processing routines.
12. I/O PROCESSING describes the components of the I/O system, ACPs, and QIO processing.
13. DEVICE DRIVER PROCESSING describes the driver data base and the structure of standard device drivers.

## STUDENT GUIDE

### RESOURCES

1. RSX-11M Release Notes (AA-2573G-TC)

Contains the most recent version information and should be read thoroughly before any system generation. Includes information on patching.

2. RSX-11M System Generation and Installation Guide

Contains complete documentation on the installation and SYSGEN procedures.

3. RSX-11M/M-Plus I/O Operations Reference Manual

Contains documentation on the FCS macros and subroutines.

4. RSX-11M/M-Plus Executive Reference Manual

Contains descriptions of all system directives.

5. RSX-11M/M-Plus Crash Dump Analyzer

Explains how to use the CDA facilities.

6. RSX-11M Guide to Writing an I/O Driver

Contains a detailed description of the procedures involved in writing a new device driver.



# OVERVIEW OF RSX-11M



## **INTRODUCTION**

RSX-11M is designed to support many applications with particular emphasis on real-time applications. For this reason, a large number of services are provided to the programmer. This module presents a brief overview of these features, many of which will be examined in detail in later modules.

## **OBJECTIVES**

1. List the major design goals of RSX-11M.
2. List the major features of RSX-11M.
3. List the major components of RSX-11M.





## DESIGN GOALS

- Real-time system with
  - 8K word minimum Executive
  - 16K word minimal system (disk based, run time only)
  - 28K word system required for SYSGEN (version 4.0)
- Upward compatible with RSX-11D
- Support
  - All PDP-11 processors
  - Most processor options
  - Full line of peripherals
- Provide system and task synchronization not relying on task priorities
- Provide extensive user facilities
  - Complete file system
  - Multiple language processors
  - Debugging and maintenance tools
- Allow for any number of simultaneously executing user tasks
- Avoid using processor priority to synchronize access to system data base

## CHARACTERISTICS OF RSX-11M

### System Features

- Supports multiprogramming
  - Several tasks can be memory-resident and active at same time
  - Improves efficiency of system
  - Allows quick response to events
  
- Provides some user control of some system functions
  - Scheduling
  - File access
  
- Completely 'Event-Driven'
  - No 'monolithic monitor'
  - Executive entered only as a result of trap or hardware interrupt
  
- Disk-Based
  - Tasks stored on disk until loaded
  - Allows quick task startup
  
- Provides multi-tasking facilities
  - Dynamic task requests
  - Passing data between tasks
  - Sharing memory areas between tasks

## OVERVIEW OF RSX-11M

### **Major Components of RSX-11M**

- Executive - Contains code to perform system functions such as task scheduling, input/output operations, etc.
- File System - Provides efficient and convenient access to data and task files.
- Utilities - Provide services needed to program and support user applications.

## THE EXECUTIVE

### Components

- Trap and interrupt vectors - Used by hardware to provide trap and interrupt service.

Vectors consist of 2 words:

Word 1 - A value to go into the PC

Word 2 - A value to go into the PS

When a trap or interrupt occurs:

Current values of PC and PS are pushed onto the stack

Values in the vector are moved into the PC and PS

- System Stack - Maintained as temporary storage for system programs.
- System Common - Contains pointers to important areas of system data base.
- Executive Code - Performs system functions.
- Dynamic Storage Area - Contains most dynamically created system data structures.

### Use of Physical Memory

- Executive contained in lowest area of memory
- Size depends on features chosen at SYSGEN; not greater than 20K words
- Executive has access to I/O page in top 4K words of address space
- Some device drivers may not be included within Executive
- Some directive service routines may not be included within the Executive

OVERVIEW OF RSX-11M

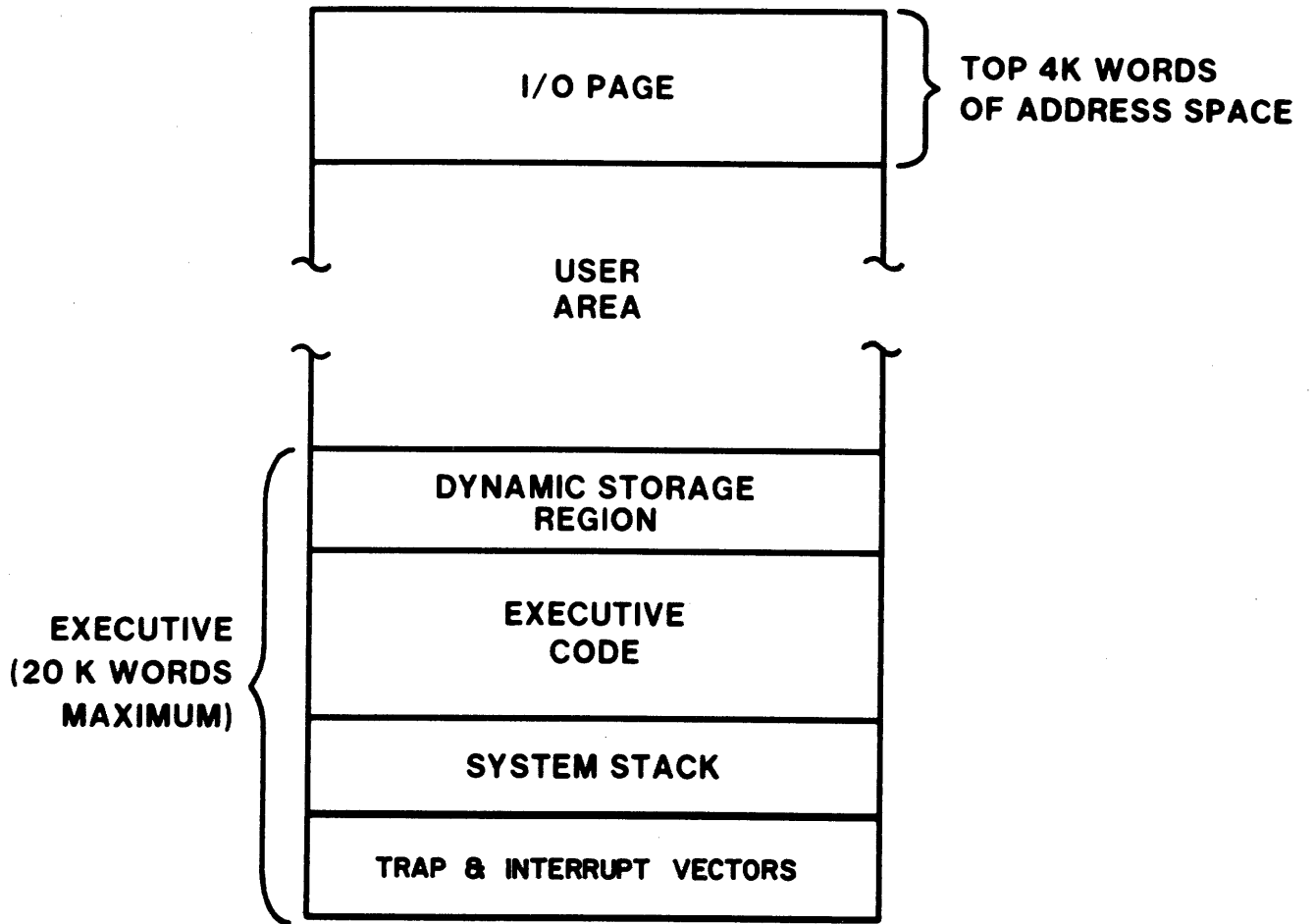


Figure 1-1 Typical Use of Physical Memory

## THE FILE SYSTEM

### Design Goals

- Allow programmer to organize data in a convenient manner
- Provide protection from unauthorized access
- Provide efficient use of disk space

### Components

- Standard structures on disk and tape volumes
- Ancillary control processor (ACP) to provide programming interface to file structured volumes
  - F11ACP - For disk volumes
  - MTAACP - For magnetic tape volumes
- Application-oriented software
  - FCS - File Control Services
  - RMS - Record Management Services

OVERVIEW OF RSX-11M

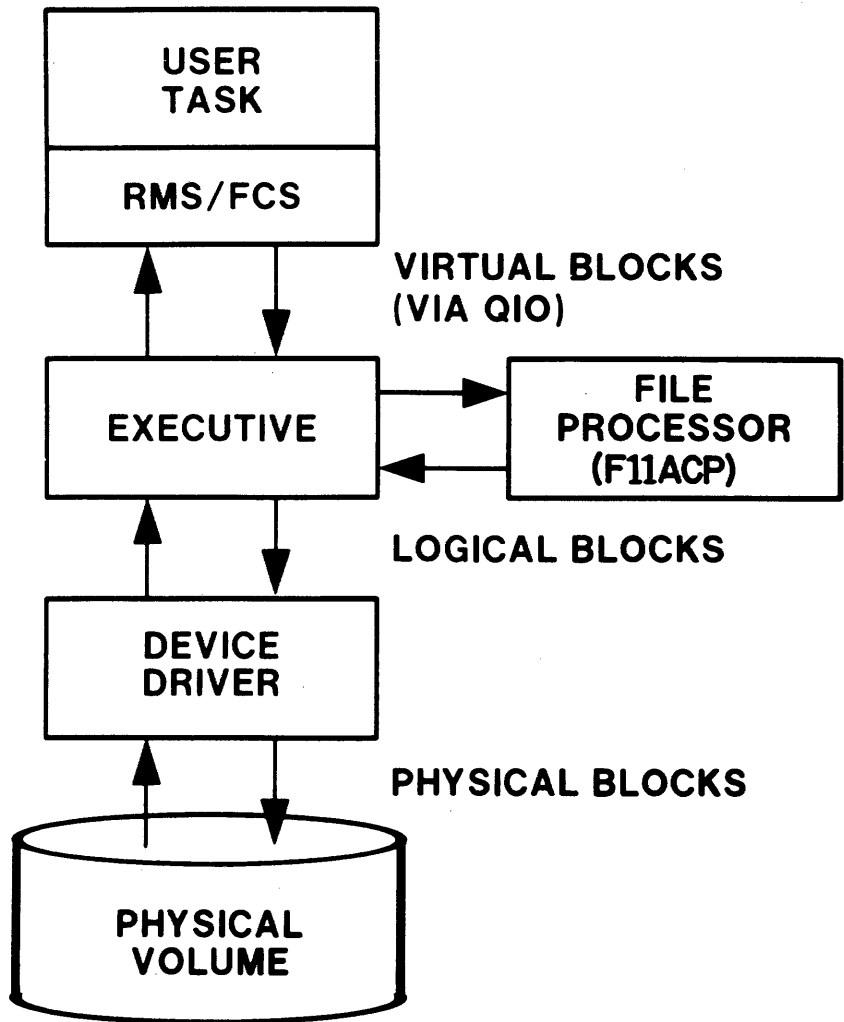


Figure 1-2 The File System

## THE UTILITIES

- Tasks distributed with operating system
  - Perform common maintenance and development functions
  - Not included in memory-resident Executive
  
- Four general categories of utilities
  - Language processors
    - MACRO-11
    - FORTTRAN
  
  - Program development utilities
    - EDT
    - EDI
    - LBR
  
  - System maintenance utilities
    - BAD
    - CMP
    - VFY
    - PAT
  
  - File manipulation utilities
    - PIP
    - FLX
    - DMP



# THE SYSTEM DATA BASE



## INTRODUCTION

The system data base includes the data structures which describe the current state of the system to the Executive. Every operation within the system has its effect on the system data base. Similarly, the state of the system data base at the time an operation is requested determines the success and effect of the operation.

Throughout this course, the system data base is used to explain the mechanics of various system operations. This module describes the most central system data structures, and how they are related. Future modules detail the data structures and their linkages.

## OBJECTIVES

1. Describe the major system data structures associated with task management.
2. Describe the major system data structures associated with partition control.
3. Describe the major system data structures associated with I/O device control.
4. Describe how the Executive manages the Dynamic Storage Region.



## STATIC AND DYNAMIC DATA STRUCTURES

- Static data structures

Created when system is built

Contained in Executive modules

Example: Data structures for standard devices selected at SYSGEN are in the Executive module SYSTB.

- Dynamic data structures

Created and eliminated as needed

Contained in Dynamic Storage Region (DSR)

Example: Data structures needed to define tasks to the system are in DSR.

### The Dynamic Storage Region

- Contains dynamic data structures

- Space allocated and deallocated as needed

- Allocation of DSR:

Performed by routines in module CORAL

Length is multiple of 4 bytes

Linked list of unallocated space is maintained by Executive

No record of allocated space is kept

First-fit algorithm is used

List of preallocated I/O packets maintained if specified at SYSGEN



THE SYSTEM DATA BASE

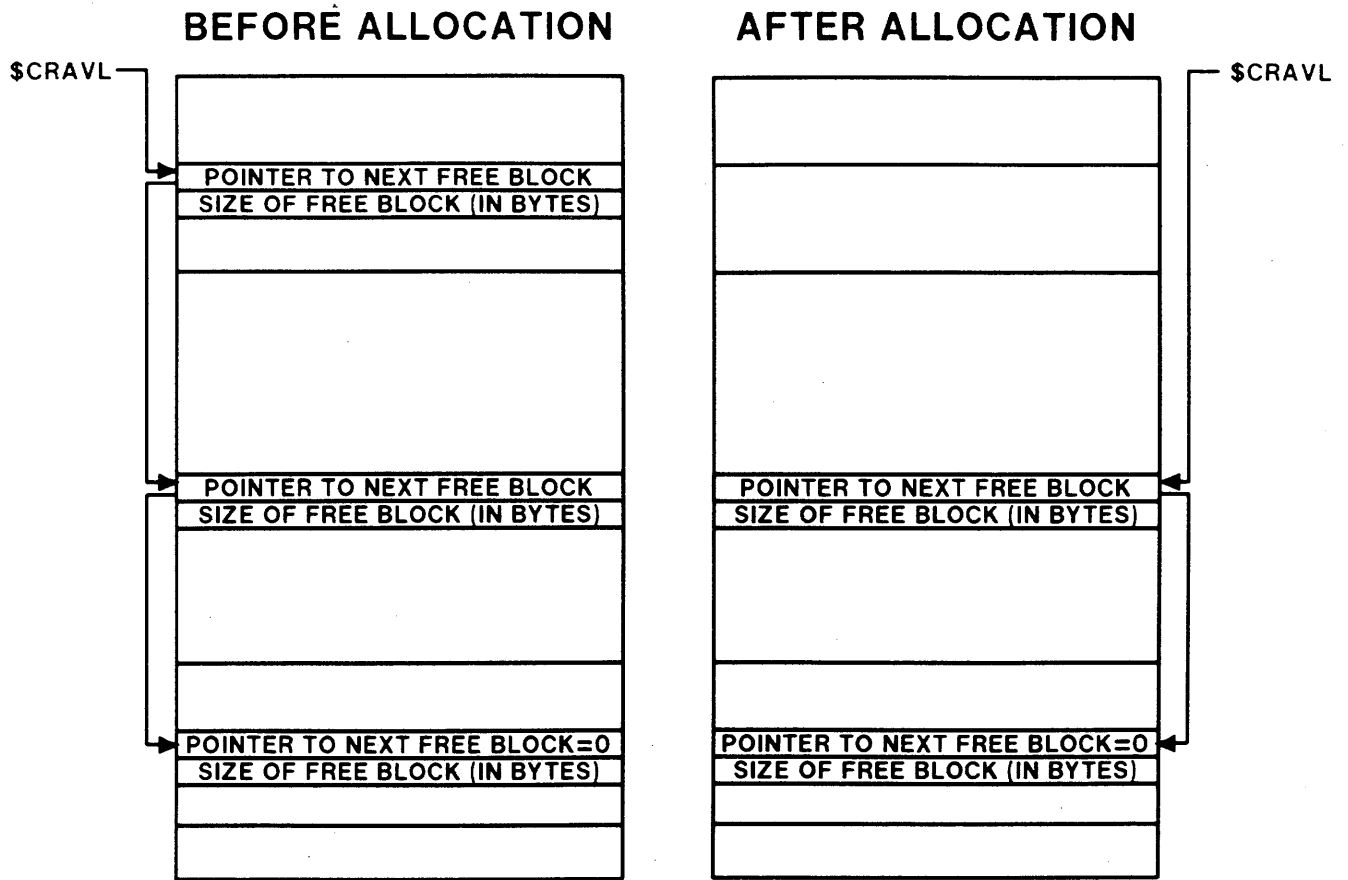


Figure 2-2 Allocating DSR

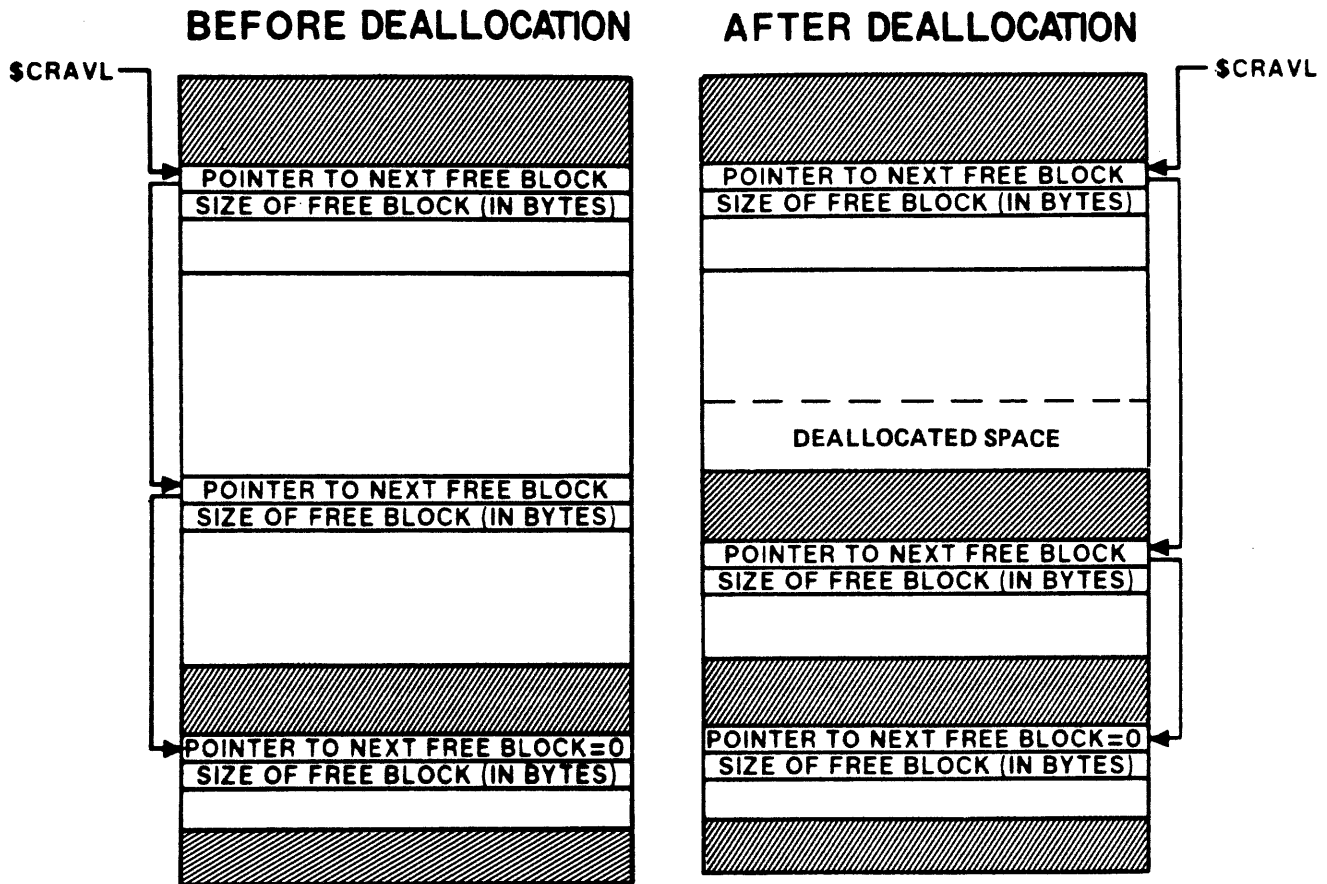


Figure 2-3 Deallocating DSR



## TASK-RELATED DATA STRUCTURES AND LISTS

### The Task Control Block (TCB)

- Defines task to system
- Contains information controlling task execution
  - Task name
  - Task priority
  - Local event flags
  - Task status words
- Contains pointers to other data structures including:
  - T.RCVL - Receive queue listhead
    - Points to linked list of data blocks queued by the 'SEND DATA' directive.
  - T.ASTL - AST queue listhead
    - Points to linked list of ASTs queued to task.
  - T.UCB - Address of data structure (UCB) identifying TI:
  - T.TCBL - Link word for System Task Directory
  - T.PCB - Address of data structure (PCB) identifying partition in which task executes
  - T.ACTL - Link word for Active Task List
- Allows task to load and begin execution quickly
  - Contains pointer to task image on disk
  - Identifies partition in which to load task

THE SYSTEM DATA BASE

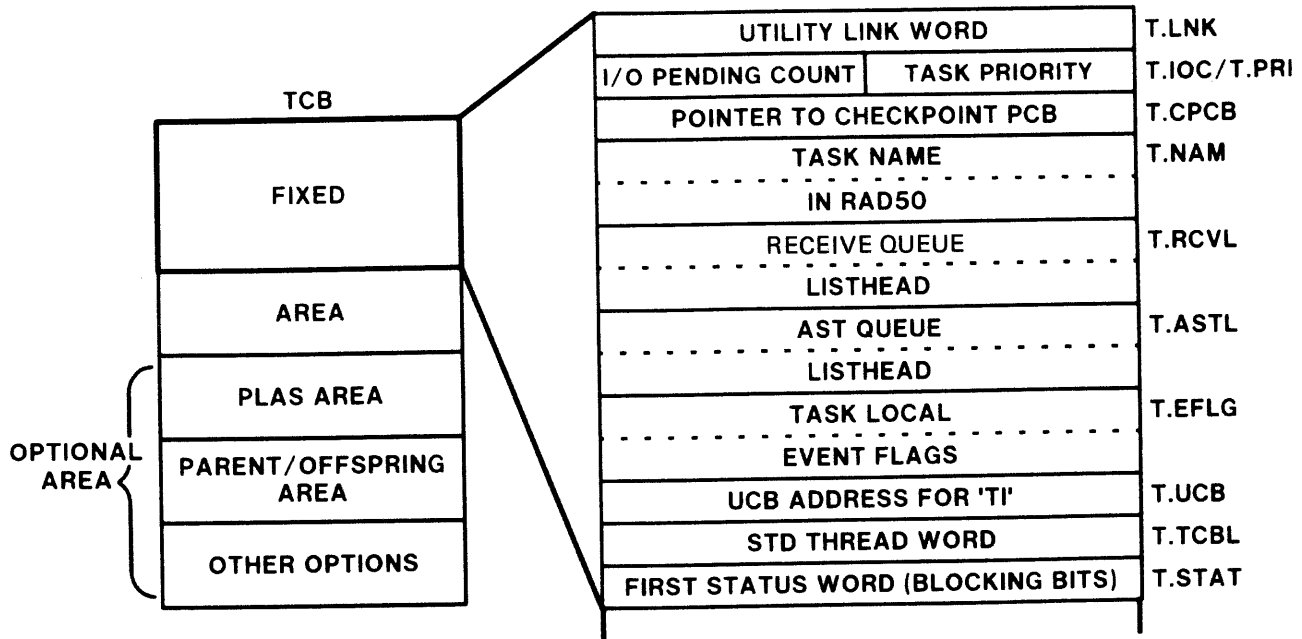


Figure 2-4 The Task Control Block  
(First Part of Fixed Area)

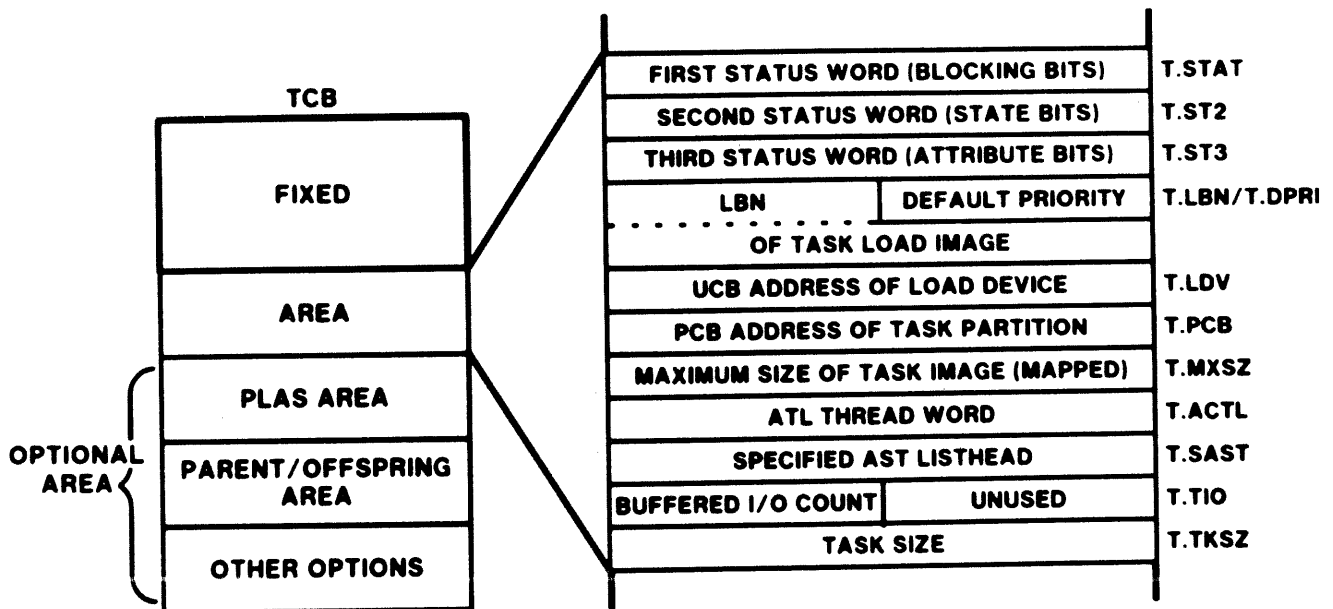


Figure 2-4 The Task Control Block  
(Second Part of Fixed Area)

THE SYSTEM DATA BASE

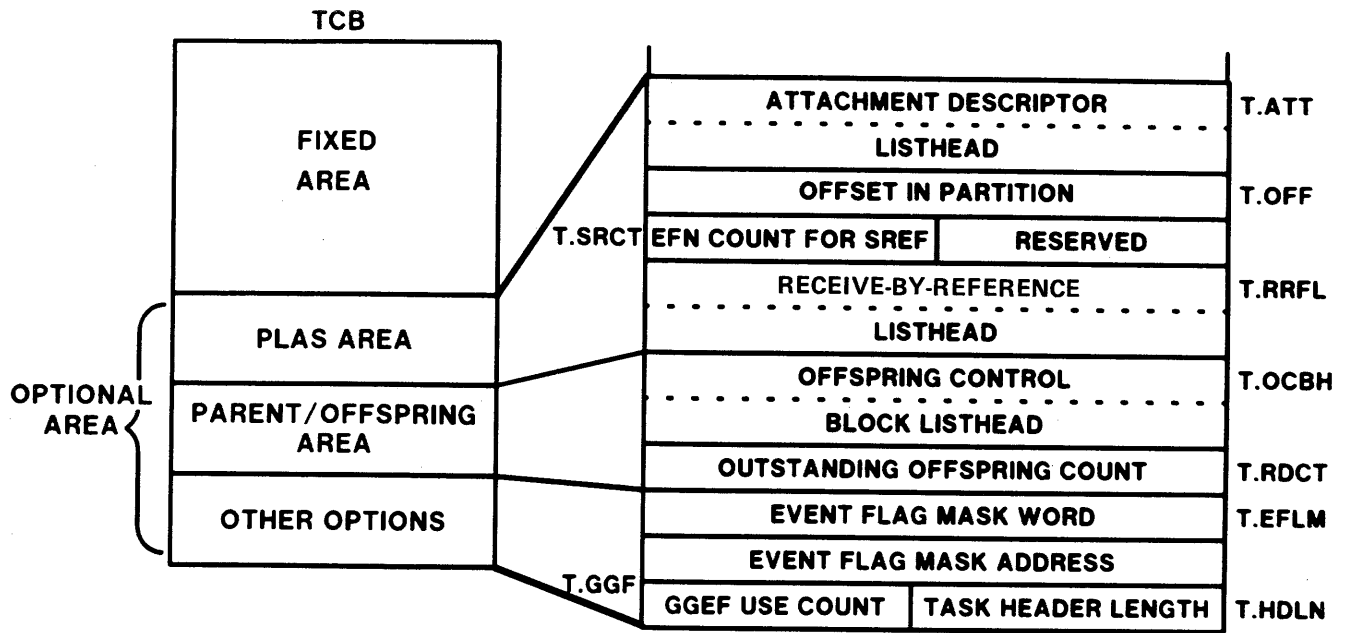


Figure 2-4 The Task Control Block (Optional Area)

THE SYSTEM DATA BASE

Table 2-1 Task Status Words

Offset	Bit	Symbol	Value	Meaning
T.STAT	15	TS.EXE	100000	Task not in execution
	14	TS.RDN	40000	I/O rundown in progress
	13	TS.MSG	20000	Abort message being output
	12	TS.NRP	10000	Task mapped to nonresident region
	8	TS.OUT	400	Task is out of memory
	7	TS.CKP	200	Task is being checkpointed
	6	TS.CKR	100	Task checkpointing requested
NOTE				
The bits in T.STAT are called blocking bits. They must all be clear for the Executive to context switch to the task.				
T.ST2	15	T2.AST	100000	AST in progress
	14	T2.DST	40000	AST recognition disabled
	13	T2.CHK	20000	Task not checkpointable
	12	T2.CKD	10000	Checkpointing disabled
	11	T2.SEF	4000	Task stopped for event flag
	10	T2.FXD	2000	Task fixed in memory
	9	T2.TIO	1000	Task engaged in terminal I/O
	8	T2.CAF	400	Dynamic checkpoint space allocation failure
	7	T2.HLT	200	Task is being halted
	6	T2.ABO	100	Task marked for abort
	5	T2.	40	Saved T2.STP on AST in progress
	4	T2.STP	20	Task stopped
	3	T2.	10	Saved T2.SPN on AST in progress
	2	T2.SPN	4	Task suspended
	1	T2.	2	Saved T2.WFR on AST in progress
0	T2.WFR	1	Task in wait for state	
T.ST3	15	T3.ACP	100000	Ancillary control processor
	14	T3.PMD	40000	Inhibit post mortem dump
	13	T3.REM	20000	Remove task on exit
	12	T3.PRIV	10000	Task is privileged
	11	T3.MCR	4000	Task requested as external MCR function
	10	T3.SLV	2000	Task is slaved
	9	T3.CLI	1000	Task is a command line interpreter
	7	T3.NSD	200	Task does not allow send data
	6	T3.CAL	100	Checkpoint space allocated in task image
5	T3.ROV	40	Task has resident overlays	

## The System Task Directory (STD)

- Linked list of TCBs
- Ordered by descending default priority
- Begins at listhead \$TSKHD in System Common
- Linked through location T.TCBL in the TCB
- 'Null Task' TCB is last entry

'Null Task' used to anchor system task lists

When 'Null Task' is scheduled, the idle loop is performed until another task becomes ready to run

'Null Task' TCB in System Common

'Null Task' never executes

- TCB is inserted when task is installed
- New TCB inserted after others of same priority
- System maintains pointers (in SYSCM) to special tasks in STD

\$TKTCB - Current task TCB

\$TKNPT - Pointer to TCB of task termination task TKTN

\$MCRPT - Pointer to TCB of MCR task

\$LDRPT - Pointer to loader TCB

THE SYSTEM DATA BASE

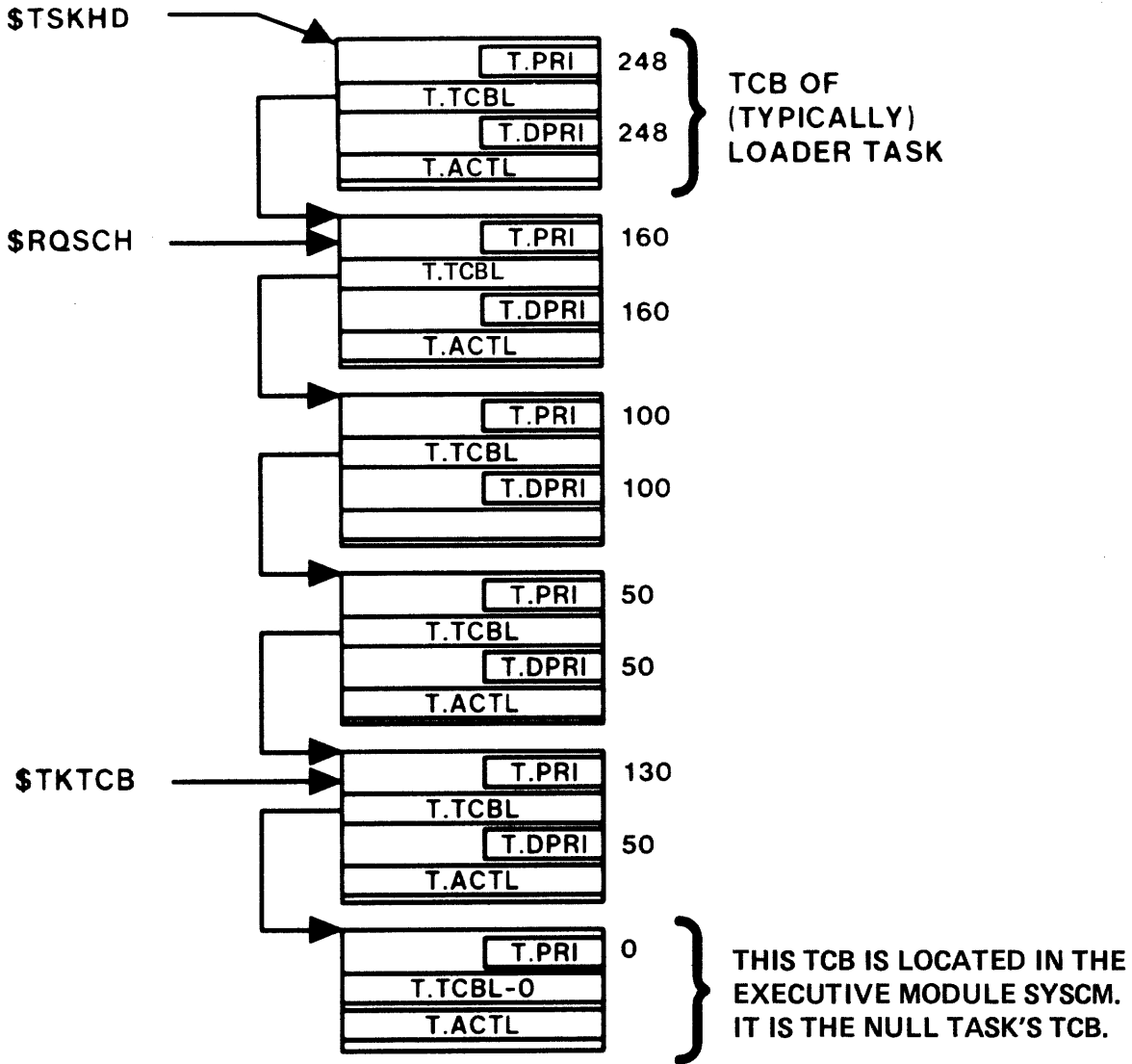


Figure 2-5 The System Task Directory

**The Active Task List (ATL)**

- Linked list of TCBs
- Ordered by descending priority
- Begins at \$ACTHD in System Common
- Linked through T.ACTL in TCB
- 'Null Task' TCB is last entry
- TCB inserted when requested; Task becomes active
- New TCB inserted after others of same priority

THE SYSTEM DATA BASE

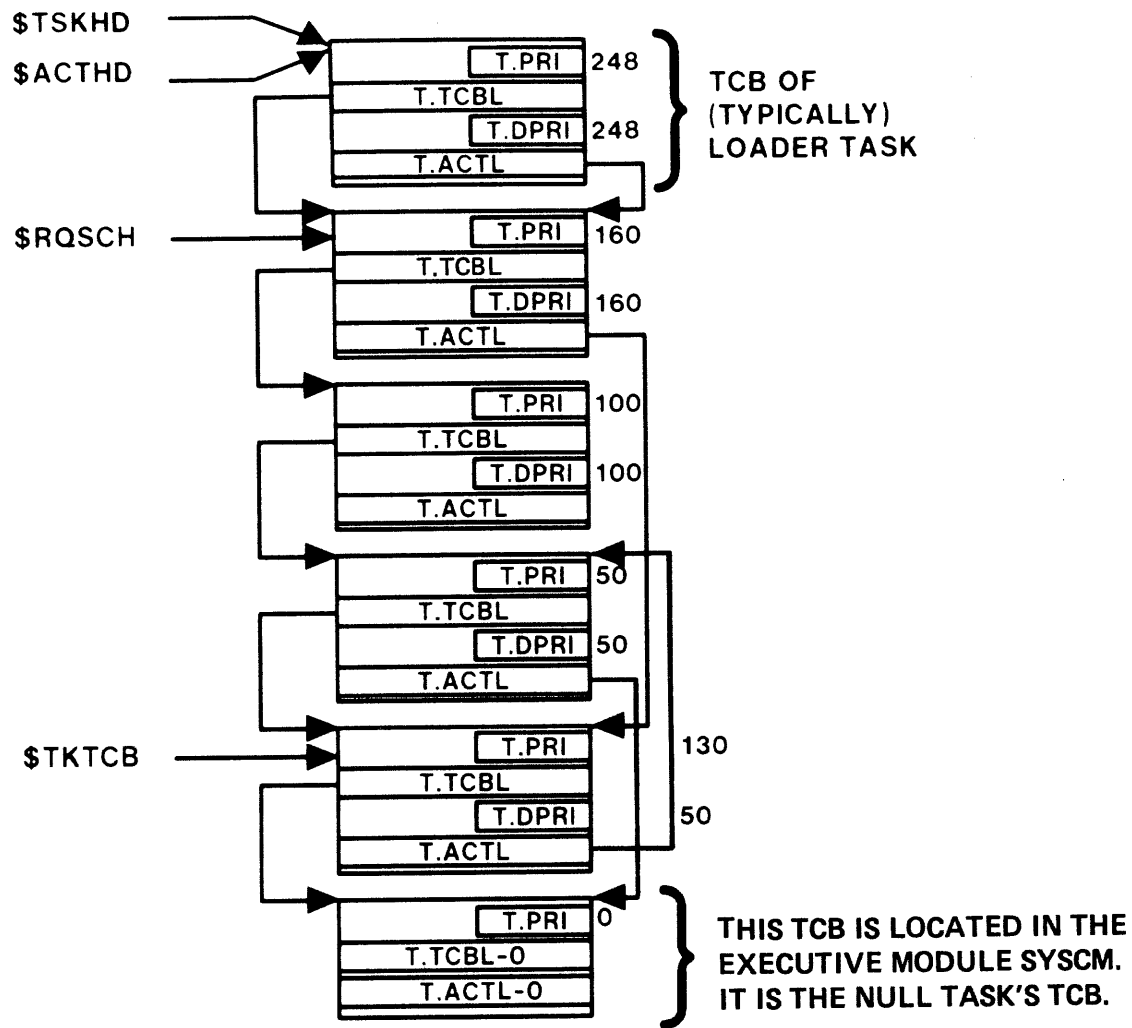


Figure 2-6 The Active Task List



## PARTITION-RELATED DATA STRUCTURES AND LISTS

### The Partition Control Block (PCB)

- Defines partition to system
- Contains information describing partition
  - Partition name
  - Physical starting address (32 word blocks number)
  - Size of partition (in 32 word blocks)
  - Partition busy word
  - Partition status word
  - Protection word
  - Current UIC of owner task
- Pointers to other data structures
  - If subpartition PCB, pointer to the main partition PCB
  - Pointer to next subpartition PCB
  - Pointer to queue of TCBS of tasks waiting for space in partition
  - Pointer to attachment descriptor block for task
  - Pointer to task header of resident task

THE SYSTEM DATA BASE

P.IOC	LINK TO NEXT PARTITION PCB		0	P.LNK
	I/O COUNT	PRIORITY OF PARTITION	2	P.PRI
	PARTITION NAME		4	P.NAM
	(IN RADIX-50)		6	
	POINTER TO NEXT SUB-PARTITION		10	P.SUB
	POINTER TO MAIN PCB		12	P.MAIN
	PHYSICAL START ADDRESS OF PARTITION		14	P.REL <sup>1</sup> ,P.HDR <sup>2</sup>
	SIZE OF PARTITION		16	P.BLKS <sup>1</sup> ,P.SIZE <sup>1</sup>
	PARTITION WAIT QUEUE LIST HEAD		20	P.WAIT
	PARTITION SWAP SIZE (SYSTEM ONLY)		22	P.SWS <sup>3</sup>
	PARTITION BUSY FLAGS		24	P.BUSY (TWO BYTES)
	TCB ADDR. OF OWNER/CURRENT UIC OF OWNER TASK		26	P.TCB/P.OWN
	PARTITION STATUS FLAGS		30	P.STAT
	POINTER TO TASK HEADER		32	P.HDR <sup>2</sup>
	PROTECTION WORD FOR PARTITION		34	P.PRO <sup>4</sup>
ATTACHMENT DESCRIPTOR		36	P.ATT <sup>5</sup>	
LIST HEAD		40		

1. 32 WORD BLOCKS FOR MAPPED SYSTEMS  
BYTES FOR UNMAPPED SYSTEMS
2. P.HDR=P.REL IN UNMAPPED SYSTEMS
3. FOR SUB-PARTITIONS OF SYSTEM CONTROLLED PARTITIONS
4. MAPPED SYSTEMS ONLY
5. MAPPED SYSTEM WITH PLAS ONLY

Figure 2-7 The Partition Control Block

THE SYSTEM DATA BASE

Table 2-2 Partition Status Word

Bit	Symbol	Value	Meaning
15	PS.OUT	100000	Partition is out of memory
14	PS.CKP	40000	Partition checkpoint in progress
13	PS.CKR	20000	Partition checkpoint requested
12	PS.CHK	10000	Partition is not checkpointable
11	PS.FXD	4000	Partition is fixed
10	PS.PER	2000	Parity error in partition
9	PS.LIO	1000	Marked by shuffler for long I/O
8	PS.NSF	400	Partition is not shufflable
7	PS.COM	200	Library or common block
6	PS.PIC	100	Position independent library of common
5	PS.SYS	40	System controlled partition
4	PS.DRV	20	Driver is loaded in partition
3	PS.DEL	10	Partition should be deleted when not attached
2	PS.APR	4	Starting APR
1		2	Starting APR
0		1	Starting APR

## The Partition List

- Linked list of PCBs
- Linked in order of increasing base address
- Begins at location \$PARHD in System Common
- Linked through P.LNK in PCB
- PCB created and inserted in list by 'SET /MAIN' or 'SET /SUB' MCR or VMR command
- PCBs of subpartitions

### Task partitions

Linked into list using P.LNK

Linked to PCB of main partition using P.SUB

### System-controlled partitions

Linked to main partition PCB using P.SUB

Not linked through P.LNK

THE SYSTEM DATA BASE

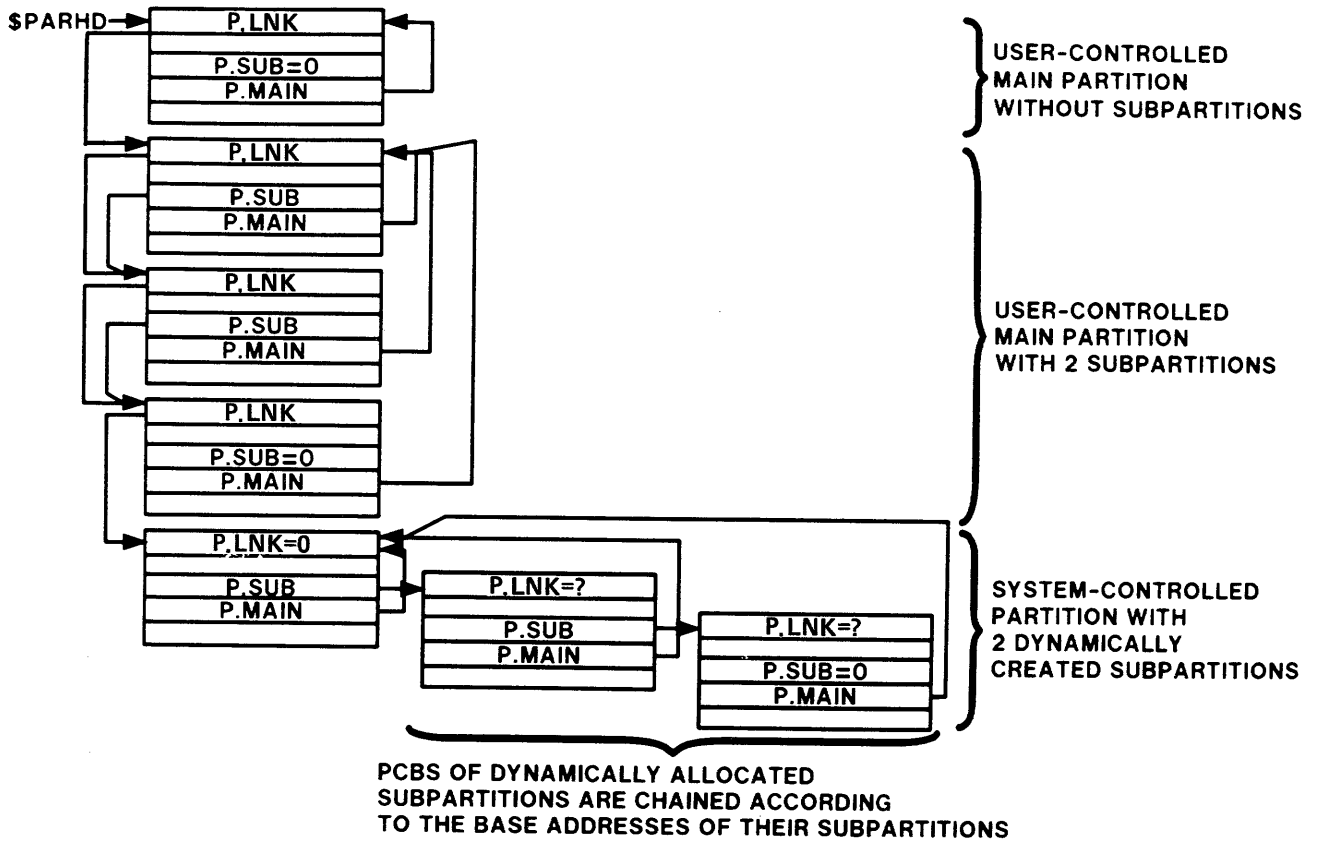


Figure 2-8 The Partition List

# THE SYSTEM DATA BASE

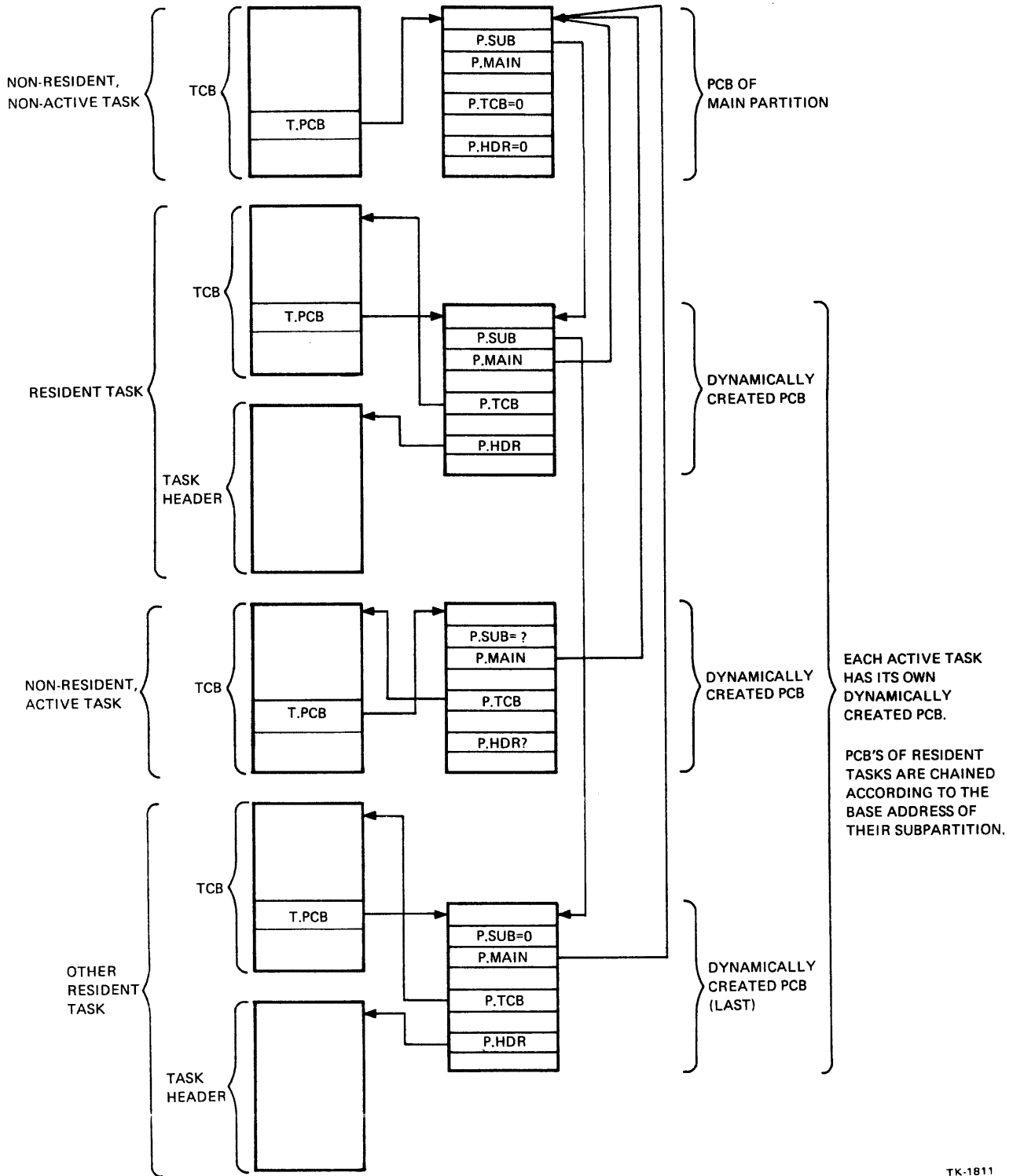


Figure 2-9 Relationship Between Task and Partition Structures

## DEVICE-RELATED DATA STRUCTURES AND LISTS

### The Device Control Block (DCB)

- Describes physical device type
- Contains information describing device
  - Generic device name in ASCII (D.NAM)
  - Physical units in system of this type (D.UNIT)
  - Device functions supported (D.MSK)
- Pointer to data structures describing physical units (D.UCB)
- Pointer to entry points in device driver (D.DSP)

LINK TO NEXT DCB		0	D.LNK
POINTER TO FIRST UCB OF THIS DEVICE TYPE		2	D.UCB
GENERIC DEVICE NAME (IN ASCII)		4	D.NAM
HIGHEST UNIT NUMBER	LOWEST UNIT NUMBER	6	D.UNIT
LENGTH OF EACH UCB OF THIS DEVICE TYPE		10	D.UCBL
POINTER TO DRIVER DISPATCH TABLE		12	D.DSP
LEGAL FUNCTION MASK	CODES 0-15	14	D.MSK
CONTROL FUNCTION MASK	CODES 0-15	16	
NO-OP FUNCTION MASK	CODES 0-15	20	
ACP FUNCTION MASK	CODES 0-15	22	
LEGAL FUNCTION MASK	CODES 16-31	24	
CONTROL FUNCTION MASK	CODES 16-31	26	
NO-OP FUNCTION MASK	CODES 16-31	30	
ACP FUNCTION MASK	CODES 16-31	32	
PCB ADDRESS OF LOADABLE DRIVER		34	D.PCB

Figure 2-10 The Device Control Block

### The Device List

- Linked list of DCBs
- Ordered by inclusion in SYSTB and by order of loading
- Begins at listhead \$DEVHD in SYSCM
- Linked through location D.LNK in DCB

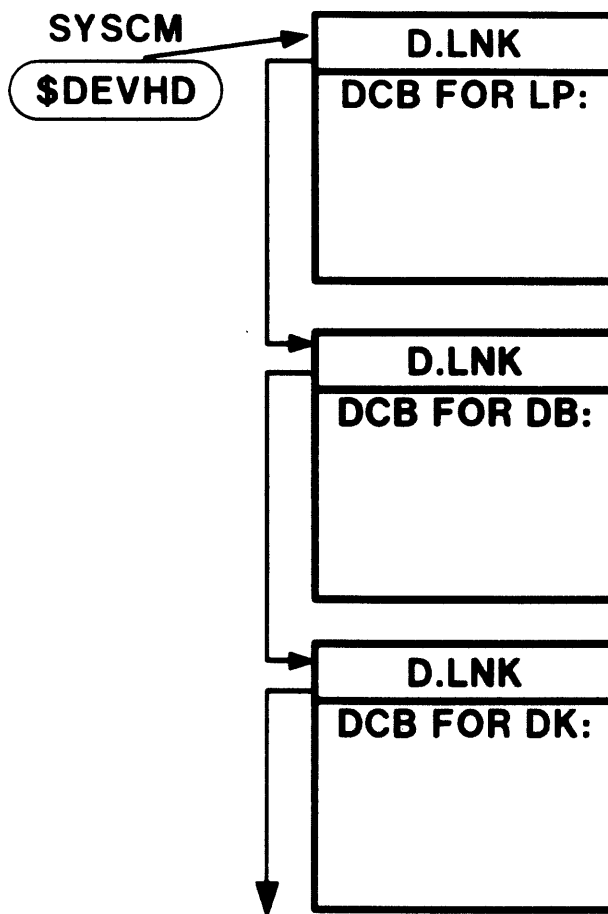


Figure 2-11 The Device List



**Other Structures**

- The Unit Control Block (UCB)
  - One UCB per physical unit of type
  - Size depends on device type
  - Contains data used to describe physical unit
- The Status Control Block (SCB)
  - One SCB per controller or per line if multiplexer
  - Size depends on device type
  - Contains data needed to control I/O operations

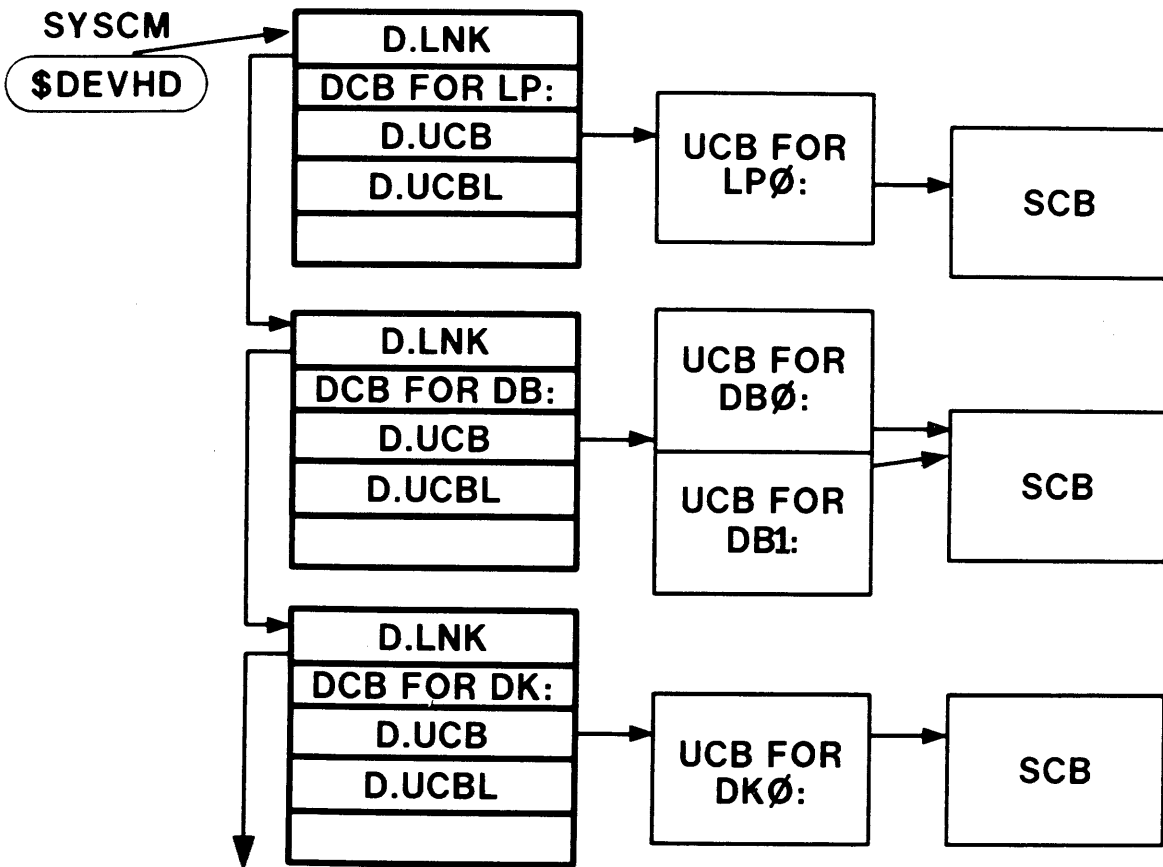


Figure 2-12 Other Data Structures

**THE CLOCK QUEUE**

**The Clock Queue Control Block**

- Describes time-dependent request
- Contains eight words; last three depends on type of request
- Five types of requests

Mark Time

Task request with periodic rescheduling

Single shot task request

Single shot internal subroutine (two types)

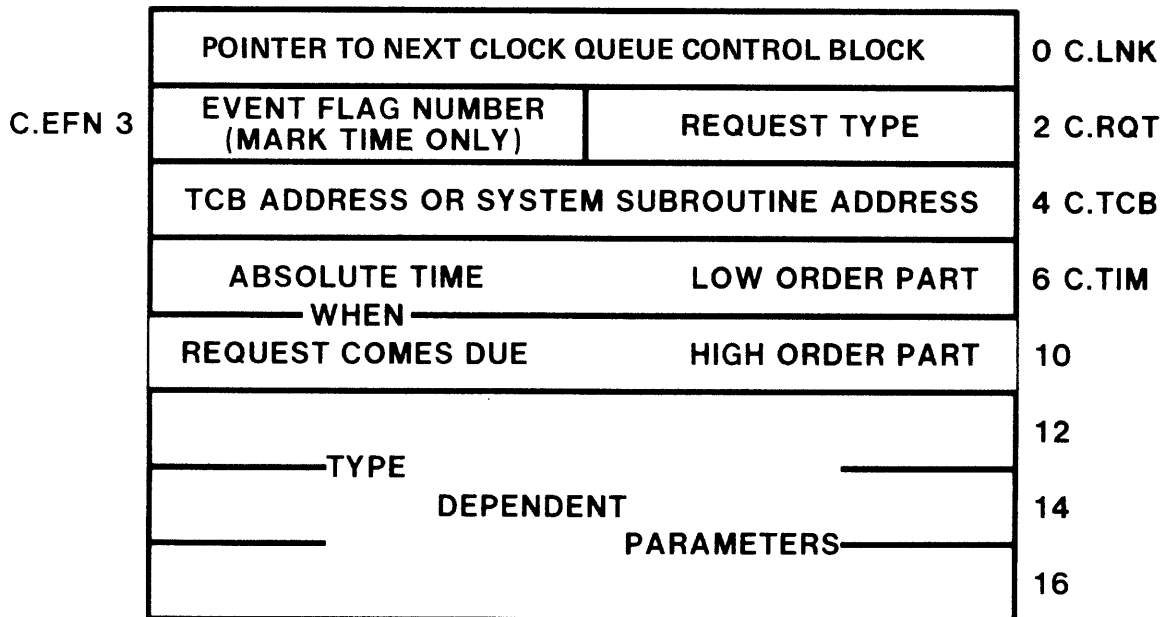


Figure 2-13 The Clock Queue Control Block

### The Clock Queue

- Linked list of Clock Queue Control Blocks
- List ordered by increasing absolute time
- Scanned by code in TDSCH when clock interrupt occurs

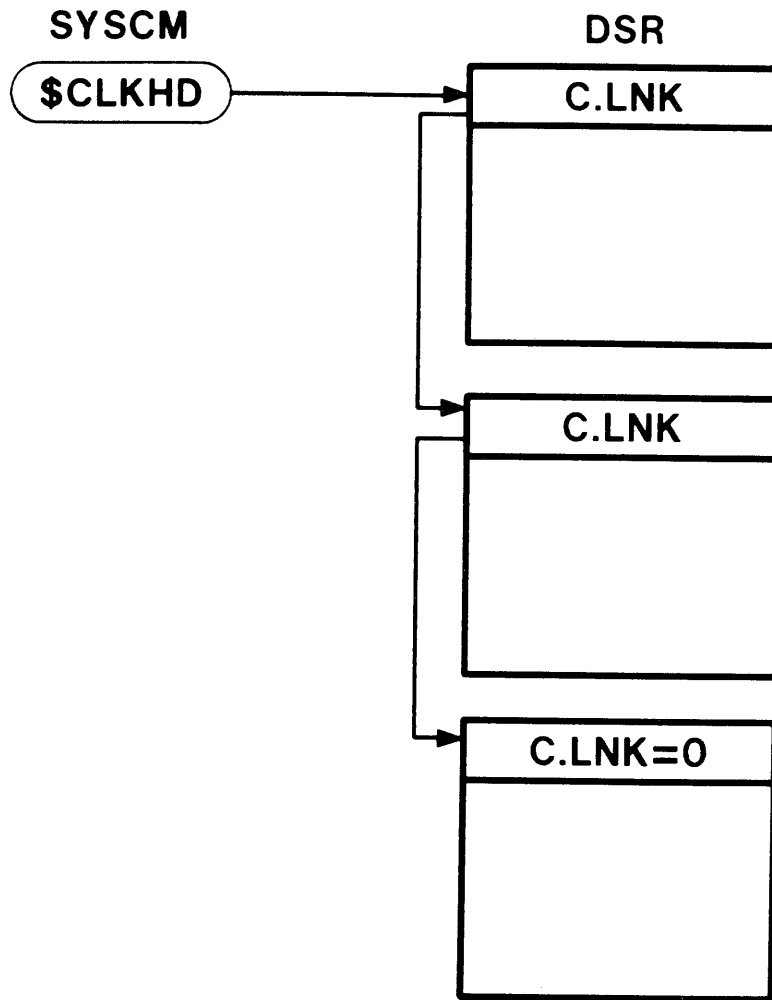


Figure 2-14 The Clock Queue



# EXECUTIVE MODULES



## EXECUTIVE MODULES

### INTRODUCTION

The Executive is composed of a number of modules. Each module contains code which performs a specific function or class of related functions. To effectively function as a systems programmer, you must be able to locate this code. This module provides a quick overview of the major modules in the Executive.

### OBJECTIVES

1. Recognize the general function of a module (i.e., general, directive processing, or device driver).
2. Locate the code which performs a given Executive function.





## EXECUTIVE MODULES

### OVERVIEW

- Over 90 possible modules in the Executive
- Modules conditionally assembled using symbols contained in [11,10]RSXMC.MAC
- Three types of modules:

#### General Executive modules

Have names which relate to function

Example: SYSCM - System Common

#### Directive Processing modules

Have 5 character names

First two characters are 'DR'

Last three characters indicate function

Example: DRABO - Module for processing the abort directive

#### Device Driver modules

Have 5 character names

First two characters indicate device type

Last three characters are 'DRV'

Example: DKDRV - Device driver for RK05 disk drives

**PRINCIPAL EXECUTIVE MODULES****System Common (SYSCM)**

- Contains pointers to system lists

\$CRAVL - Pointer to first block of free pool space  
 \$TSKHD - Pointer to STD  
 \$ACTHD - Pointer to ATL  
 \$PARHD - Pointer to Partition List  
 \$DEVHD - Pointer to Device List  
 \$GGEF - Pointer to Group Global Event Flag List  
 \$CLKHD - Pointer to Clock Queue  
 \$FRKHD - Pointer to Fork Queue  
 \$CFLPT - Pointer to Checkpoint File PCB List  
 \$UMRWT - Pointer to UMR wait queue

- Contains pointers to specific data blocks

\$HEADR - Pointer to header of current task  
 \$TKNPT - Pointer to TCB of TKTN  
 \$SHFPT - Pointer to TCB of shuffler  
 \$TKTCB - Pointer to TCB of current task  
 \$RQSCH - Pointer to TCB of requested task  
 \$MCRPT - Pointer to TCB of MCR  
 \$LDRPT - Pointer to TCB of loader

- General system data

\$CMBEG - The TCB of the null task  
 \$UMRHD - First UMR mapping assignment block  
 \$CURPR - Current task priority  
 \$COMEF - Common event flags  
 \$PWRFL - Powerfail recovery request flag  
 \$ABTIM - Absolute time counter  
 \$STKDP - Stack depth indicator  
 \$INTCT - Clock interrupt ticks count  
 \$DYPMN - Days per month table  
 \$BTMSK - Bit mask table  
 \$IOABM - I/O active bitmap  
 \$TKPS - Ticks per second  
 \$CXDBL - Context switching disabled flag

## EXECUTIVE MODULES

### System Entrance and Exit Routines (SYSXT)

- Contains routines used for entering and exiting the Executive
  - \$DIRSV - Called when Executive entered by system trap
  - \$FORK - Used to create FORK process by driver
  - \$FORK1 - Used to create FORK process by non-driver
  - \$FORK2 - Used to create FORK process by CINT\$ routine
  - \$INTSV - Called when Exec entered by interrupt
  - \$INTSE - Called when Exec entered by interrupt (Error Logging)
  - \$INTSC - Called when Exec entered by interrupt (CINT\$)
  - \$INTXT - Called to exit the Exec after an interrupt
  - \$DIRXT - Called to exit the Exec after a system trap
  - \$SWSTK - Called to enter the Exec from a privileged task
- Contains code for the system 'idle loop'

### DSR Allocation Routines (CORAL)

- Contains routines used to allocate space in DSR
  - \$ALOCB - Allocates a block of specified size from DSR
  - \$ALCLK - Allocates a clock queue control block from DSR
  - \$DECLK - Deallocates a clock queue control block
  - \$ALPKT - Allocates a 'send' or I/O request block
  - \$DEPKT - Deallocates a 'send' or I/O request block
  - \$DEACB - Deallocates a block

## EXECUTIVE MODULES

### I/O Related Routines (IOSUB)

- Contains routines used in I/O-related processing
  - \$GTPKT - Gets I/O packet from I/O queue
  - \$GSPKT - Gets I/O packet
  - \$IODON - Handles common I/O completion

### PLAS Routines (PLSUB)

- Contains subroutines used to manipulate Program Logical Address Space (PLAS)
  - \$SRNAM - Searches for specified partition
  - \$CKACC - Checks if desired access to region is allowed
  - \$CRATT - Creates Attachment Descriptor Block (ADB)
  - \$SRATT - Searches for specified ADB
  - \$SRWND - Searches for specified address window
  - \$UNMAP - Unmaps address window

### Queue Manipulation Routines (QUEUE)

- Contains subroutines used to manipulate queues
  - \$CLINS - Inserts an entry into the clock queue
  - \$CLRMV - Removes an entry from the clock queue
  - \$QINSF - Inserts into FIFO queue
  - \$QINSP - Inserts into priority queue
  - \$QMCRl - Queues MCR command line
  - \$QRMVF - Removes from front of queue
  - \$QRMVT - Removes next entry with specified TCB address

## EXECUTIVE MODULES

### Task Request Related Routines (REQSB)

- Contains subroutines used to handle task requests
  - \$ABCTK - Aborts current task
  - \$ABTSK - Aborts specified task
  - \$BILDS - Sets up task stack and initialize task header
  - \$ACTTK - Puts task in Active Task List (ATL)
  - \$SETCR - Sets conditional scheduling request
  - \$SETF - Sets event flag
  - \$DASTT - Declares a non-I/O related AST
  - \$QASTT - Queues an AST to a specified task
  - \$SRAST - Searches for specified type of AST
  - \$SRSTD - Searches STD for specified task
  - \$ACTRM - Removes task from ATL
  - \$STPCT - Stops current task
  - \$STPTK - Stops specified task
  - \$RLPAR - Releases task partition
  - \$RLPRL - Releases specified partition
  - \$NXTSK - Assigns next task to partition
  - \$FNDSF - Finds space in system controlled partitions
  - \$TSTCP - Tests if checkpoint should be initiated
  - \$ICHKP - Initiates checkpoint of specified task
  - \$CHKPT - Checkpoint task
  - \$LOADT - Puts task in loader queue
  - \$TSKRT - Requests task execution
  - \$MAPTK - Maps task address window

### SST Service Routines (SSTSR)

- Contains routines to service Synchronous System Traps (SST)
  - \$EMSST - Non-RSX EMT instruction
  - \$ILINS - Illegal or reserved instruction
  - \$IOTRP - IOT instruction
  - \$SGFLT - Memory protect violation
  - \$TRACE - T-bit trap or BPT instruction
  - \$TRP04 - Odd address, Non-existent memory, etc.
  - \$SSTXT - Common SST exit routine

### **Time Dependent Scheduling (TDSCH)**

- Contains routines to handle time dependent scheduling
- Entered from clock interrupt
  - Updates system time and date
  - Manages clock queue
  - Checks for device timeouts
  - Manages Round Robin scheduling
  - Manages Executive level disk swapping

### **System Initialization (INITL)**

- Executes only for system which has not been saved
  - Contains the Executive transfer address location (\$INITL)
- Performs system initialization functions
  - Writes load device and image file information into SYSCM
  - Initializes Processor Status Word
  - Initializes Memory Management registers (Mapped system)
  - Turns on memory management hardware (Mapped system)
  - Initializes Unibus Mapping Registers (11/44, 11/70)
  - Calculates size of physical memory
  - Verifies the existence of the external directive commons
  - Verifies the presence of the floating point processor
  - Verifies the presence of EIS
  - Verifies that all selected devices are online
  - Verifies the presence of the watchdog timer
  - Sets up system clock
- Deallocates its space to DSR
- Values initialized by INITL are written to system image by SAV task

## EXECUTIVE MODULES

Table 3-1 Executive Modules by Function

Function	Modules
<b>Scheduling</b>	
Task Scheduling	TDSCH - Time-Dependent Scheduling SYSXT - Normal Scheduling
Round Robin Scheduling	TDSCH
Disk-Swapping	TDSCH
Idle Loop	SYSXT
<b>Interrupt Processing</b>	
Clock Interrupts	TDSCH
I/O Interrupts	XXDRV - 'XX' Indicates Device
System Entrance	SYSXT
System Exit	SYSXT
<b>Trap Processing</b>	
Synchronous System Traps	SSTSR
'EMT' Traps	DRSUB DRDSP
'TRAP' Traps	DRSUB DRDSP
System Entrance	SYSXT
System Exit	SYSXT
Context Switching	SYSXT
Data Movement	BFCTL

# EXECUTIVE MODULES

Table 3-1 Executive Modules by Function (Cont)

Function	Modules
DSR Allocation	
For Clock Queue	CORAL
For FIFO Queues	CORAL
For Priority Queues	CORAL
For CLI Messages	CORAL
For Error Messages	ERROR
Error Logging	ERROR
I/O Processing	
I/O Parameter Block	IOSUB
UMR Allocation	IOSUB
I/O Completion	IOSUB



## EXECUTIVE MODULES

### DIRECTIVE MODULES

#### Resident Directive Module (DRSUB)

- Contains entry points for routines entered by system traps
  - \$TRTRP - Handles TRAP instruction
  - \$EMTRP - Handles EMT instruction
- Contains commonly used routines
  - \$ELGEF - Eliminates Group Global Event Flag block
  - \$DEAGF - Deaccesses group global event flags
  - \$DRDSE - Declares significant event
  - \$DRWSE - Waits for significant event
  - \$MPXC1 - Maps the first directive common
  - \$MPXC2 - Maps the second directive common
  - \$DRQRQ - Queues an I/O request and calls driver
  - \$GTUCB - Gets UCB address for given device and unit
  - \$OTHR1 - Calls directive routine in second directive common

#### Directive Dispatcher (DRDSP)

- Contains code to process EMT traps
- Determines if EMT is
  - Directive call
  - Switch to Kernel mode
  - Non-RSX EMT instruction
- Contains table defining directives in system

EXECUTIVE MODULES

Table 3-2 Directive Processing Modules

Entry	Module	Function
ABRT\$	\$DRABO	DRABO Abort Task
ALTP\$	\$DRAP1	DRATP Alter Priority
ALUN\$	\$DRASG	DRASG Assign LUN
ASTX\$\$	\$DRAXT	DRATX AST Service Exit
ATRG\$	\$DRATR	DRREG Attach Region
CINT\$	\$DRCIN	DRCIN Connect to Interrupt Vector
CLEF\$	\$DRCEF	DRSED Clear Event Flag
CMKT\$	\$DRCMS	DRCMT Cancel Mark Time Requests
CNCT\$	\$DRCNC	DRSPW Connect
CRAW\$	\$DRCRW	DRMAP Create Address Window
CRGF\$	\$DRCRE	DRGEF Create Group Global Event Flags
CRRG\$	\$DRCRR	DRREG Create Region
CSRQ\$	\$DRCSR	DRCMT Cancel Time Based Requests
DECL\$\$	\$DRDSE	DRSUB Declare Significant Event
DSAR\$\$	\$DRDAR	DRDAR Disable AST Recognition
DSCP\$\$	\$DRDCP	DRDCP Disable Checkpointing
DTRG\$	\$DRDTR	DRREG Detach Region
ELAW\$	\$DRELW	DRMAP Eliminate Address Window
ELGF\$	\$DRELE	DRGEF Eliminate Group Global Event Flags
EMST\$	\$DREMS	DRSPW Emit Status
ENAR\$\$	\$DREAR	DRDAR Enable AST Recognition
ENCP\$\$	\$DRECP	DRDCP Enable Checkpointing
EXIF\$	\$DREIF	DREIF Exit If
EXIT\$\$	\$DREXT	DREIF Task Exit
EXST\$	\$DREXS	DRSPW Exit With Status
EXTK\$	\$DREXP	DREXP Extend Task
GCCI\$	\$DRGCL	DRGCL Get command for command interpreter
GCII\$	\$DRCLI	DRCLI Get command interpreter information
GLUN\$	\$DRGLI	DRGLI Get LUN Information
GMCR\$	\$DRGCL	DRGCL Get MCR Command Line
GMCX\$	\$DRGMX	DRMAP Get Mapping Context
GPRT\$	\$DRGPP	DRGPP Get Partition Parameters
GREG\$	\$DRGPP	DRGPP Get Region Parameters
GSSW\$\$	\$DRGSS	DRGSS Get Sense Switches
GTIM\$	\$DRGTP	DRGTP Get Time Parameters
GTSK\$	\$DRGTK	DRGTK Get Task Parameters
MAP\$	\$DRMAP	DRMAP Map Address Window
MRKT\$	\$DRMKT	DRMKT Mark Time
QIO\$	\$DRQIO	DRQIO Queue I/O Request
QIOW\$	\$DRQIO	DRQIO Queue I/O Request and Wait
RCST\$	\$DRRCS	DRRAS Receive Data or Stop
RCVD\$	\$DRREC	DRRAS Receive Data
RCVX\$	\$DRREC	DRRAS Receive Data or Exit
RDAF\$	\$DRRAF	DRRES Read All Event Flags
RDXF\$	\$DRRAF	DRRES Read Extended Event Flags

## EXECUTIVE MODULES

**Table 3-2 Directive Processing Modules (Cont)**

Entry	Module	Function	
RPOI\$	\$DRREQ	DRSPW	Request and pass offspring information
RQST\$	\$DRREQ	DRSPW	Request Task
RREF\$	\$DRRRF	DRMAP	Receive By Reference
RSUM\$	\$DRRES	DRRES	Resume Task
RUN\$	\$DRRUN	DRMKT	Run Task
SCAA\$	\$DRCLI	DRCLI	Specify command arrival AST
SCLI\$	\$DRCLI	DRCLI	Set command line interpreter
SDAT\$	\$DRSND	DRRAS	Send Data
SDRC\$	\$DRSRC	DRSPW	Send, Request, and Connect
SDRP\$	\$DRSRC	DRSPW	Send data request and pass offspring control block
SETF\$	\$DRSEF	DRSED	Set Event Flag
SFPA\$	\$DRFEX	DRPUT	Specify Floating Point AST
SMSG\$	\$DRSMG	DRSMG	Send message
SPND\$\$	\$DRSPN	DRRES	Suspend
SPRA\$	\$DRPUT	DRPUT	Specify Power Recovery AST
SPWN\$	\$DRREQ	DRSPW	Spawn
SRDA\$	\$DRRCV	DRPUT	Specify Receive Data AST
SREA\$	\$DRREX	DRPUT	Specify Requested Exit AST
SREF\$	\$DRSRF	DRMAP	Send By Reference
SRRA\$	\$DRRRA	DRPUT	Specify Receive-By-Reference AST
STLO\$	\$DRSTL	DRSED	Stop for Logical OR of Event Flags
STOP\$\$	\$DRSTP	DRRES	Stop
STSE\$	\$DRSTS	DRSED	Stop for Single Event Flag
SVDB\$	\$DRSDV	DRSST	Specify SST Vector Table for Debugging
SVTK\$	\$DRSTV	DRSST	Specify SST Vector Table for Task
ULGF\$	\$DRELE	DRCMT	Unlock group global event flags
UMAP\$	\$DRUNM	DRMAP	Unmap Address Window
USTP\$	\$DRUNS	DRRES	Unstop Task
WSIG\$\$	\$DRWSE	DRSUB	Wait for Significant Event
WTLO\$	\$DRWFL	DRSED	Wait for Logical OR of Event Flags
WTSE\$	\$DRWFS	DRSED	Wait for Single Event Flag

## EXECUTIVE MODULES

### DEVICE DRIVER MODULES

#### System Device Tables (SYSTB)

- Contains DCBs, UCBs and SCBs, for devices with resident data bases.
- Data bases for standard drivers are contained in SYSTB.
- User can include other device data bases in SYSTB at SYSGEN.

#### RK05 Driver (DKDRV)

- Device driver for RK05 disk drives.
- Contains code for performing I/O to device.
- Interrupts from RK05 drive cause entry into DKDRV at \$DKINT

EXECUTIVE MODULES

Table 3-3 Standard Device Drivers

Driver	Device
DKDRV	RK05 Disk Drives
DMDRV	RK06,RK07 Disk Drives
DBDRV	RP04,RP05,RP06 Disk Drives
DRDRV	RM02,RM03,RM05,RP07,RM80 Disk Drives
DLDRV	RL01,RL02 Disk Drives
LPDRV	Line Printer
TTDRV	Terminal
MMDRV	TU16,TE16,TU45,TU77 Magnetic Tape
MTDRV	TU10,TE10,TS03,TM11 Magnetic Tape
MSDRV	TS04 Magnetic Tape
DTDRV	TC11 DECTape
DXDRV	RX01 Floppy Disk Drive
DYDRV	RX02 Floppy Disk Drive
DDDRV	TU58 Disk Cartridge
DSDRV	RS03,RS04 Disk Drives
PPDRV	Paper Tape Punch
PRDRV	Paper Tape Reader
CTDRV	TA11 Cassette Tape
DFDRV	RS08 Fixed Head Disk Drive
DPDRV	RP02 Disk Drive
LKDRV	KMC-11 Line Printer, Controller



# FILE SYSTEM OVERVIEW





## FILE SYSTEM OVERVIEW

### INTRODUCTION

This module introduces the FILES-11 system. FILES-11 consists of an on-disk and in-memory data structure. The on-disk is the same for a number of related operating systems (i.e., IAS, RSX-11D, etc.). The in-memory structure is RSX-11M specific. This structure is a cache of information which improves the performance of the file system.

### OBJECTIVES

1. Describe the on-disk and in-memory structures of the FILES-11 system.
2. Describe the directory structure used in FILES-11.
3. Describe how files are accessed on a FILES-11 volume.

### RESOURCES

1. RSX-11M/M-Plus I/O Operations Reference Manual



## FILE SYSTEM OVERVIEW

### CONCEPTS

#### FILES-11

- Method of organizing data on mass-storage media
- Common to: RSX-11M/M-PLUS, RSX-11D, IAS, TRAX, VMS

File system includes:

- File processing software such as FCS or RMS
  - Provides easy interface between user program and file system
  - Allows access data by means of user-defined records
- Executive code to handle queued I/O requests
  - Result of QIO directive
  - Provides synchronization of I/O operations
  - Determines if I/O operation is file-oriented
- A device driver to handle primitive I/O operations
  - Data transfers between the device and memory
- An ancillary control processor, ACP, which performs file-related I/O operations
  - Possible conversion to driver operations

A FILES-11 volume may be:

- Any kind of disk (including floppy disks)
- DECTape

FILE SYSTEM OVERVIEW

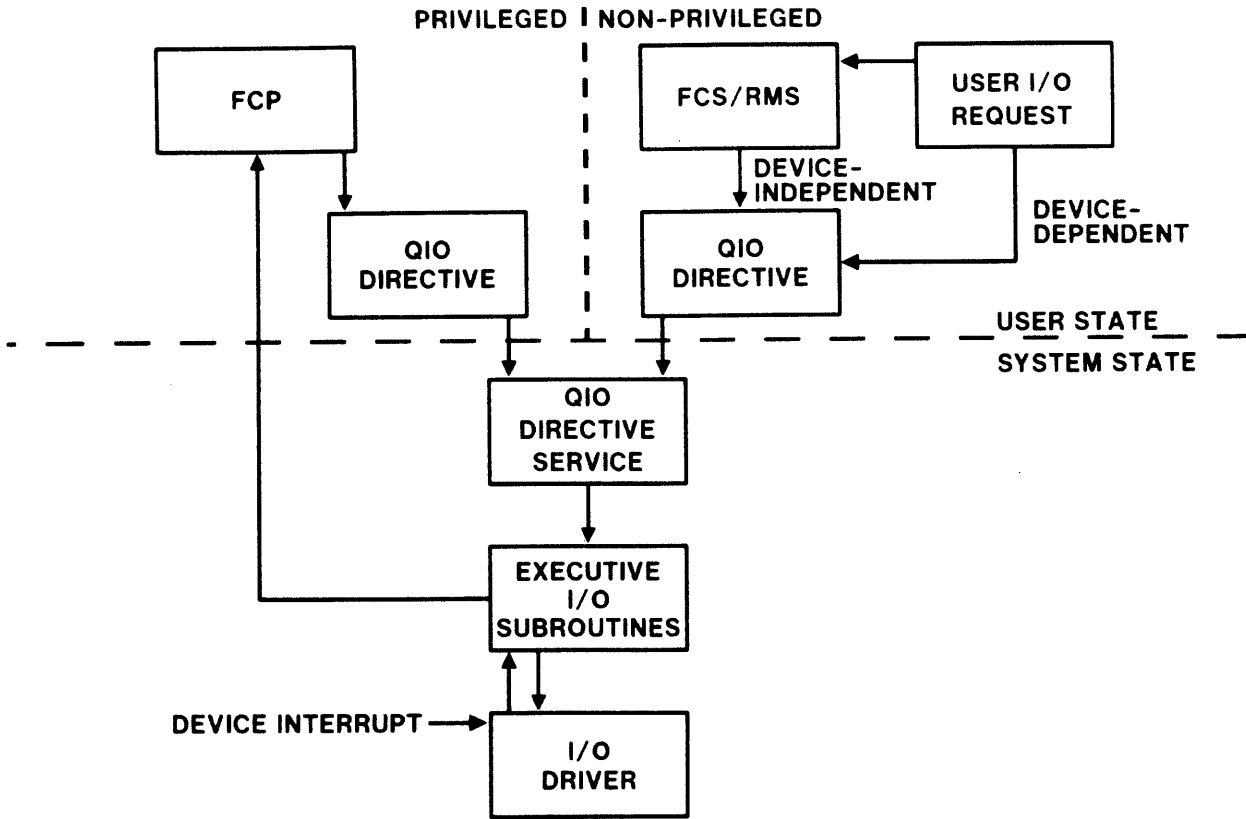


Figure 4-1 The File System

## FILE SYSTEM OVERVIEW

### Files

Three units of measurement of space on media:

- Physical blocks

Physically addressable unit

Length dependent on type of media

Usually 512 bytes

RX01 - 128 bytes

RX02 - 128 or 256 bytes

Normally referenced by device driver

- Logical blocks

Length equal to 512 bytes

Block numbers unique for volume

Begins at logical block 0

Highest logical block equals volume size minus one

Normally referenced by the file processor (F11ACP)

- Virtual blocks

Used by programmer to access data in files

Length always equal to 512 bytes

Virtual block numbers relative to file

Begins at virtual block 1

Highest virtual block equals file size

## FILE SYSTEM OVERVIEW

Files consist of two parts:

- The File Header
- The File Body

### The File Header

- Contains description of file
  - File name
  - File owner
  - File characteristics used by FCS and RMS
  - Information for mapping virtual blocks to logical blocks
- Usually one block long (512. bytes); size depends on the file processor in use

### The File Body

- Contains data stored by user and any control data appended by the file access method
- Consists of a number of contiguous groups of logical blocks (segments)

FILE SYSTEM OVERVIEW

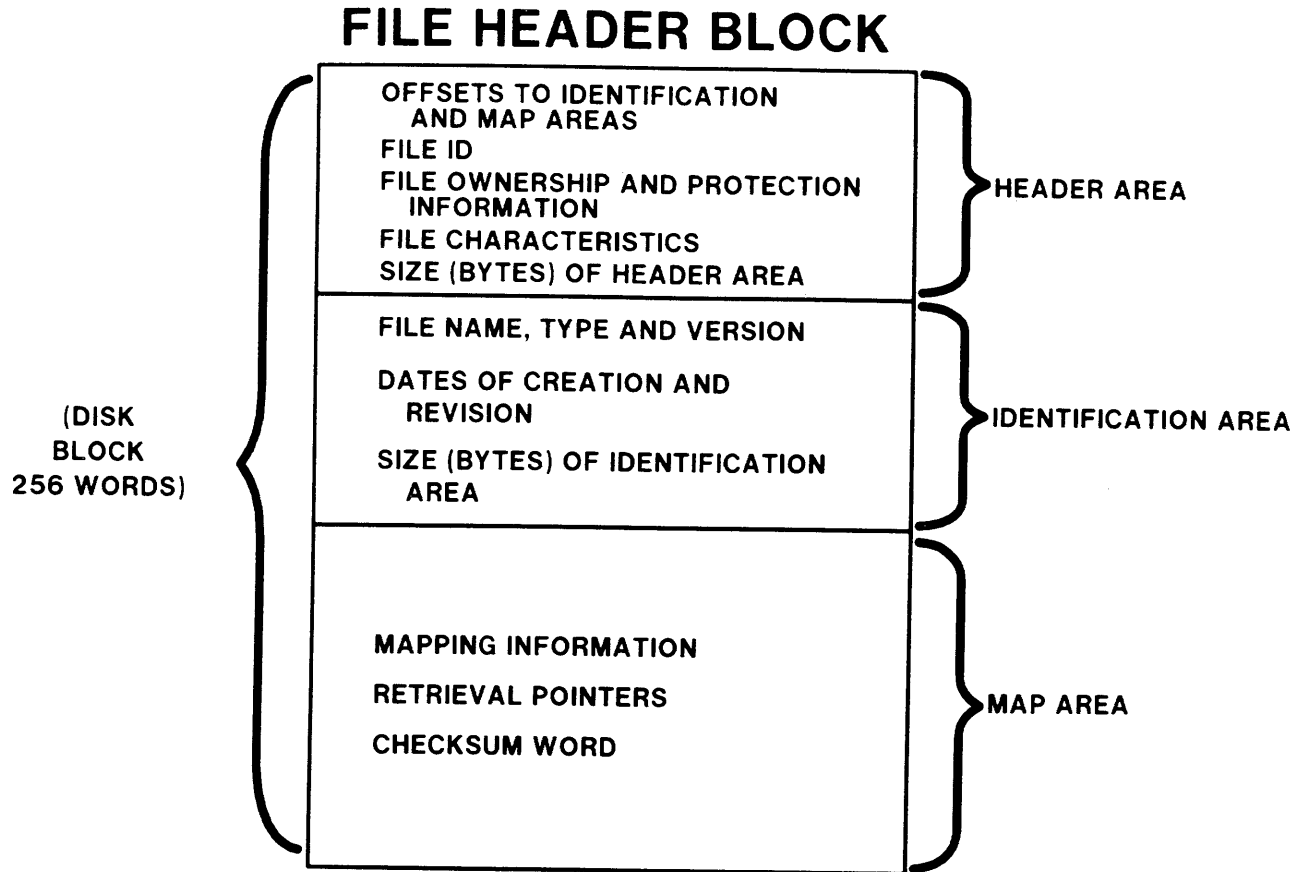


Figure 4-2 The File Header

# FILE SYSTEM OVERVIEW

Dump of DB2:[305,306]INTR01.MOD;26 - File ID 7450,60,0  
 File header

HEADER AREA

```

H.IDOF          027
H.MPOF          056
H.FNUM,
H.FSEQ          (7450,60)
H.FLEV          401
H.FOWN          [305,306]
H.FPRO          [RWED,RWED,RWED,R]
H.UCHA          000 =
H.SCHA          000 =
H.UFAT
F.RTYP          002 = R.VAR
F.RATT          002 =  FD.CR
F.RSIZ          102 = 66.
F.HIBK          H:0 L:000013 = 11.
F.EFBK          H:0 L:000013 = 11.
F.FFBY          310 = 200.
(R)EST)
000000 000000 000000 000000 000000 000000 000000 000000
000000
  
```

IDENTIFICATION AREA

```

I.FNAM,
I.FTYP,
I.FVER          INTR01  .MOD;26
I.RVNO          6
I.RVDT          14-DEC-81
I.RVTI          02:50:22
I.CRDT          15-OCT-81
I.CRTI          09:46:39
I.EXDT          --
  
```

MAP AREA

```

M.ESQN          000
M.ERVN          000
M.EFNU,
M.EFSQ          (0,0)
M.CTSZ          001
M.LBSZ          003
M.USE           002 = 2.
M.MAX           314 = 204.
M.RTRV
SIZE            LBN
11.            H:001 L:165751 = 125929.
  
```

CHECKSUM

```

H.CKSM          123624
  
```

Example 4-1 The File Header for a Data File



# FILE SYSTEM OVERVIEW

Dump of DB2:[305,306]SPY.TSK#16 - File ID 16104,7,0  
File header

HEADER AREA

H.IDOF	027
H.MPOF	056
H.FNUM,	
H.FSEQ	(16104,7)
H.FLEV	401
H.FOWN	[305,306]
H.FPRO	[RWED,RWED,RWED,R]
H.UCHA	200 = UC.CON
H.SCHA	000 =
H.UFAT	
F.RTYP	001 = R.FIX
F.RATT	000 =
F.RSIZ	1000 = 512.
F.HIBK	H:0 L:000050 = 40.
F.EFBK	H:0 L:000051 = 41.
F.FFBY	0 = 0.
(REST)	
000000	000000 000000 000000 000000 000000 000000 000000 000000
000000	

IDENTIFICATION AREA

I.FNAM,	
I.FTYP,	
I.FVER	SPY .TSK#16
I.RVNO	22
I.RVDT	14-DEC-81
I.RVTI	02:50:28
I.CRDT	05-JUN-81
I.CRTI	14:14:33
I.EXDT	--

MAP AREA

M.ESQN	000
M.ERVN	000
M.EFNU,	
M.EFSQ	(0,0)
M.CTSZ	001
M.LBSZ	003
M.USE	002 = 2.
M.MAX	314 = 204.
M.RTRV	
SIZE	LBN
40.	H:001 L:172544 = 128356.

CHECKSUM

H.CKSM	133671
--------	--------

Example 4-2 The File Header for a Task Image

### Retrieval Pointers

- Defines the correspondence between logical and virtual blocks
- Contained in the file header:
  - Maximum: 102 per header
  - One fragment per retrieval pointer
  - Maximum file length with 1 block per header: 26112 blocks
- Four bytes long
  - One byte: number of virtual blocks in segment; maximum is 256 blocks.
  - Three bytes: pointer to first logical block in segment.

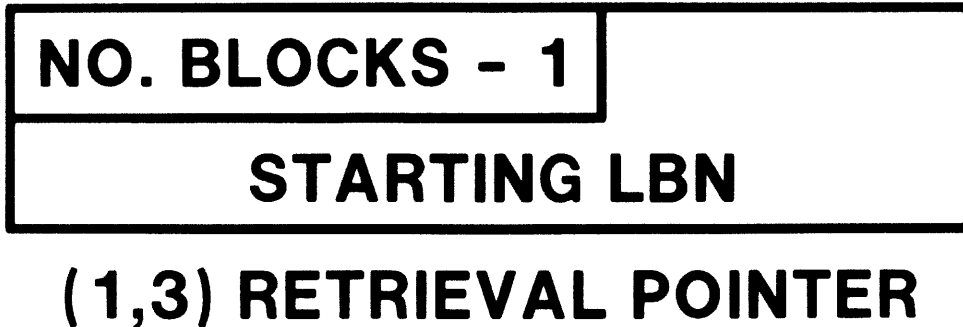


Figure 4-3 Retrieval Pointer

FILE SYSTEM OVERVIEW

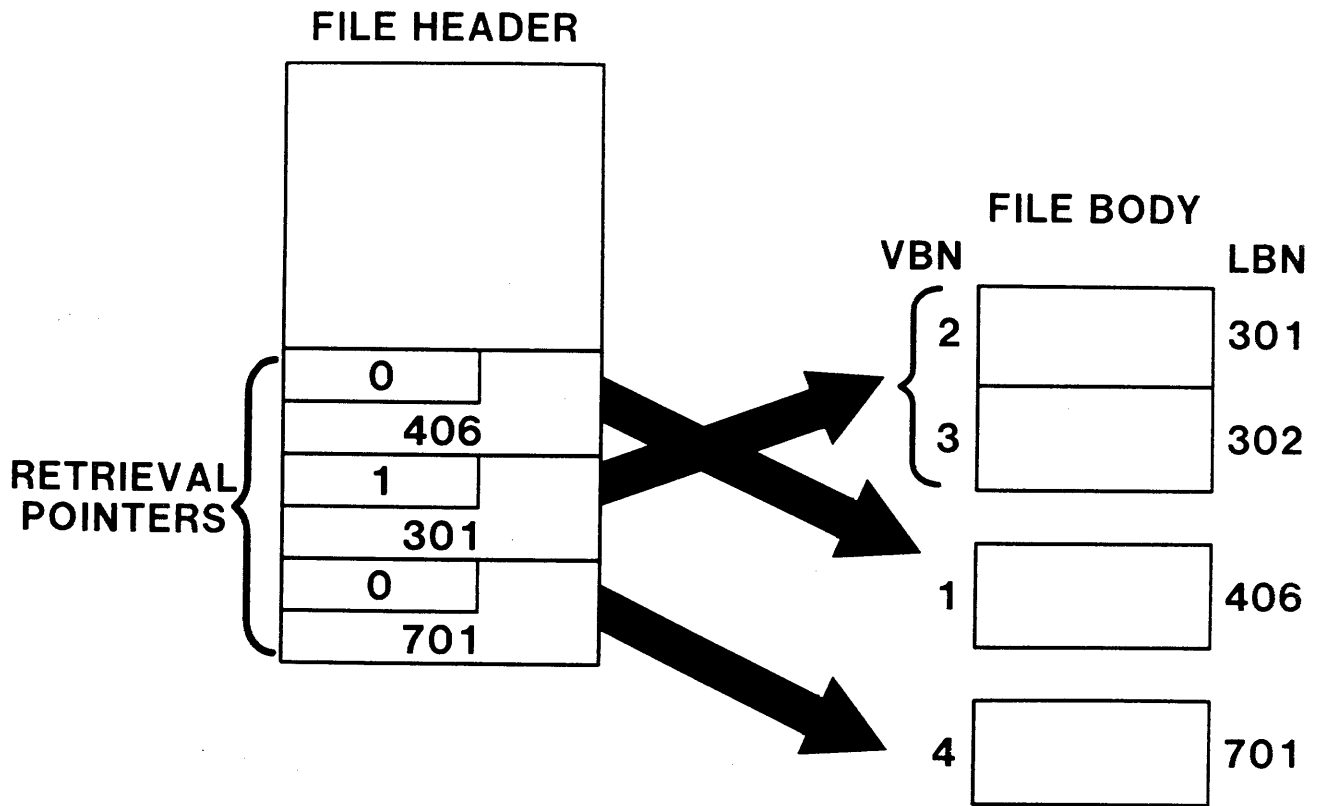


Figure 4-4 Mapping Virtual to Logical Blocks

# FILE SYSTEM OVERVIEW

## File Directories

- Contains information needed to identify and locate files
  - File name, type and version number
  - File number (Relative number of file headers in index file)
  - File sequence number (Number of times a file header is used)
- Two types of directories
  - Master File Directory (MFD) -- One per volume.
  - User File Directory (UFD) -- As many as desired per volume
- Naming convention
  - Name of directory: xxxyyy.DIR;l
  - where
    - xxx is a group number
    - yyy is a member number
  - Master File Directory: 000000.DIR;1
  - User File Directory for UIC: [6,32]: 006032.DIR;1

1	FILE ID
2	FILE SEQUENCE NO.
3	0
4	FILENAME
5	(RAD50)
6	
7	FILE TYPE (RAD50)
8	FILE VERSION

Figure 4-5 Directory Record

## FILE SYSTEM OVERVIEW

### FILES-11 VOLUMES

#### The Standard Files

- The Index File: INDEXF.SYS
- The Bitmap File: BITMAP.SYS
- The Master File Directory: 000000.DIR
- The Bad Block File: BADBLK.SYS
- The System Checkpoint File: CORIMG.SYS

## FILE SYSTEM OVERVIEW

### The Index File

- Contains basic structures needed by file system.

Boot Block  
Home Block  
Index File Bitmap  
All File Headers

- Filespec: [0,0]INDEXF.SYS;1,  
File ID/SEQ: 1/1
- Boot Block

Contains bootstrap code for hardware booting of device

Always virtual block 1 of index file

Always logical block 0 of volume

Written by SAV command when the /WB switch is used

If volume not bootable, contains code to print the message: THIS VOLUME DOES NOT CONTAIN A HARDWARE BOOTABLE SYSTEM

- Home Block

Contains information needed by file system to access data on volume

Volume label

Pointer to index file bitmap

Size of index file bitmap

Checksum words to validate data in home block

Always located in virtual block 2 of index file

Located in first good block in sequence  
1, 400, 1000, 1400, .....

Checksum used to identify homeblock

## FILE SYSTEM OVERVIEW

- Index File Bitmap

- Allows fast access to unused blocks in index file

- Always located beginning in virtual block 3 of index file

- One bit per possible file header in index file

- Bit is set to indicate if block is in use

- Bit clear if block is free

- Bit is set if block is in use

- File Headers

- Contained in virtual blocks starting at block  $3+n$ , where  $n$  is the length of the bitmap

- First 16 headers are contiguous

- Virtual block of header =  $2 + m + n$

- where

- $n$  = number of blocks in index file bitmap

- $m$  = file number

FILE SYSTEM OVERVIEW

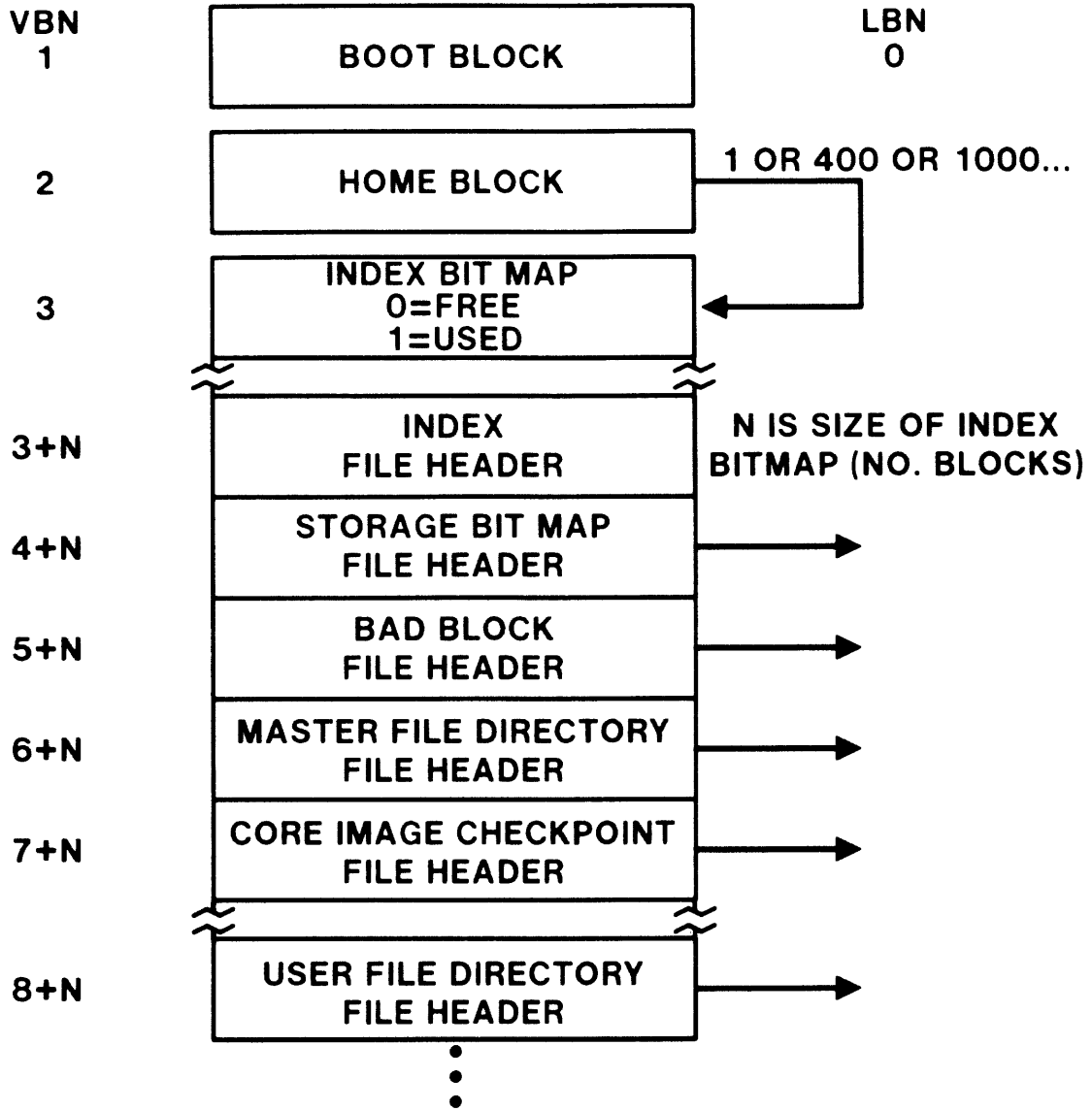


Figure 4-6 Structure of the Index File



# FILE SYSTEM OVERVIEW

## The Bitmap File

- Virtual block number 1 contains allocation information used on RSX-11D
- Bitmap starts in virtual block number 2 of the bitmap file
- One bit per logical block on volume
- Value of each bit indicates status of corresponding block
  - Bit set - block not allocated to file
  - Bit clear - block allocated
- VFY compares clear bits with retrieval pointers
- Filespec: [0,0]BITMAP.SYS;1,  
File ID/SEQ: 2/2

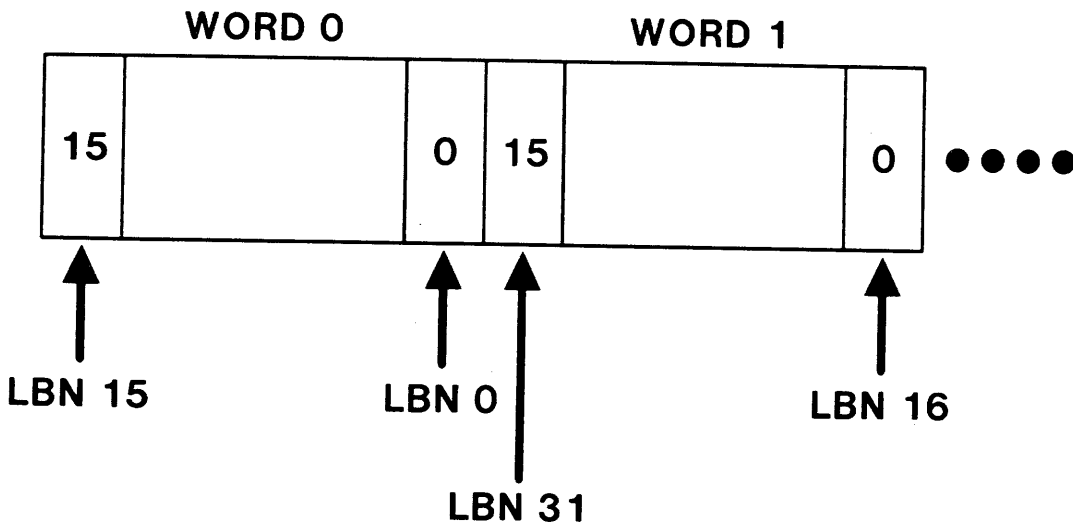


Figure 4-7 The Bitmap File

### The Master File Directory

- Directory corresponding to UFD [0,0]
- Contains entries for the five standard files
- Contains entries for all UFDs on volume
- Contains entry for system account file RSX11.SYS
- Filespec: [0,0]000000.DIR;1,  
File ID/SEQ: 4/4

### The Badblock File

- Used to keep bad blocks from being allocated to user files
- Badblock information created by BAD or entered by the user or manufacturer allocates blocks to file
- Filespec: [0,0]BADBLK.SYS;1, File ID/SEQ: 3/3
- No dynamic badblock handling

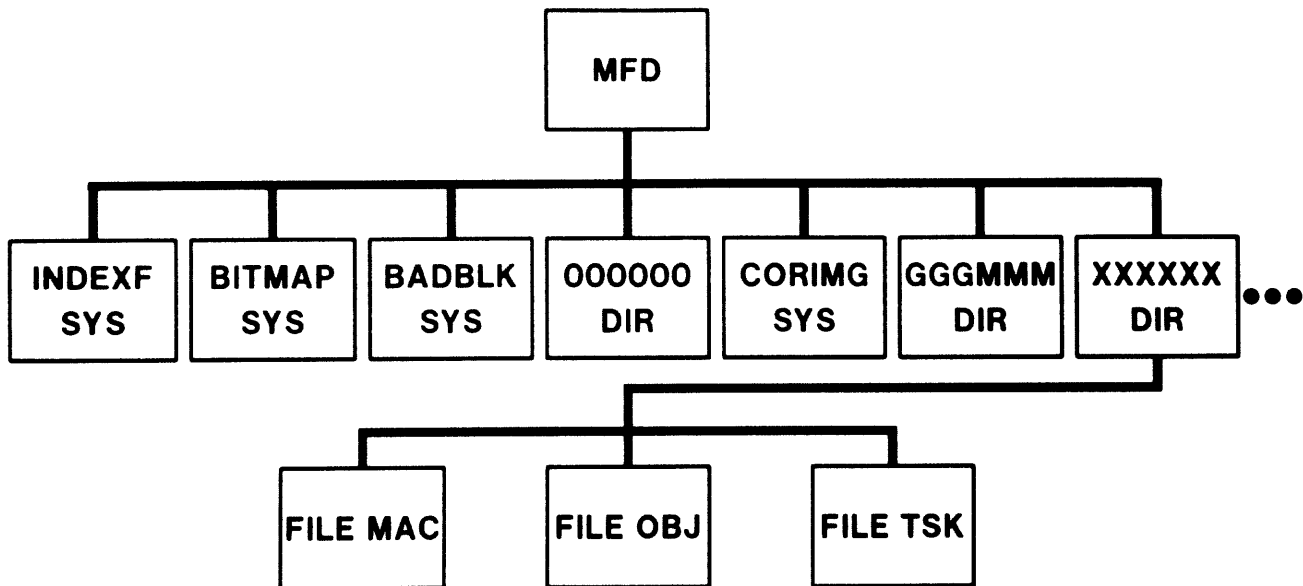


Figure 4-8 Two Level Directory Structure

## FILE SYSTEM OVERVIEW

### **The System Checkpoint File**

- Used to checkpoint tasks
- No space allocated when volume initialized
- Space allocated by ACS command
- Always contiguous
- Filespec: [0,0]CORIMG.SYS;1,  
File ID/SEQ: 5/5

## FUNCTIONS OF THE FILE SYSTEM

### Creating a FILES-11 Volume

- FILES-11 volume created by INITIALIZE command
- Home block information can be modified by the HOME command
- Creates five standard files
- Volume characteristics determined:
  - Volume label
  - Number of blocks for default file extension
  - Size of index file (number of blocks used for file headers)
  - Number of files on volume
  - Location of index file
  - Default protection for files on volume

# FILE SYSTEM OVERVIEW

## Creating a File

- Index file bitmap searched for first free block
- First free block used for file header
- Bitmap file searched for required number of free blocks to allocate initial file
- Entry for new file placed in UFD

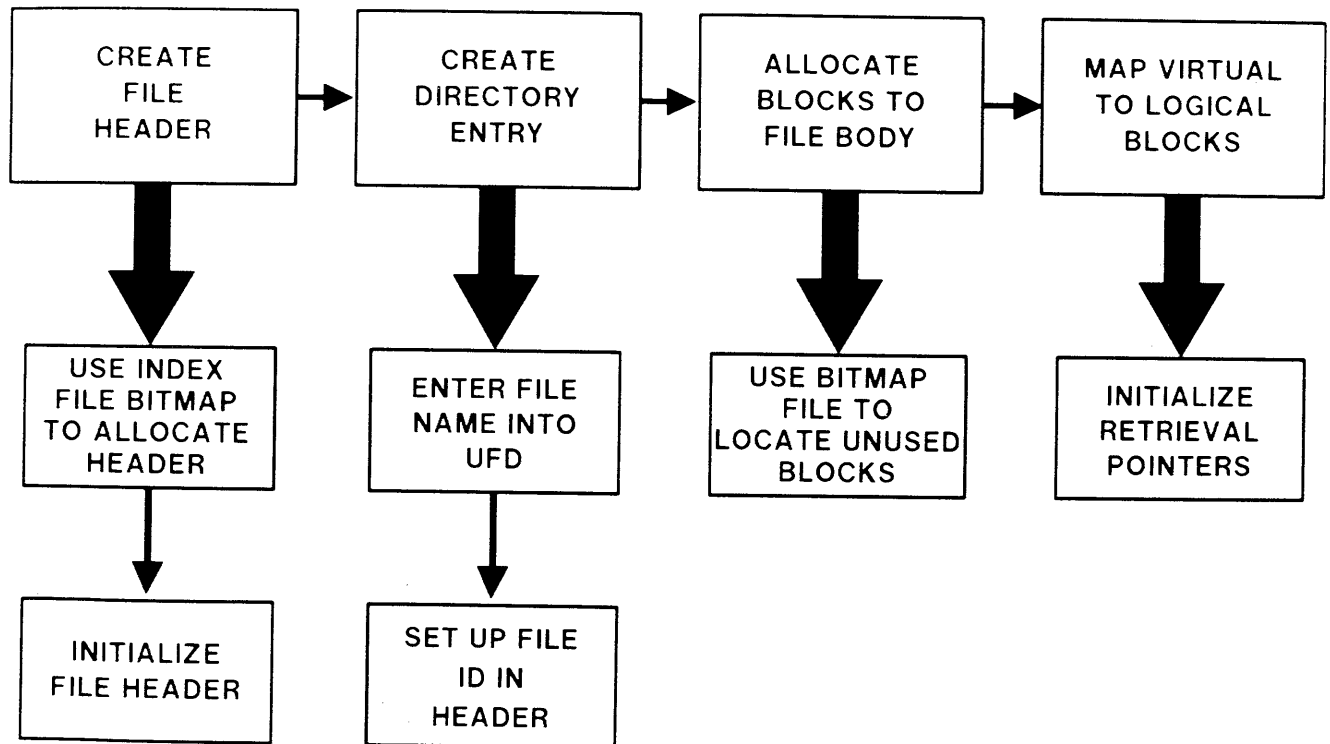


Figure 4-9 Creating a File

# FILE SYSTEM OVERVIEW

## Accessing a File

- By file name - DB1:[101,101]DATA.DAT;1

MFD from device mounted on DB1: is searched for 101101.DIR

File ID for 101101.DIR is used to find the file header

Retrieval pointers from header are used find UFD file

UFD is searched for entry for DATA.DAT

File ID for DATA.DAT is used to find the file header

Retrieval pointers from header are used to find file

File is accessed

- If file ID is known, file header can be accessed without using directories

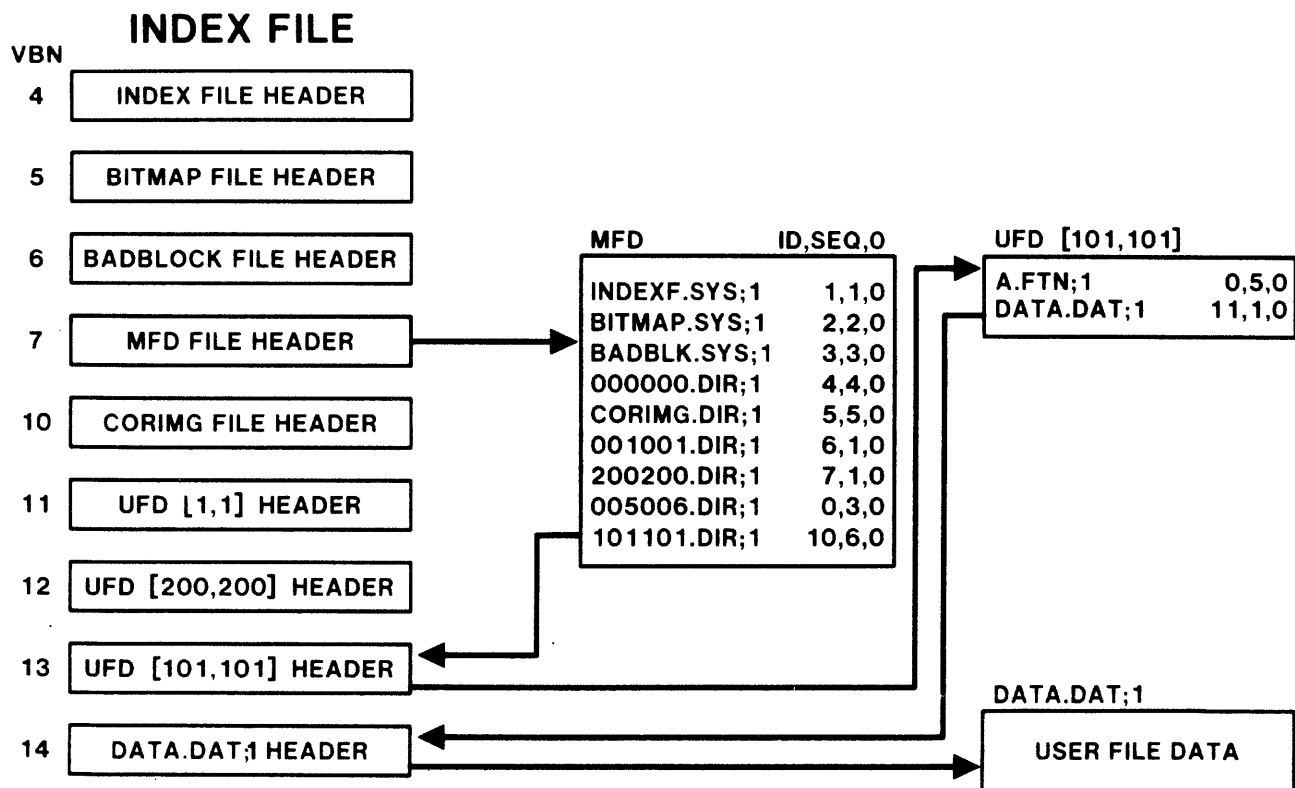


Figure 4-10 Accessing a File

## FILE SYSTEM OVERVIEW

### THE FILE PROCESSOR

#### File Control Processors

- Privileged system task which handles file-specific I/O
- Processes QIO commands queued to its receive queue
- Several file processors supplied with system
  - FllACP - Used for FILES-11 disk volumes
  - MTAACP - Used for magnetic tape volumes
  - NETACP - Used by DECNET
- To speed up file operations, dedicate appropriate FCPxxn to volumes
  - >INS \$FCPxxx/TASK=DB1FCP
  - >MOU DK0:/ACP=DB1FCP

## FILE SYSTEM OVERVIEW

### Logical Units

- Tasks specify I/O devices by using logical unit numbers.
- Each logical unit number refers to a unique I/O device.
- Pointer to an entry of the logical unit table for the task.
- The logical unit table is in the task header.
- Each entry is two words long:

Word one is a pointer to the UCB for the device:

Word two is a pointer to a FILES-11 window block if file is open; and 0 otherwise.

- FILES-11 window block is a data structure used to store retrieval pointers.
- Logical unit table constructed and units assigned at taskbuild.
- Logical unit assignments can be changed by:

REASSIGN command

ALUN\$ directive



FILE SYSTEM OVERVIEW

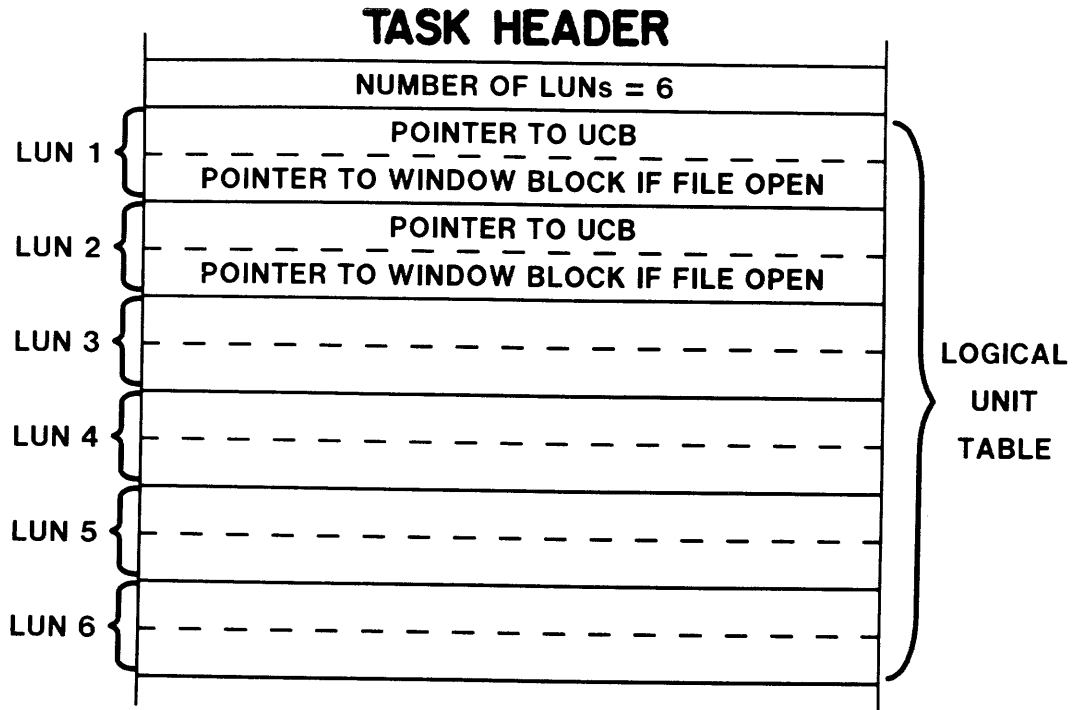


Figure 4-11 The Logical Unit Table

## Data Structures

- The Volume Control Block (VCB)
  - Created from information in home block
  - One VCB per mounted volume
  - Contains
    - Transaction count for volume
    - Logical block number of index file bitmap
    - Logical block number of storage bitmap
    - Pointers to other data structures, e.g. FCB
  
- The File Control Block (FCB)
  - Created from file header
  - One FCB per open file
  - Contains
    - Logical block number of file header
    - File number and sequence numbers
    - File owner and protection code
  
- FILES-11 Window Block
  - One window block per accessor to file
  - Contains
    - Access privileges of accessor
    - Retrieval pointers (seven by default)

### NOTE

Retrieval pointers in the file header use one byte for the block count and three bytes for the disk address; those in the window block use two bytes for the count and four bytes for the disk address.

FILE SYSTEM OVERVIEW

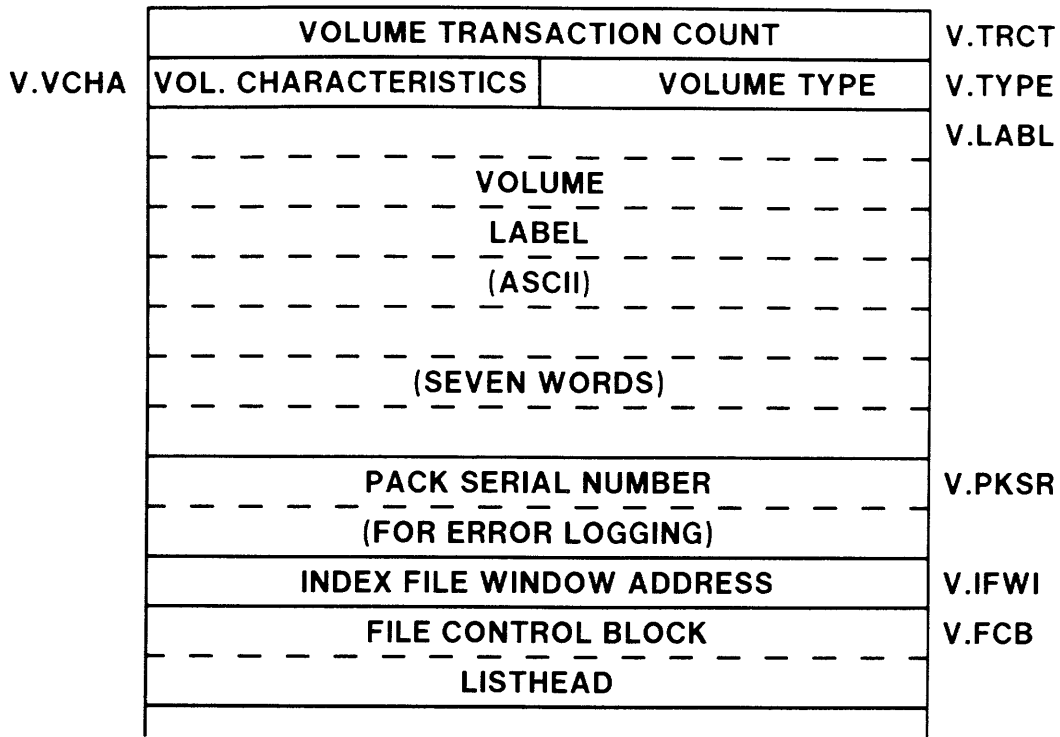


Figure 4-12 The Volume Control Block (Part One)

FILE SYSTEM OVERVIEW

V.IBSZ	INDEX FILE BITMAP SIZE	V.IBLB
	INDEX FILE BITMAP LBN	
V.SBCL	MAXIMUM NUMBER OF FILES	V.FMAX
	BITMAP FILE CLUSTER	DEFAULT SIZE OF WINDOW
V.FIEX	BITMAP FILE SIZE	V.SBSZ
	DEFAULT FILE EXTENSION	V.SBLB
V.LRUC	BITMAP FILE LBN	V.VOWN
	VOLUME OWNER UIC	
	VOLUME PROTECTION WORD	
	DEFAULT FILE PROTECTION WORD	
V.FFNU	AVAILABLE LRU SLOTS	V.FRBK
	NUMBER OF FREE BLOCKS ON VOLUME	V.STS
1ST FREE BLOCK IN INDEX BITMAP	VOLUME STATUS	
	RESERVED FOR FUTURE USE	V.EXT

Figure 4-12 The Volume Control Block  
(Part Two)

FILE SYSTEM OVERVIEW

	POINTER TO NEXT FCB	F.LINK
	FILE NUMBER	F.FNUM
	FILE SEQUENCE NUMBER	F.FSEQ
F.FSQN	FILE SEGMENT	UNUSED
	UIC OF FILE OWNER	F.FOWN
	FILE PROTECTION CODE	F.FPRD
F.SCHA	SYSTEM CHARACTERISTICS	USER CHARACTERISTICS
	FILE HEADER	F.HDLB
	LOGICAL BLOCK NUMBER	
	LOGICAL BLOCK NUMBER OF VIRTUAL BLOCK 1 OF CONTIGUOUS FILE (0 OTHERWISE)	F.LBN
F.NLCK	SIZE OF FILE IN BLOCKS	F.SIZE
	NUMBER OF LOCKS	NUMBER OF ACCESSSES
	STATUS BITS	NUMBER OF WRITE ACCESSSES
	DIRECTORY EOF BLOCK NUMBER	F.DREF
	1ST WORD OF DIRECTORY NAME	F.DRNM
	POINTER TO EXTENSION FCB	F.FEXT
	STARTING VIRTUAL BLOCK NUMBER OF THIS FILE SEGMENT	F.FVBN
	POINTER TO LOCKED BLOCK LIST	F.LKL
	WINDOW BLOCK LIST	F.WIN

Figure 4-13 The File Control Block

FILE SYSTEM OVERVIEW

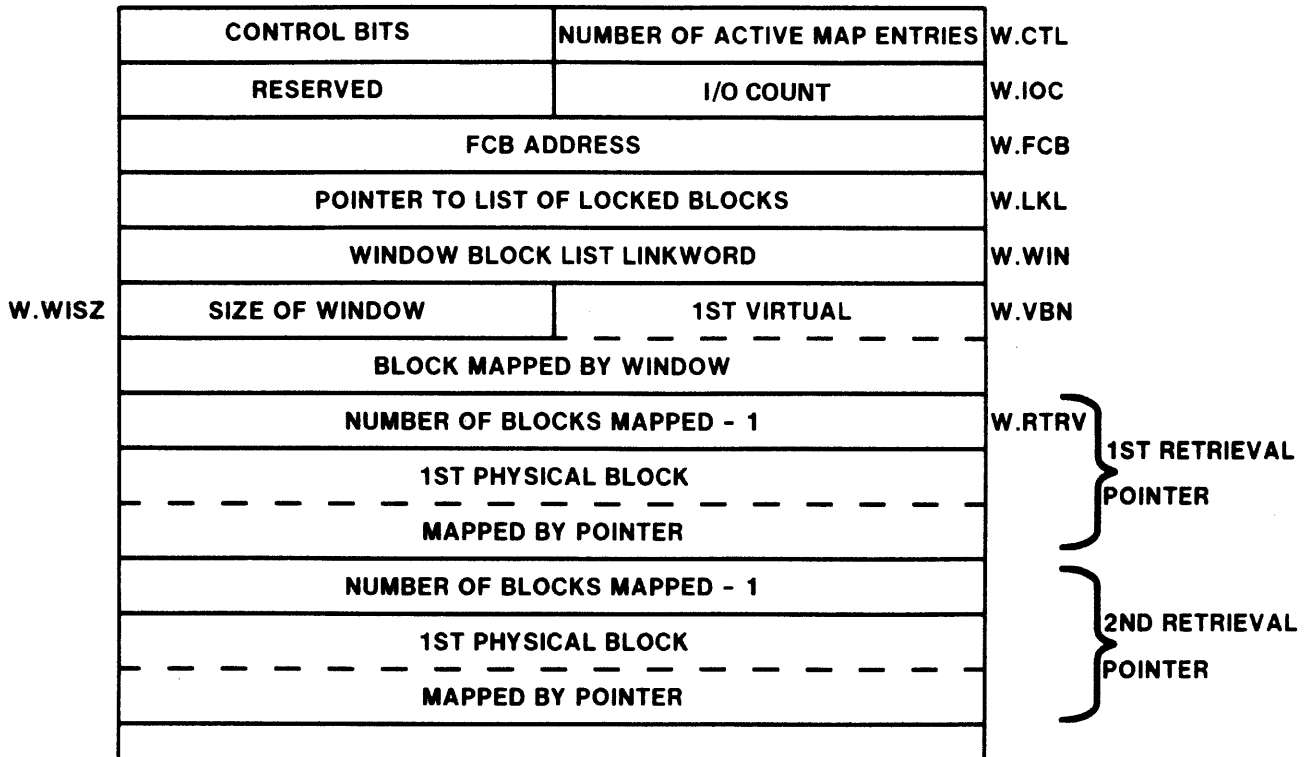


Figure 4-14 FILES-11 Window Block

**Mounting a Volume**

- Volume mounted by MOUNT command

Compares the volume label with that specified in the MOUNT command

Copies homeblock information into VCB

Associates an ACP with the volume

- Steps in mounting a FILES-11 volume:

Volume Control Block is created

VCB is linked from the UCB using U.VCB

Index file is opened

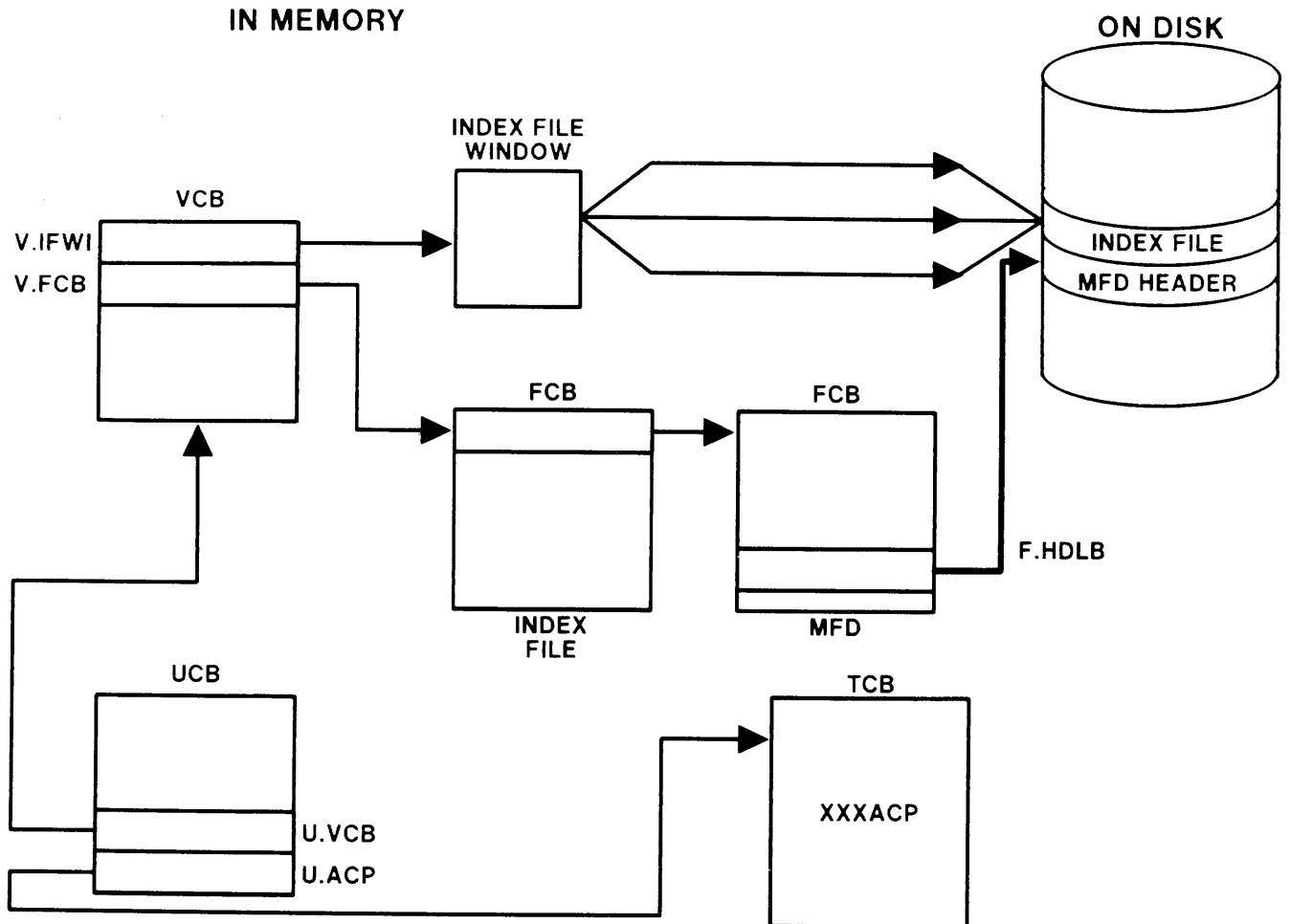


Figure 4-15 Mounting a Volume

## FILE SYSTEM OVERVIEW

### Opening a File

- Steps in opening a file:

File Control Block or FCB is created.

FILES-11 window block is created for file.

FCB is inserted in the FCB queue for volume.

Pointer from logical unit table to window block is initialized.

- Shared files have only one FCB but separate window blocks.
- File system keeps, in memory, a list of FCBs of the more recently used directories.

This list is called the LRU.

Eliminates need to read directories from disk when file is accessed.

Least recently used directory is flushed when new directory accessed if list is full.

Size of LRU list is determined by LRU switch on INI or HOM command.



# FILE SYSTEM OVERVIEW

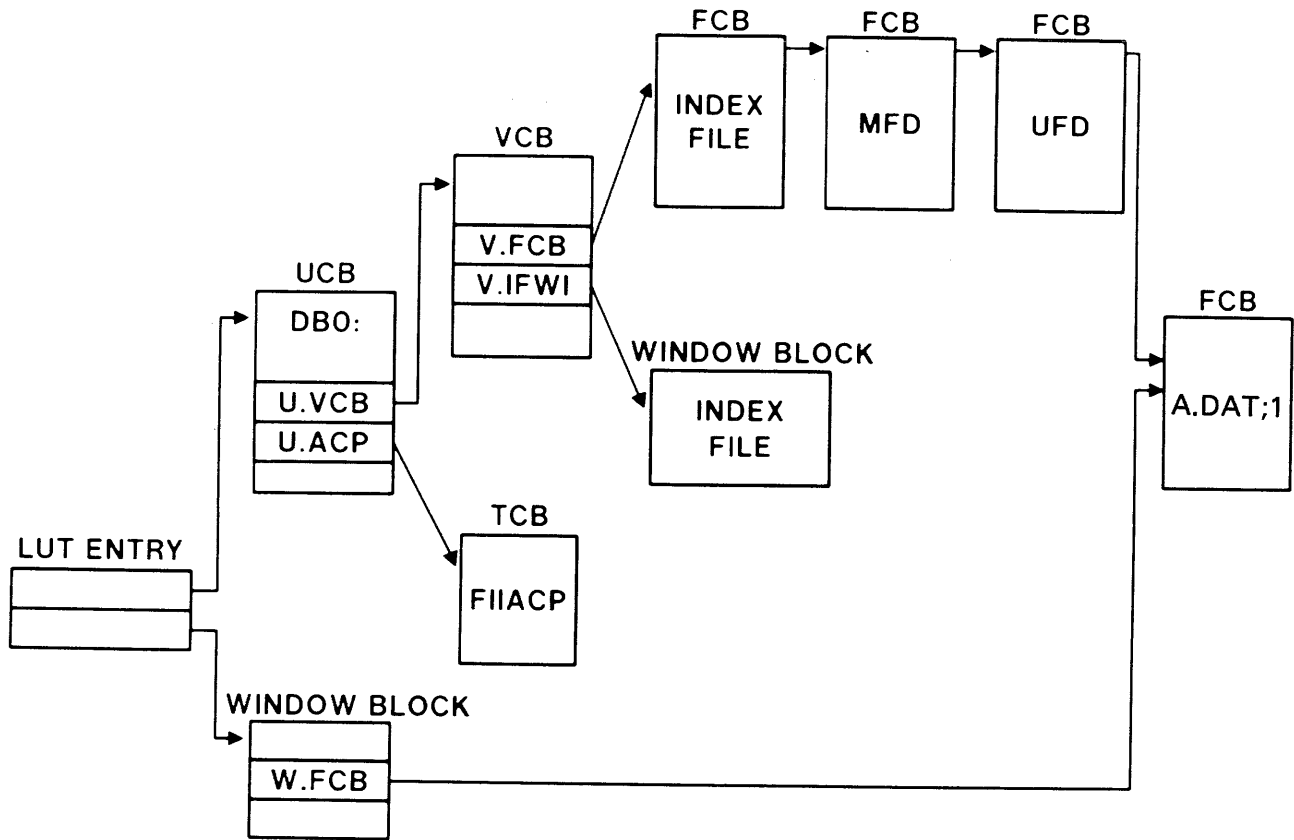


Figure 4-16 Opening a File

FILE SYSTEM OVERVIEW

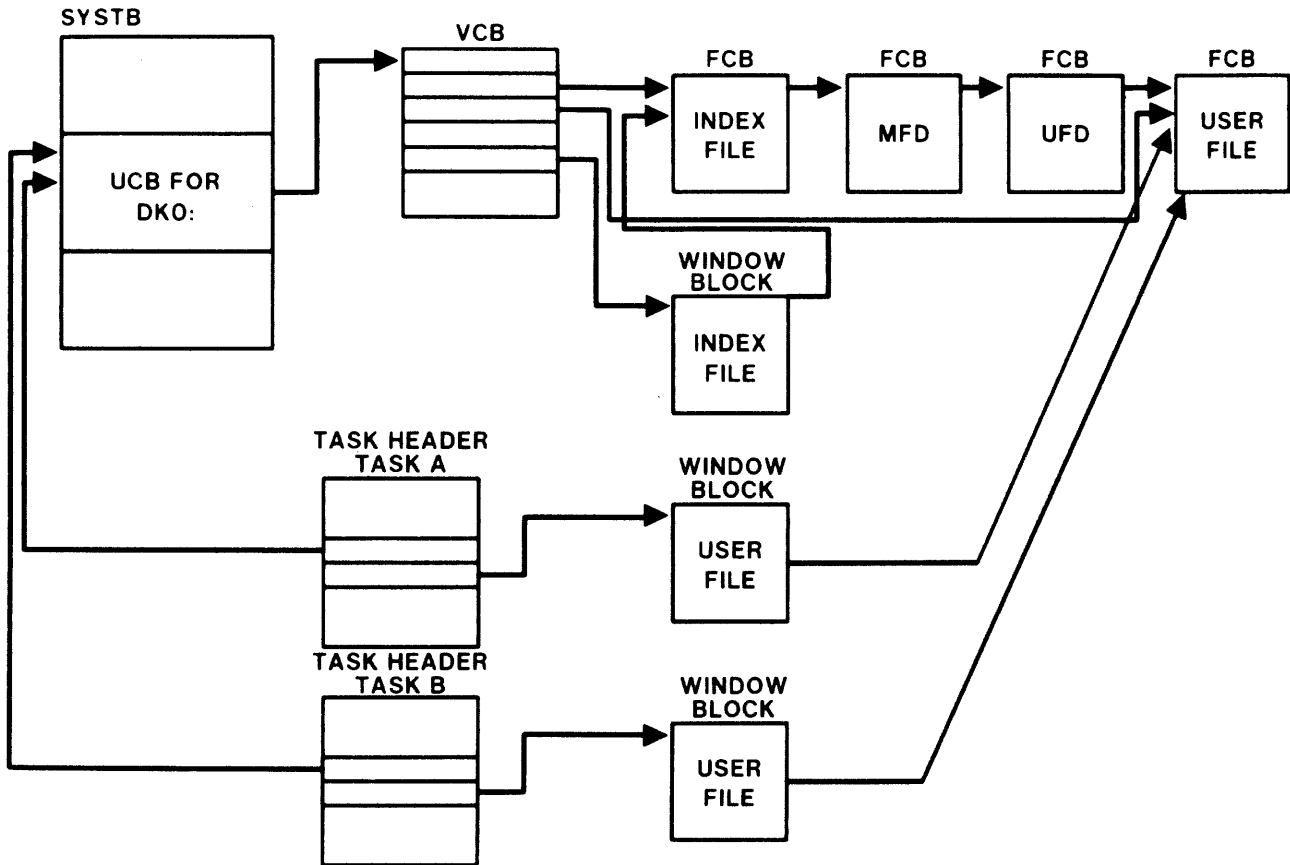


Figure 4-17 Shared Access

# SYSTEM GENERATION



# SYSTEM GENERATION

## INTRODUCTION

The RSX-11M operating system is designed to support a large variety of application environments and possible hardware configurations available to the PDP-11 processor. The process used to adapt the system to these varied conditions is called System Generation or SYSGEN.

The RSX-11M SYSGEN procedure is designed to allow customizing of the operating system to be performed in an efficient and accurate manner. The procedure is run under the control of supplied indirect command files. Facilities such as VMR and SAV are provided to help the user set up his system quickly.

## OBJECTIVES

1. Generate a functioning RSX-11M system.
2. Perform the ancillary functions, VMR and SAV, to produce a practical system.

## RESOURCES

1. RSX-11M System Generation and Management Guide



# SYSTEM GENERATION

## OVERVIEW

### **SYSGEN Functions**

- Provide support for existing hardware
  - The processor model (e.g., PDP-11/44)
  - Processor options (e.g., memory management, floating-point processor)
  - Devices installed on system
  - Number of controllers and physical units
  - Vector and CSR addresses for all devices
  
- Provide needed software features
  - Executive options (e.g., directives, 'round-robin')
  - File system (version of F11ACP)
  - Resident library support (e.g., FCPRES)
  - Terminal support (e.g., full-duplex)

## SYSTEM GENERATION

### The SYSGEN Process

- SYSGEN procedure is contained in three indirect command files

SYSGEN.COMD - First phase of SYSGEN

Assembles Executive  
Assembles device drivers  
Creates command files to be used in phase two

SYSGEN2.COMD - Second phase of SYSGEN

Taskbuilds the Executive  
Taskbuilds the device drivers  
Creates needed libraries  
Taskbuilds the privileged system tasks

SYSGEN3.COMD - Third phase of SYSGEN

Allows system tasks to be rebuilt

- Between phase two and phase three, VMR should be applied to the new system

Use VMR command file SYSVMR.COMD created by the SYSGEN procedure

Can be edited to add desired partitions  
Must be edited if system is unmapped

Configure the new system

Set up partitions  
Load device drivers  
Install system tasks

- SYSGEN procedure creates saved answer file SYSSAVED.DAT

Contains answers to SYSGEN questions in symbolic form  
File can be modified by user for use in later SYSGEN



## SYSTEM GENERATION

### Types of SYSGEN

- SYSGEN can be performed using the base-line system on the distribution kit
  - Called a standalone SYSGEN
  - System is dedicated to SYSGEN, no other users
- SYSGEN can be performed using an existing RSX-11M system
  - Called an on-line SYSGEN
  - Other users can use the system during most of the SYSGEN process
- MCR commands can be inhibited during the SYSGEN process
  - Called a PREPGEN
  - Saved answer file can be corrected/modified for use later in live SYSGEN

## SYSTEM GENERATION

### **New Features for Version 4.0**

- Autoconfigure option determines correct hardware configuration
  - Processor type
  - CSR and vector addresses
  
- Standard feature Executive option produces a mapped system
  - Most software options
  - Supports all layered products
  
- Improved saved answer file support
  - Saves responses to Phase II questions
  - Supports named input and output saved answer files
  - Can create a single saved answer file for Phase I and II
  
- A minimum of 28K words of memory is required for SYSGEN
- Directive commons increase POOL size
- Taskbuild .CMD and .ODL files are dynamically created
- A PLAS overlaid FCS resident library may be selected
- Either EDI or EDT may be selected for editing SYSGEN files
- Phase I can chain to Phase II without a break

## SYSTEM GENERATION

### PREPARING FOR SYSGEN

#### Distribution Kits

- There are several different kits available
  - 'Big Disk' distribution kit for RP04/05/06/07, RM02/03/05, RM80 and RA80
  - RK06/07 distribution kit
  - RL01/02 distribution kit
  - RK05 distribution kit
- Distribution kit must be copied before SYSGEN using DSC
  - Version 3.2 DSC cannot be used unless V 4.0 patch has been applied (see release notes)
  - Copy of standalone DSC supplied with kit can be used

#### Autopatch

- A collection of patches to the released system
  - Issued at regular intervals
  - Also may include patches to layered products
- Must always be applied to released version without previous patches
- Uses an indirect command file to generate patched system

## Individual Patches

- Patching source files

Used for Executive, driver and MCR patches

Use Source Language Input Program (SLP)

Create SLP command file  
Invoke SLP with command file

For MACRO-11 sources, output for SLP must be:

Assembled  
Task-built  
Integrated into system (Method depends on component  
patched)

- Patching object files

Used for patching utilities

Use Object Module Patch Utility (PAT)

Create MACRO-11 source file for correction  
Assemble correction file  
Apply correction to old object file using PAT

Output from PAT must be:

Task-built  
Reinstalled into the system

- Patching task image files

Infrequently used for operating system patches

Frequently used for patching layered products

Use Task/File Patch Program (ZAP)

Create ZAP command file  
Invoke ZAP to apply patches to task image file

- Patches supplied by DIGITAL are cumulative

Apply a patch only if you have already applied all  
previous patches

Unless the patch states otherwise, apply patch to most  
recent version of the component

## SYSTEM GENERATION

### DETAILS OF SYSGEN

#### Phase 1

There are seven sections in Phase 1

Setup - How SYSGEN is to be run

Target Configuration - The environment for which the SYSGEN is being performed

Host Configuration - The system on which SYSGEN is being run

Executive Options - What features are desired in the new system

Terminal Driver - Which type of terminal driver and which features are desired

System Options - Which file processor, CLI support, and POOL monitoring support is desired

Peripheral Options - Specification of devices, controllers and their vectors, and CSRs

After questions have been answered, the Executive and drivers are assembled

## SYSTEM GENERATION

### Phase 2

There are eight sections in Phase 2

Setup - How SYSGEN Phase 2 is to be run

Library Commons Creation - Modifies SYSLIB, creates other libraries used in taskbuilding system tasks

Executive Taskbuild - Creates system images RSX11M.TSK, EXCOM1.TSK and EXCOM2.TSK

System Image Creation - Creates RSX11M.SYS from RSX11M.TSK

Full-Duplex Terminal Driver Taskbuild - Creates the full-duplex driver if selected

Loadable Driver Taskbuild - Creates all drivers not built into the Executive

Privileged Task Taskbuild - Builds privileged system tasks

System VMR - Modifies RSX11M.SYS, creating partitions, installing tasks, etc.

## SYSTEM GENERATION

### Phase 3

- Optional - May be performed when and as often as desired
- Used to build optional tasks not included in distribution kit
- Used to rebuild supplied tasks to:
  - Change defaults
  - Incorporate support for ANSI magtape and/or FCS big-buffering
  - Use a resident FCS library
- Used to rebuild tasks after patching
- VMR must be used to remove and install new versions of tasks installed in the system image

## EXECUTIVE OPTIONS

### Standard Feature Executive

- Allows the generation of a system supporting all standard features
- Requires a mapped system
- Provides the following:

- DBMS-11 support
- FILES-11 ACP support
- RMS support
- Nonresident task support
- Loadable task loader
- Directive commons
- Memory management directives
- All other Executive directives
- Address checking support
- I/O rundown support
- Multiuser support
- ANSI Magtape support
- Loadable driver support
- AST support
- 20K word Executive
- Error logging
- Powerfail recovery
- User written driver support
- System controlled partitions
- Round-robin scheduler and disk swapping
- Software write lock support
- Queue manager
- Shuffler
- Crash dump support
- Full-duplex terminal driver
- DCL and two user written CLIs
- POOL monitoring
- PLAS resident FCS
- 'MIDDLE' F11ACP



## SYSTEM GENERATION

### The Terminal Driver

- Two possible terminal drivers:
  - Half-duplex driver
  - Full-duplex driver
- Half-duplex driver comes in three forms:
  - Baseline
  - Tailored
  - Tailorable
- The baseline half-duplex driver
  - Minimum terminal driver
  - Not available with multiuser systems
- The tailored half-duplex driver features include:
  - Automatic carriage/line feed
  - Write with CTRL/O cancellation
  - Breakthrough write
  - CTRL/R rewrite
  - Get multiple characteristics
  - Get terminal driver options
  - Read after prompt
  - Read with no echo
  - Read with special terminator
  - CRT rubout support
  - User terminal input buffering
- The tailorable driver allows selection of all possible terminal options
- The full-duplex driver includes:
  - Task checkpoint during input
  - Passes form feeds directly to the terminal
  - Supports unsolicited input character AST (requires Executive AST support)
  - Hold screen mode
  - LA30P support
  - Device independent cursor positioning
  - Plus features included in the tailored half-duplex driver
- Full-duplex driver requires a mapped system with loadable driver support

### **Choosing a File Processor**

- Several different versions of F11ACP available
- Versions differ in amount of overlaying and in number of internal buffers
- See discussion in module 'I/O Processing' for descriptions of available ACPS

## USING VMR

### Overview of VMR

- Can perform many of the same tasks as MCR
  - Define partitions
  - Load drivers
  - Install tasks
- Commands operate on system image file
- Used to perform system initialization for needed features
  - Set up partitions
  - Load standard drivers
  - Install system tasks and utilities

# SYSTEM GENERATION

## On a Mapped System

- SYSGEN generates a VMR command file which should be edited to produce the system desired
- All needed partitions are defined
  - Driver partition
  - Directive commons
  - All leftover space goes in GEN
- Commands for partitions needed by application tasks must be added to the command file
- All DEC-supplied drivers are loaded
- All important system tasks are installed

<b>GEN</b>	<b>321400</b>
<b>FCPPAR</b>	<b>275400</b>
<b>FCSRES</b>	<b>242700</b>
<b>SYSPAR</b>	<b>232600</b>
<b>DRVPAR</b>	<b>206200</b>
<b>TTPAR</b>	<b>146200</b>
<b>LDRPAR</b>	<b>143400</b>
<b>EXCOM2</b>	<b>134500</b>
<b>EXCOM1</b>	<b>120000</b>
<b>EXECUTIVE</b>	

Figure 5-1 Partition Structure on Mapped Systems

## SYSTEM GENERATION

### On an Unmapped System

- Modification of SYSVMR.CMD recommended on unmapped system

It is not possible for SYSVMR.CMD to create an optimal partition structure

- For unmapped 16K to 24K systems, VMR:

Creates partition GEN and installs all tasks into it

Length is always 40000 bytes

Creates partition SYSPAR

Length is 1000 bytes if FCPMIN chosen

Length is 1200 bytes if FCPSML chosen

Creates partition SPLPAR if PRT chosen

Length is 10400 bytes

- For unmapped 24K to 28K systems, VMR:

Creates partition GEN and installs all tasks into it

Length is always 40000 bytes

Creates partition SYSPAR

Length is 1000 bytes if FCPMIN chosen

Length is 1200 bytes if FCPSML chosen

Creates partition PAR14K

Length is 70000 bytes

Creates partition SPLPAR if PRT selected

Length is 10400 bytes

SYSTEM GENERATION

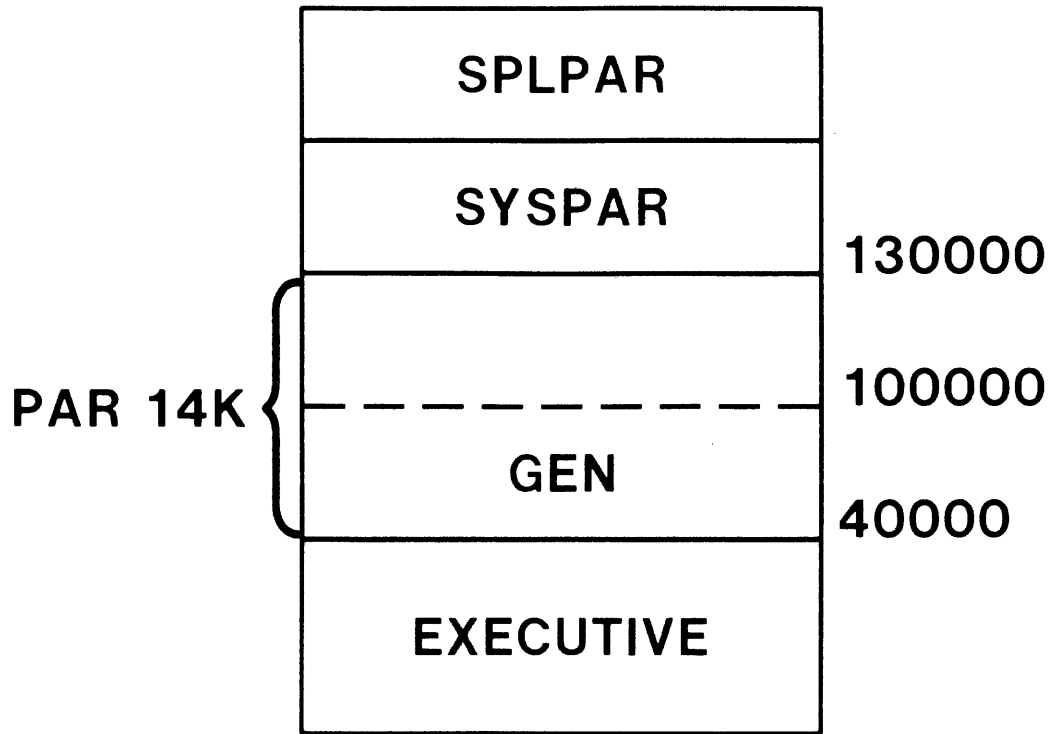


Figure 5-2 Partition Structure on Unmapped 24K to 28K Systems

SYSTEM GENERATION

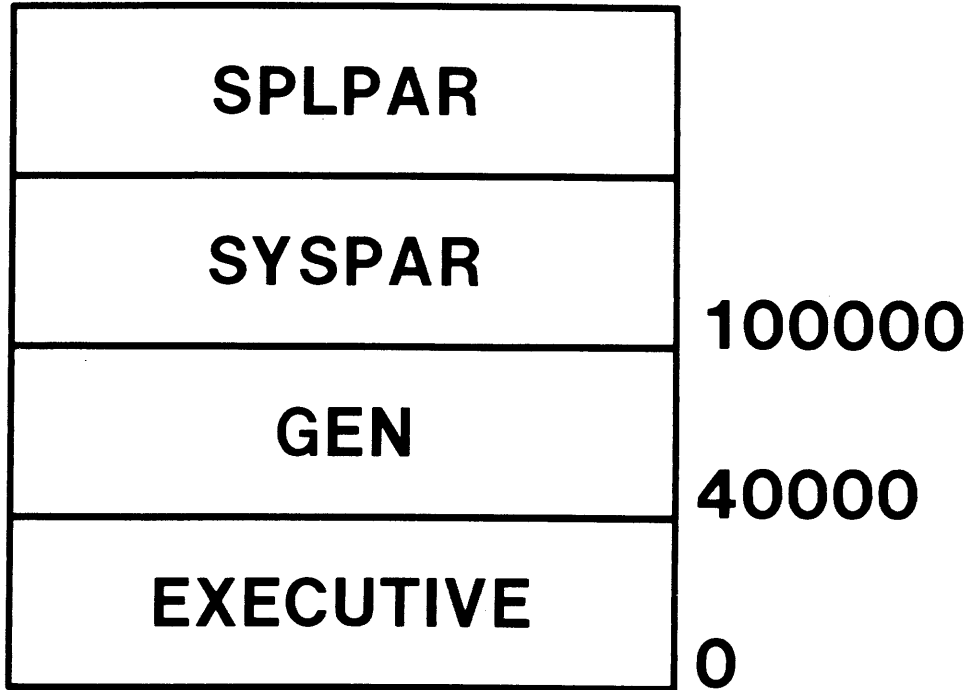


Figure 5-3 Partition Structure on Unmapped 16K to 24K Systems

## SYSTEM GENERATION

### SAVING THE NEW SYSTEM

- Copies the current system image into the system image file from which the system was booted
- Used to make a system hardware bootable
- System must be saved before compressed by DSC or BRU
- Requirements for saving a system

SAV must run from CO:

Error logging is not active

All tasks are installed from LB:

No checkpoint files are active

No volumes are mounted except the load device

The load device can be successfully dismounted

No tasks have outstanding I/O

No task is connected to interrupts

All drivers, active tasks and fixed tasks reside within the saved area of memory

- Saving a system

Lowest part of memory copied into buffer in SAV task

Secondary bootstrap program loaded into low memory

Special driver used to load system to and from disk

Cannot use interrupts

Same special drivers used by SAV and BOOT



SYSTEM GENERATION

Can create a bootstrap program within the volume bootblock

Reads in first block in system image file

Transfers control to secondary bootstrap in block just loaded into memory

Before writing system image to disk, converts logical block number in TCB into file ID

When system booted, file IDs in TCBs converted back into logical block number

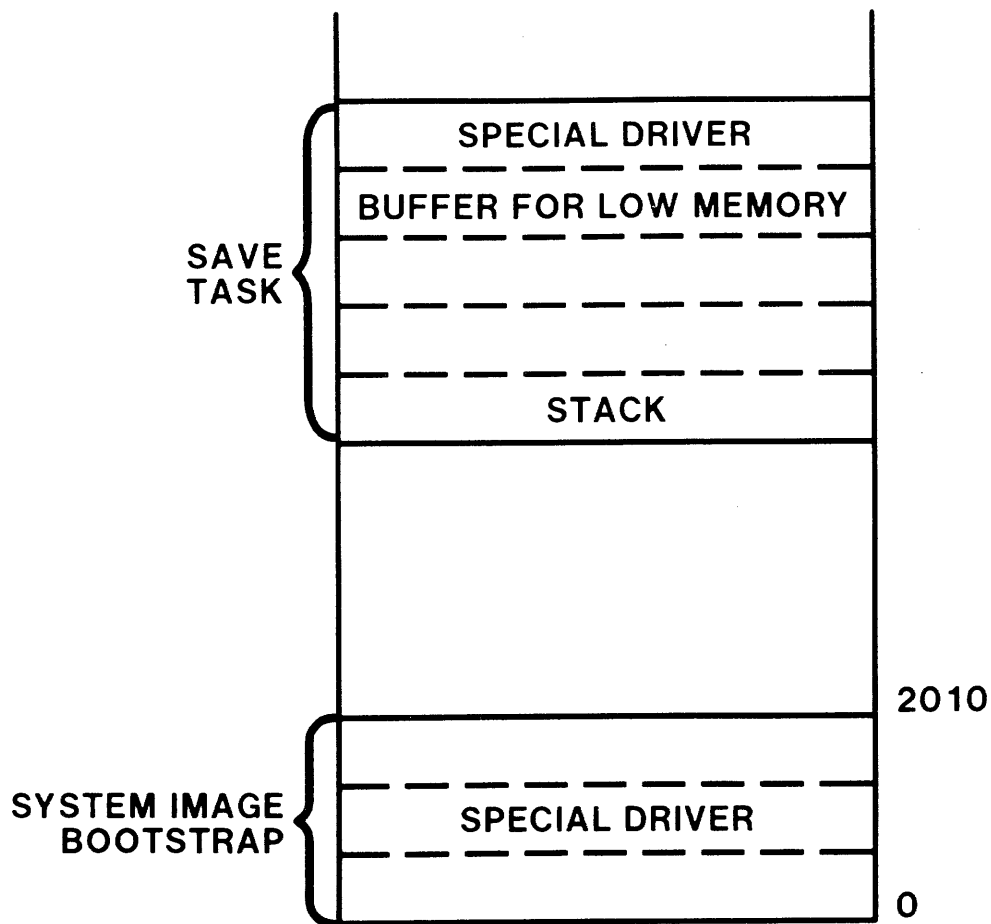


Figure 5-4 Saved System Image



# **PHYSICAL AND VIRTUAL MEMORY**



## INTRODUCTION

The most important resource managed by an operating system is physical memory. To manage memory, an operating system must define subdivisions of memory, allocate space to tasks, and optimize memory use. This module examines the data structures used to perform these tasks.

Since the PDP-11 uses 16-bit words, only 32K words of physical memory can be addressed unless some form of address relocation is provided. On the PDP-11, the KT-11 memory management hardware provides the mechanism for relocation. This module also explains the hardware and processing used.

## OBJECTIVES

1. Diagram the data structures used by the Executive to control physical memory.
2. List the steps in checkpointing a task.
3. Describe the memory management hardware.



## CONCEPTS

### Physical Addresses

- A contiguous series of word addressable hardware locations
- Defines main memory and peripheral device registers

### Virtual Addresses

- Set of addresses used within a task
- Program counter is a 16-bit register

User task can reference addresses between  $\emptyset$  and 177777 octal

Virtual addresses are local to a task

### Unmapped Systems

- 32K words of addressing space
- Maximum physical memory is 28K words
- Programs built for specific memory location
- No memory protection

PHYSICAL AND VIRTUAL MEMORY

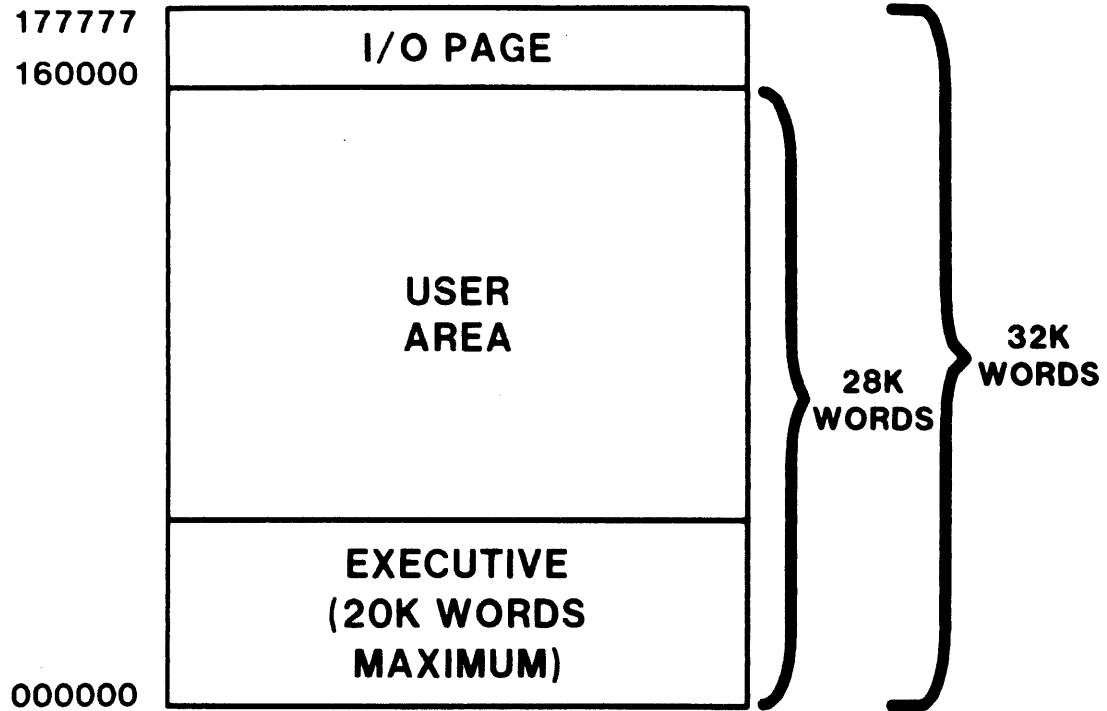


Figure 6-1 Typical Unmapped System



## PHYSICAL AND VIRTUAL MEMORY

### Mapped Systems

- KT-11 hardware is present
- Two types of mapped systems
  - 18-bit addresses
    - 128K words of addressing space
    - 124K words of physical memory
  - 22-bit addresses
    - 2048K words of addressing space
    - 1920K words of physical memory
- 16-bit virtual address converted to 18- or 22-bit physical addresses
- Virtual addresses range from 0 to 32767
- Relocation and memory protection provided

PHYSICAL AND VIRTUAL MEMORY

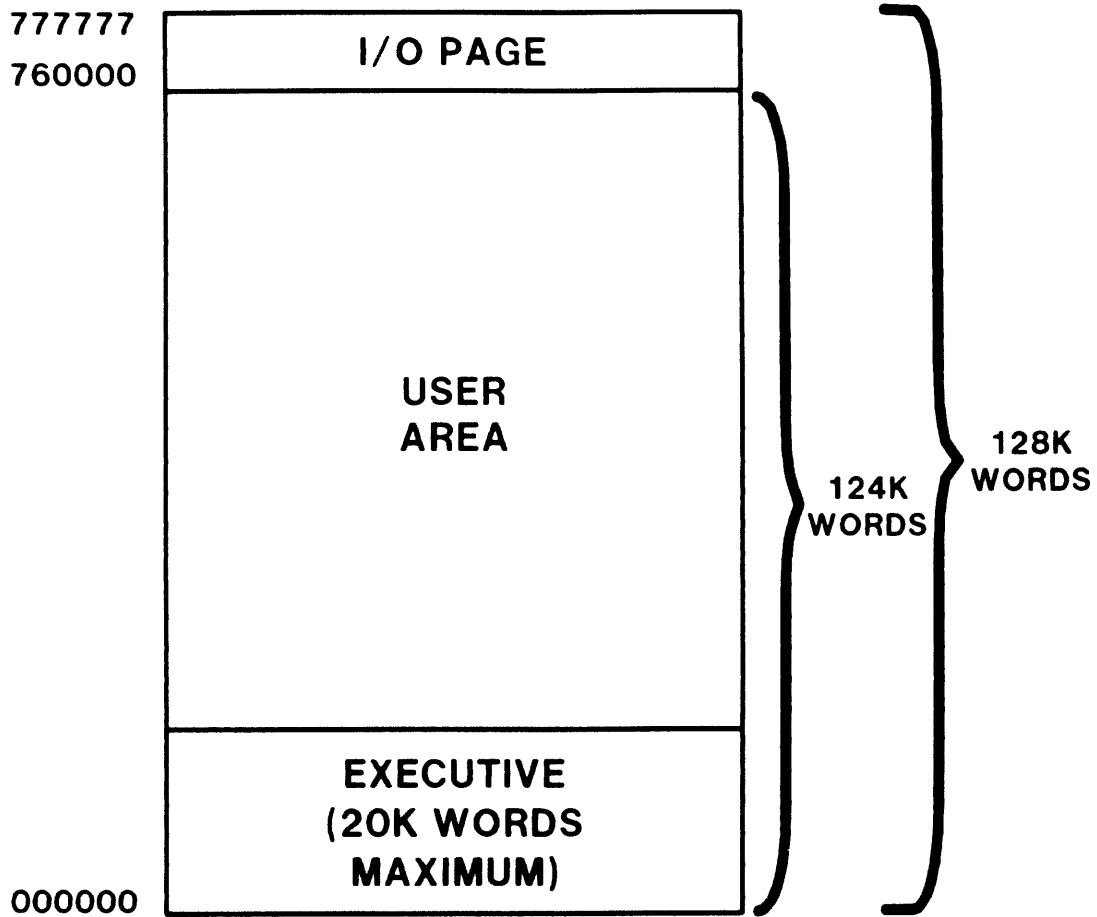


Figure 6-2 Typical Mapped System with 18-bit Addressing

PHYSICAL AND VIRTUAL MEMORY

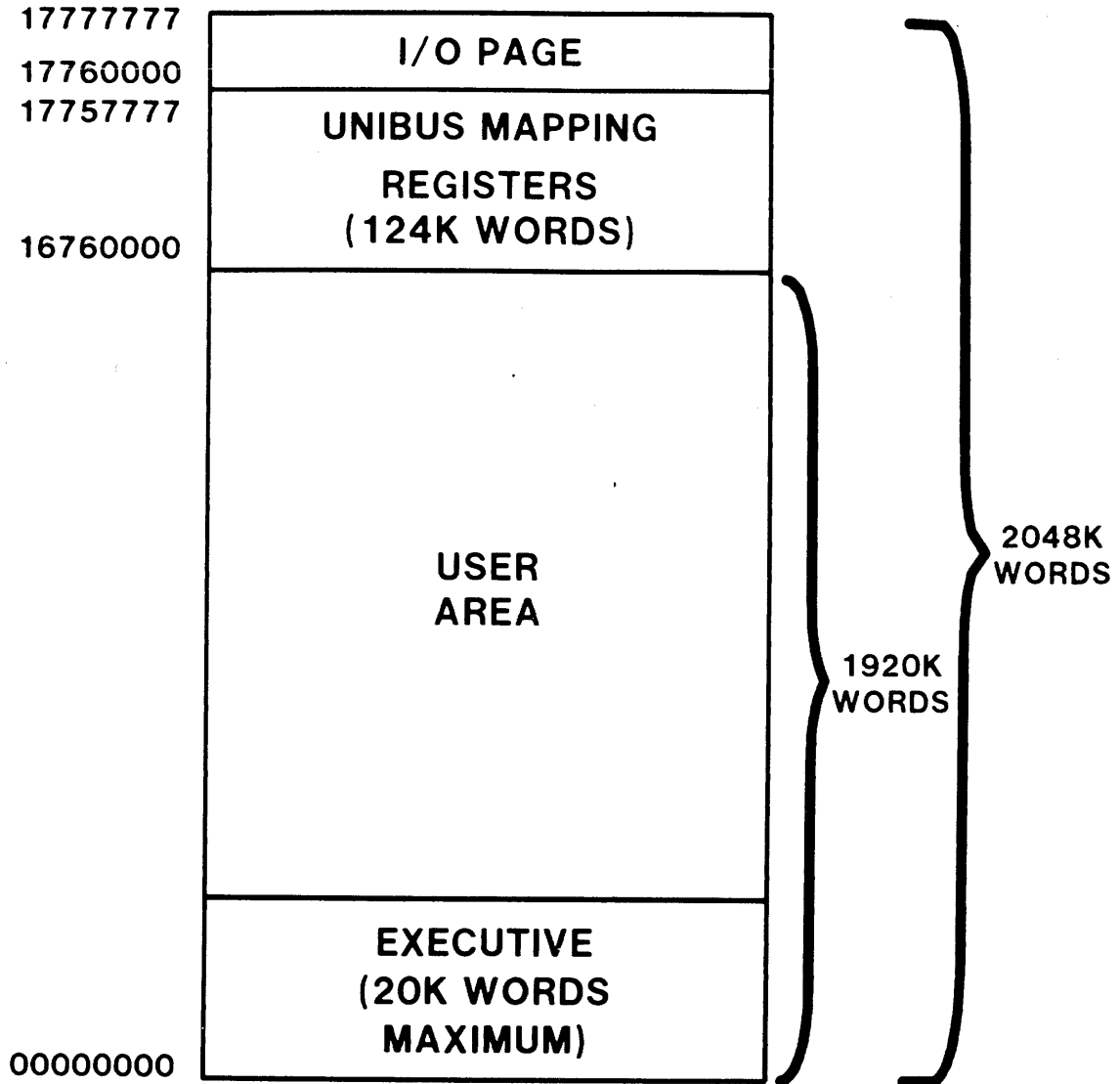


Figure 6-3 Typical Mapped System with 22-bit Addressing

## MEMORY MANAGEMENT

### Overview

- Basic functions

  - Perform memory relocation/mapping

  - Provide extended memory addressing capability

- Task is mapped in pages

  - Page length is from 1 to 128 memory blocks

  - Memory block is 32 words in length (100 octal bytes)

## PHYSICAL AND VIRTUAL MEMORY

### Memory Management Hardware

- Several sets of relocation registers: Active Page Registers (APRs)
- Each APR consists of two 16-bit words

#### Page Address Register (PAR)

Contains a physical memory address in units of 32 words memory blocks

Used to relocate 4K words of virtual memory (one page)

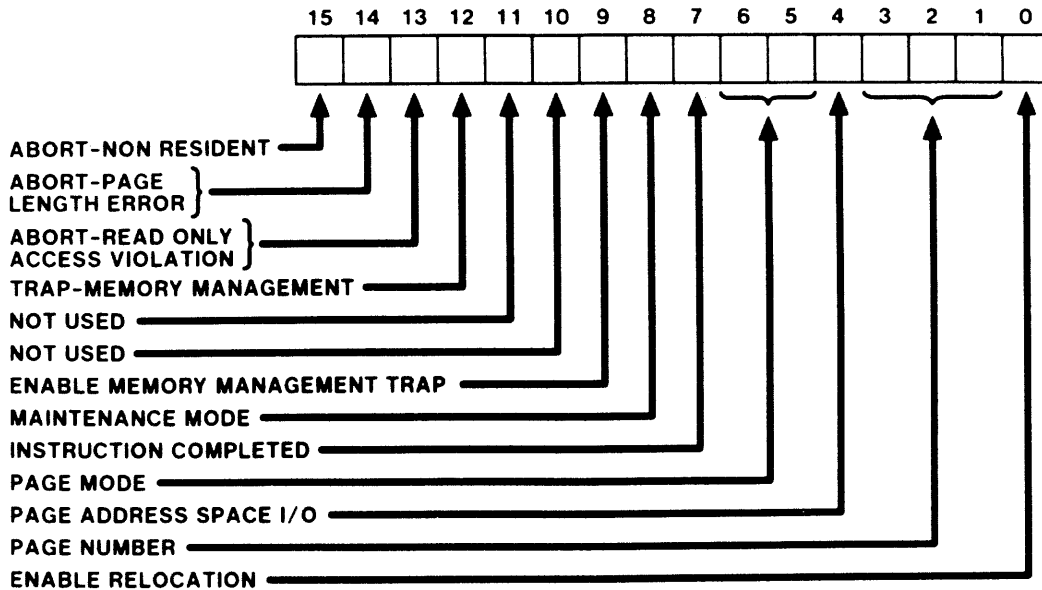
#### Page Descriptor Register (PDR)

Contains the size of the virtual memory block to be relocated

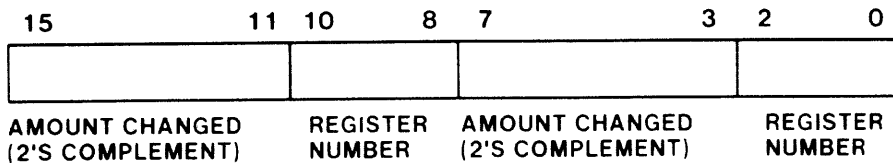
Provides control of access rights

- Every mapped system contains at least two sets of eight APRs
  - KERNEL Mode APRs
  - USER Mode APRs
- Larger processors have more APRs
  - APRs for KERNEL and USER mode Instruction and Data space
  - Supervisor mode Instruction and Data space APRs
- The Processor Status Word (PS) determines the APRs in use
- Four memory management registers (MMR0, MMR1, MMR2, and MMR3) control processor use of memory management
  - MMR0 - Error flags
    - Page number whose reference caused error
    - Other status flags
  - MMR1 - Only on 11/44 and 11/70
    - Records any autoincrement/decrement of general purpose registers
  - MMR2 - The Virtual Address Program Counter
  - MMR3 - Only on 11/44 and 11/70
    - Enables/disables Use of D space APRs
    - 22-bit mapping
    - UNIBUS mapping

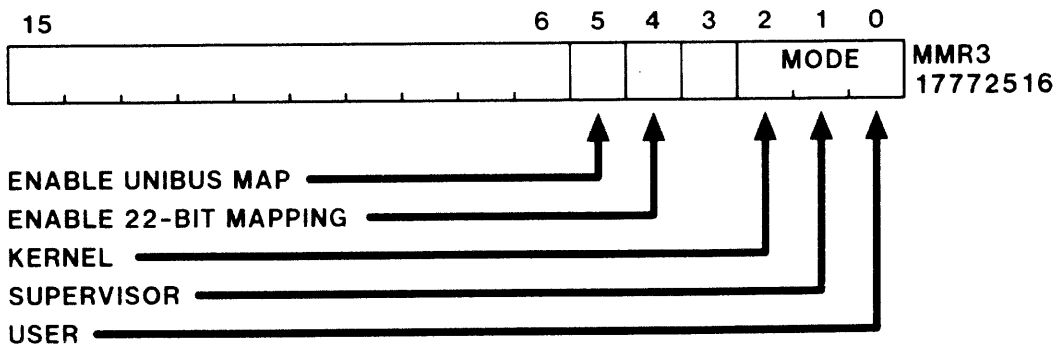
PHYSICAL AND VIRTUAL MEMORY



**MEMORY MANAGEMENT REGISTER #0 (MMRO)**



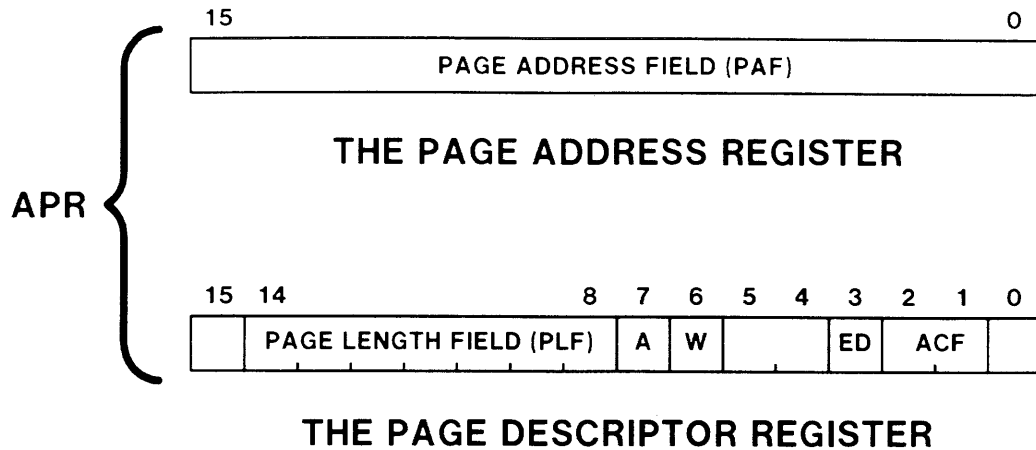
**MEMORY MANAGEMENT REGISTER #1 (MMR1)**



**MEMORY MANAGEMENT REGISTER #3 (MMR3)**

Figure 6-4 Registers Used by Memory Management

PHYSICAL AND VIRTUAL MEMORY



**ACF - ACCESS CONTROL FIELD**

**ED - EXPANSION DIRECTION**

**A } - ACCESS INFORMATION BITS**  
**W }**

**PLF - PAGE LENGTH FIELD**

Figure 6-5 Active Page Registers

PHYSICAL AND VIRTUAL MEMORY

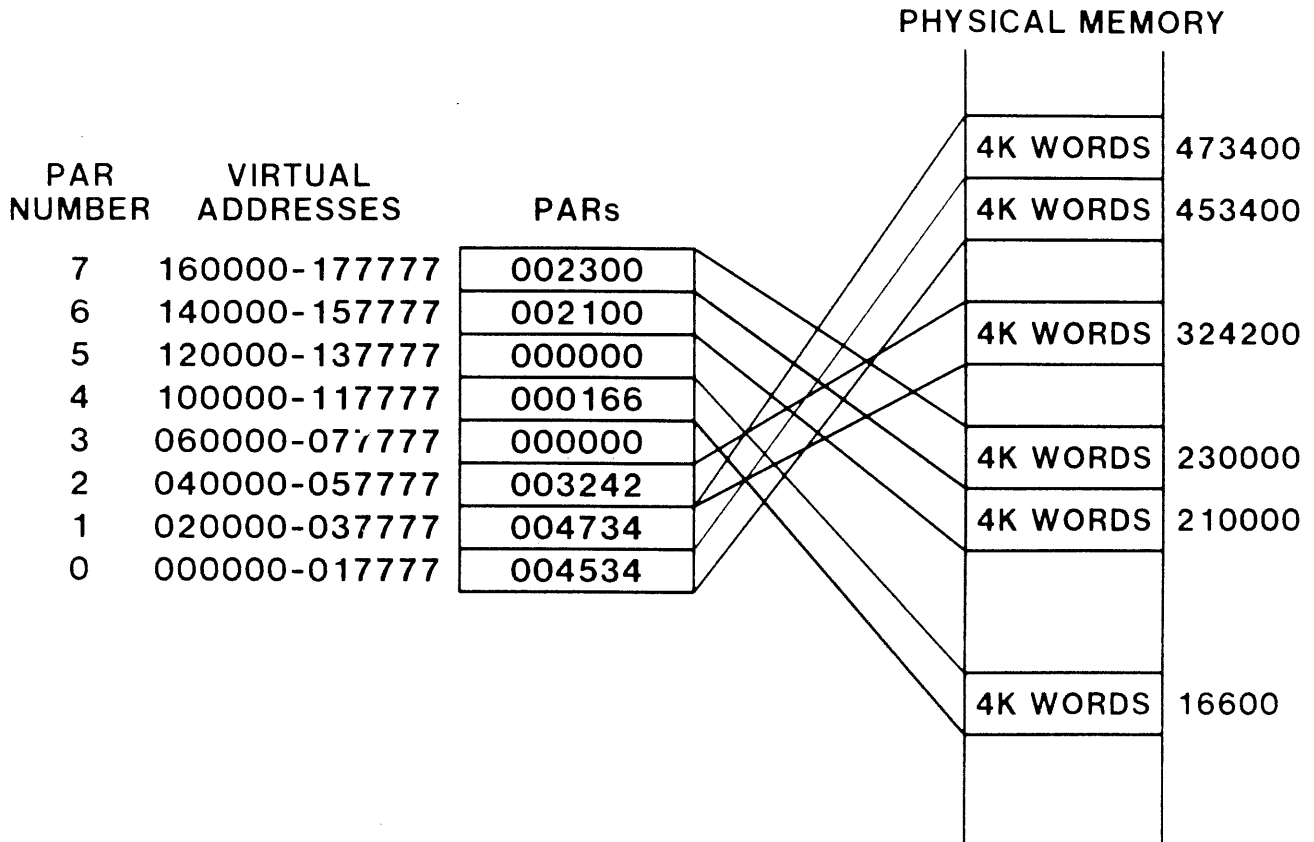


Figure 6-6 Page Address Registers



### Software Use of Memory Management

- RSX-11M uses KERNEL and USER instruction space APRs
- KERNEL APRs are loaded so that
  - APRs 0 through 3 or 4 point to Executive code and data
    - 4 APRs for 16K word Executives
    - 5 APRs for 20K word Executives
  - APR 7 points to the I/O page
  - Other APRs are dynamically mapped as needed
- User tasks are mapped using USER APRs
  - If task does not map to the Executive
    - APRs are used consecutively starting at APR 0
  - If task maps to the Executive
    - APRs 0 through 3 or 4 are the same as the KERNEL
    - APRs 0 through 3 or 4
    - APR 7 points to the I/O page
    - Other USER APRs are used to map the user task

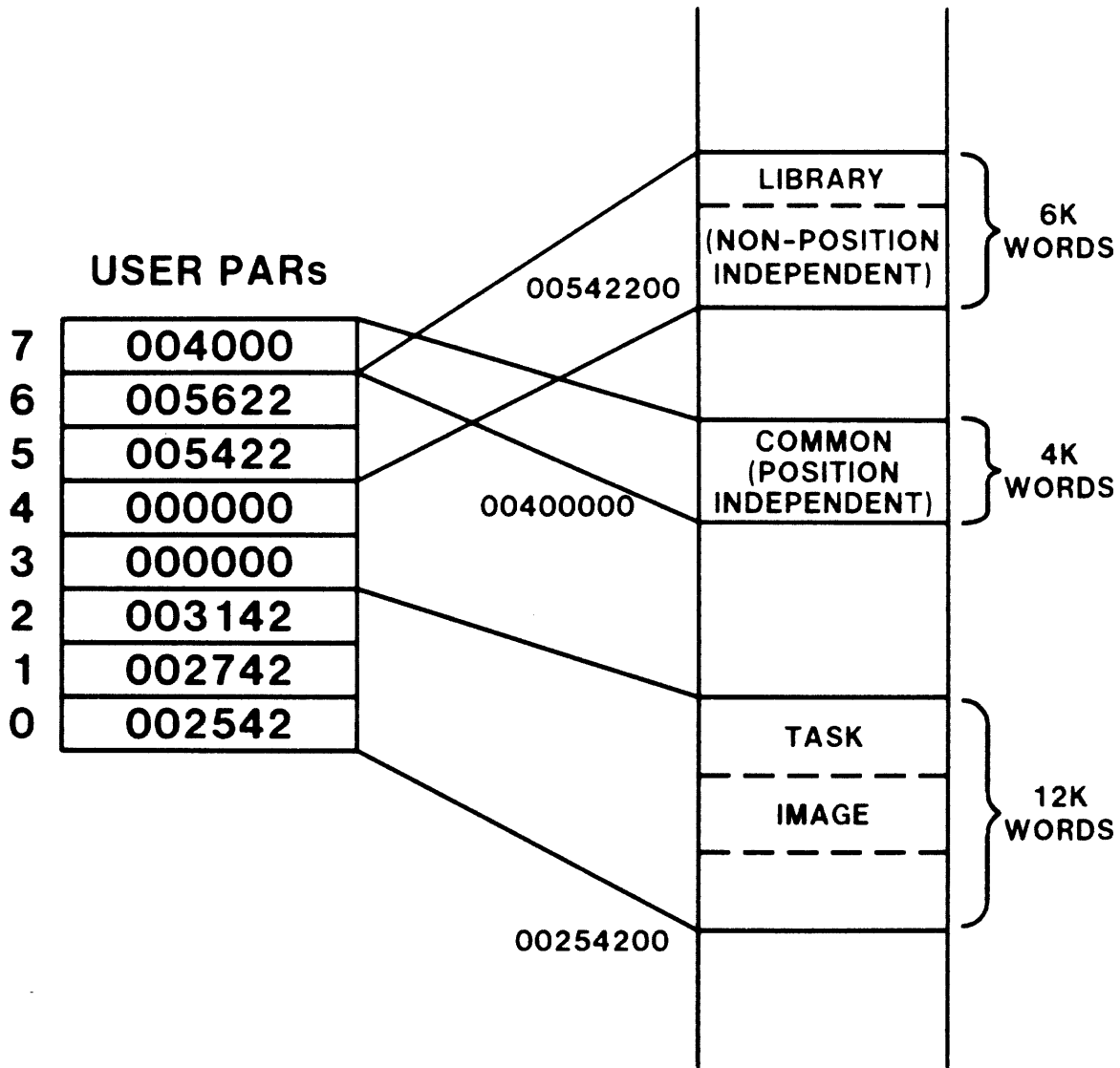


Figure 6-7 Use of Memory Management by a Nonprivileged Task

PHYSICAL AND VIRTUAL MEMORY

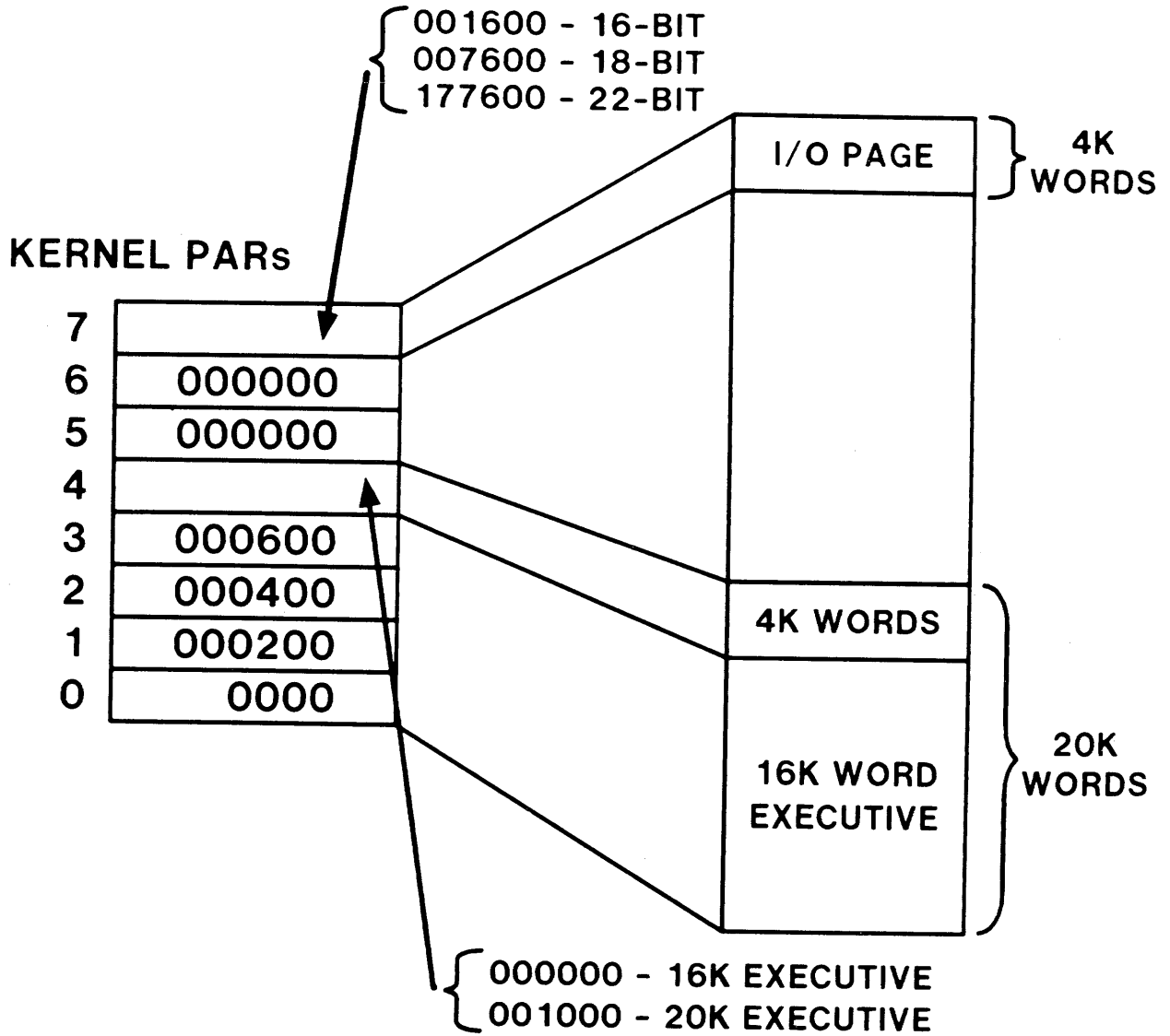


Figure 6-8 Use of Memory Management by the Executive

PHYSICAL AND VIRTUAL MEMORY

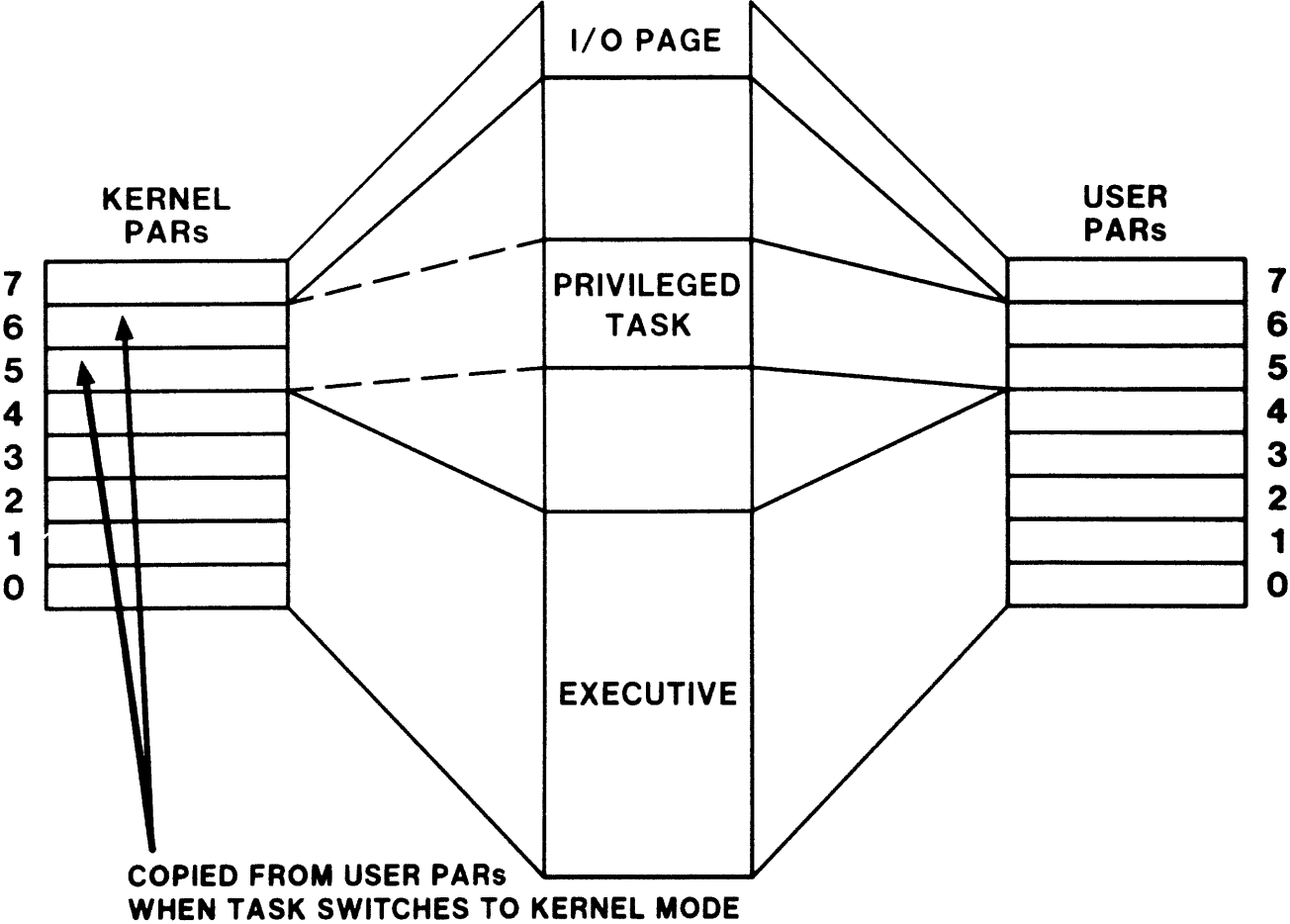


Figure 6-9 Use of Memory Management by a Privileged Task

## ALLOCATING PHYSICAL MEMORY

### Partitions

#### Task Partitions

- Controlled by user
- May be divided into subpartitions
- May be built to run in main partition or in one of the subpartitions
- Controlled by busy word P.BUSY in the PCB of the main partition

#### Common Partitions

- Used for shared data or code
- Linked to task statically by taskbuilder or dynamically by using memory management directives

#### Device Partitions

- Pseudo-areas whose addresses overlay the I/O page
- Allow nonprivileged tasks to access the I/O page

#### System-Controlled Partitions

- Used to hold executable tasks, device drivers, and dynamic regions
- Space allocated as needed by the Executive
- Tasks loaded into dynamically created subpartitions

PHYSICAL AND VIRTUAL MEMORY

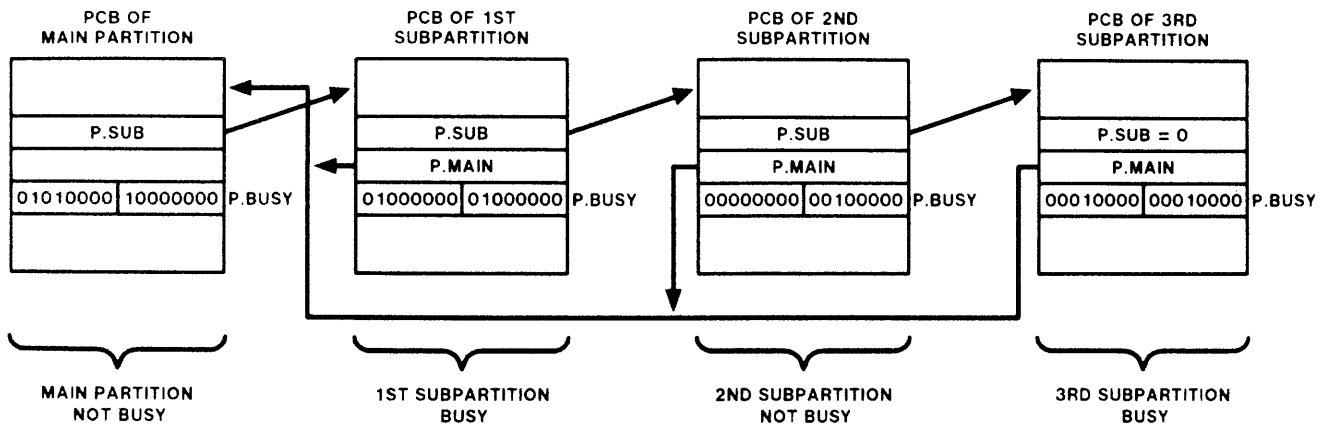


Figure 6-10 Subpartitions of a Task Partition

### **The Partition Wait Queue**

- Linked list of TCBs of tasks waiting for space in partition
- Ordered by descending task priority
- When TCB is placed in wait queue of system controlled partition, subpartition PCB is created but not linked to partition list
- First task in queue is allocated space before others

PHYSICAL AND VIRTUAL MEMORY

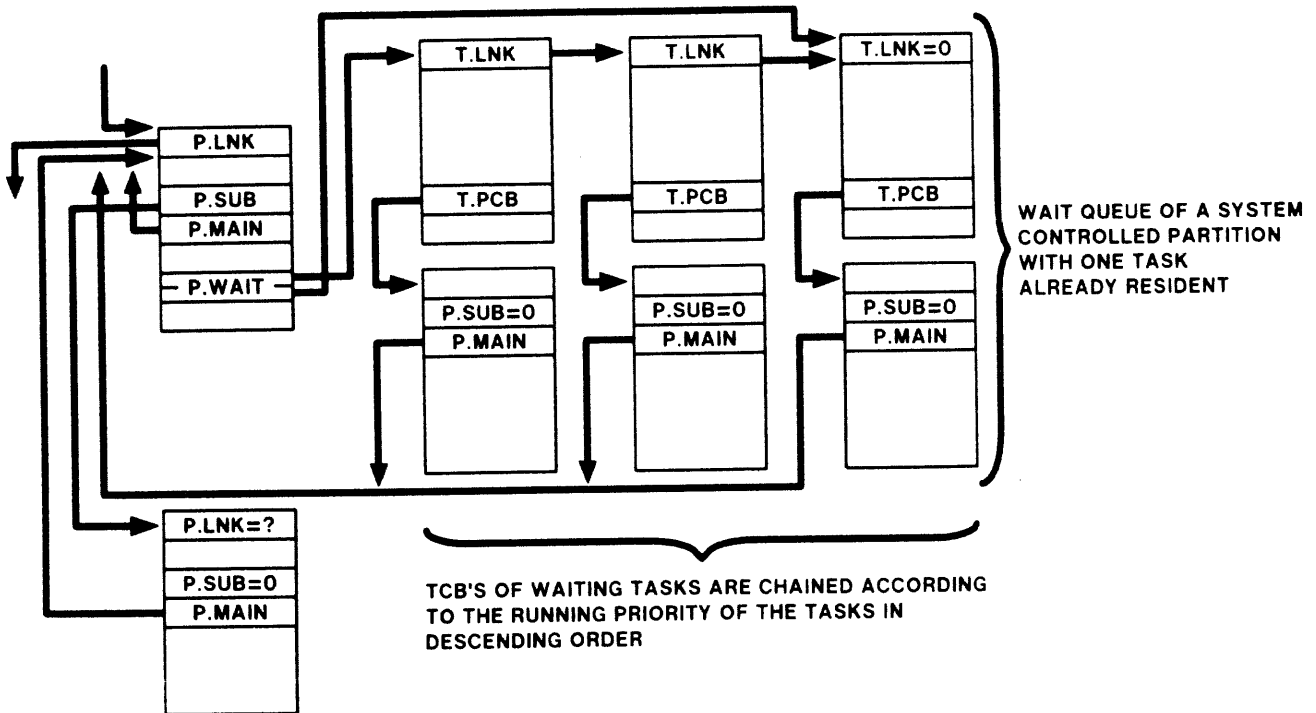
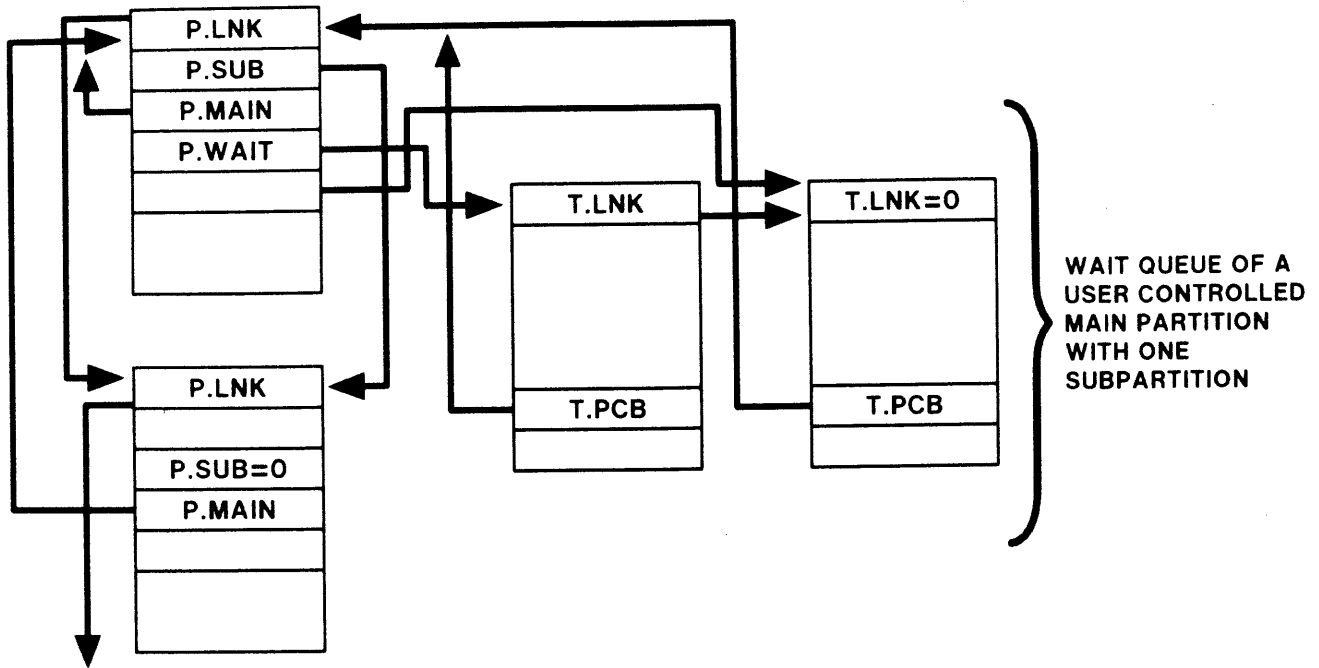


Figure 6-11 The Partition Wait Queue



## USING PHYSICAL MEMORY

### Loading Tasks

- Task TCB placed in loader queue after space allocated
- Loading performed by loader task, LOADR
- Loader task uses loader queue to decide which task to load next

Utility link word, T.LNK, used to link TCBs in queue

Location T.RCVL in the loader TCB is the queue listhead

- Steps in loading:

Executive places TCB of task to be loaded in the loader queue (LOADRs receive queue)

Executive unstops the loader

Loader scans queue and loads task

When queue is empty, loader calls \$STPCT to stop itself

### Checkpointing

- Task is copied from memory to space on a disk volume

Allows a higher priority task to execute

Copied either to a reserved area in task image file or to a system checkpoint file

Reserved area only used if system checkpoint files are full

- Steps in checkpointing a task

Test to see if task should be checkpointed

Initiate the checkpoint operation

Allocate checkpoint space and write the task to disk

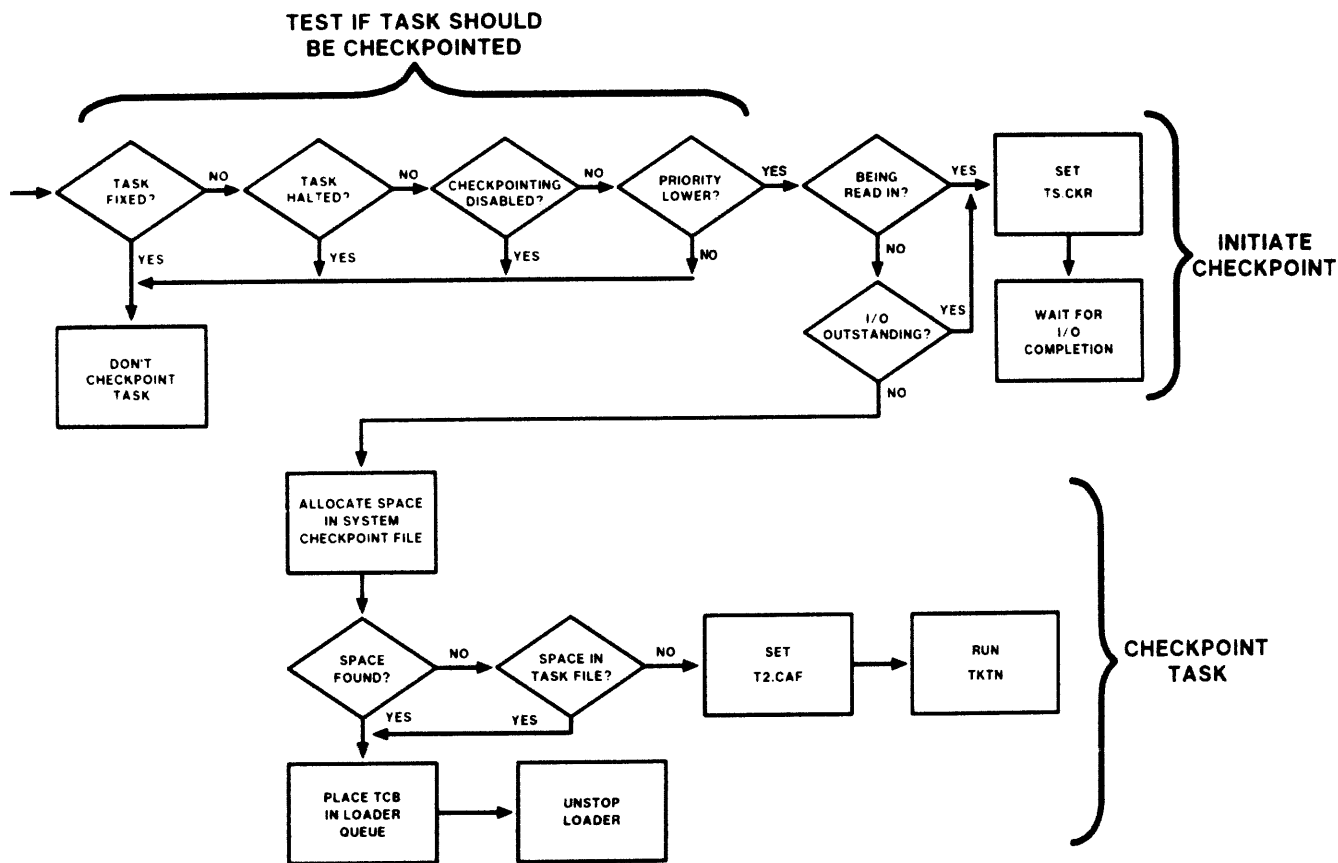


Figure 6-12 Steps in Checkpointing a Task

PHYSICAL AND VIRTUAL MEMORY

POINTER TO NEXT CHECKPOINT PCB	0 P.LNK
UCB ADDRESS OF CHECKPOINT DEVICE	2 P.PRI
_____ LBN OF CHECKPOINT FILE _____	4 P.NAM
	6
POINTER TO NEXT CHECKPOINT SUBPARTITION CB	10 P.SUB
POINTER TO CHECKPOINT MAIN PARTITION CB	12 P.MAIN
RELATIVE BLOCK NO. WITHIN CHECKPOINT FILE	14 P.REL
SIZE OF CHECKPOINT TASK (IN DISK BLOCKS)	16 P.SIZE

**CHECKPOINT PARTITION CONTROL BLOCK**

Figure 6-13 System Checkpoint Files: The Checkpoint PCB

PHYSICAL AND VIRTUAL MEMORY

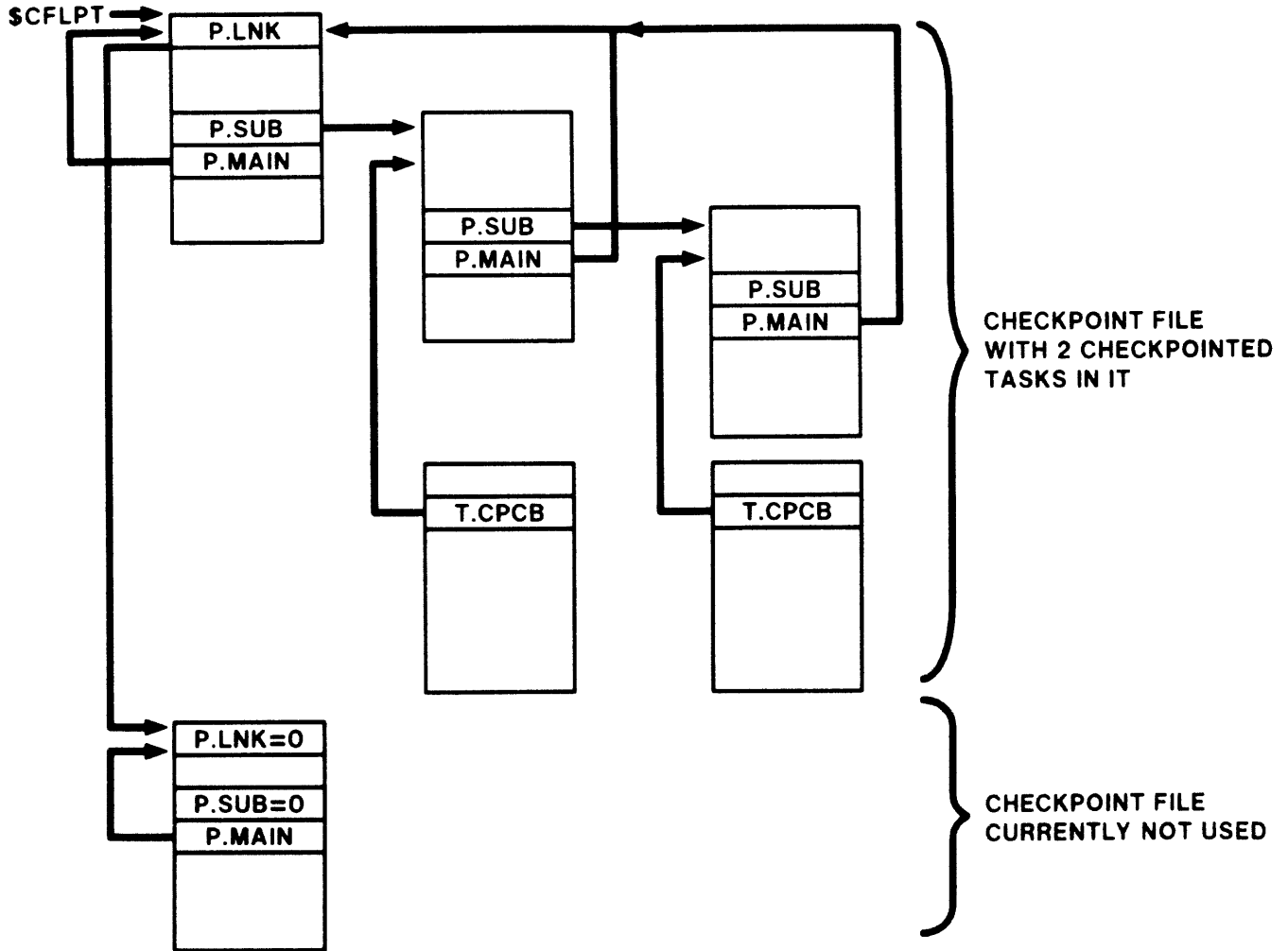


Figure 6-13 System Checkpoint Files: PCB Linkages

## Shuffling

- Consolidates holes in a system-controlled partition
- Shuffling performed by shuffler task - SHUFL
- Performed in two passes over a system-controlled partition

## Shuffler Pass One

- Partition list searched, from \$PARHD, for system-controlled partition
- If task is in wait queue of system-controlled partition, shuffle operation is initiated
- Shuffle operation:
  - Find next hole (first?)
  - Find region following hole
  - Determine if region is shufflable
  - If shufflable, checkpointable and stopped, or blocked by MCR BLOCK command, task is checkpointed
  - If shufflable, move region and contents to bottom of hole
  - When all regions have been shuffled, invoke \$NXTSK to reallocate space
- Nonshufflable regions
  - Loaded device drivers
  - Tasks connected to interrupt vectors
  - Tasks fixed for parity errors
  - Tasks with long outstanding I/O (did not complete in 1/2 second)
  - Dynamic regions
  - If nonshufflable region is found, next hole is found and process continues
- If pass one completes and the partition wait queue is not empty, pass two is invoked.

**Shuffler Pass Two**

- Attempts to gain space by finding a contiguous sequence of holes and lower priority checkpointable tasks
- Checkpoint operations initiated by calls to \$ICHKP
- When checkpointing is complete, pass one is rerun

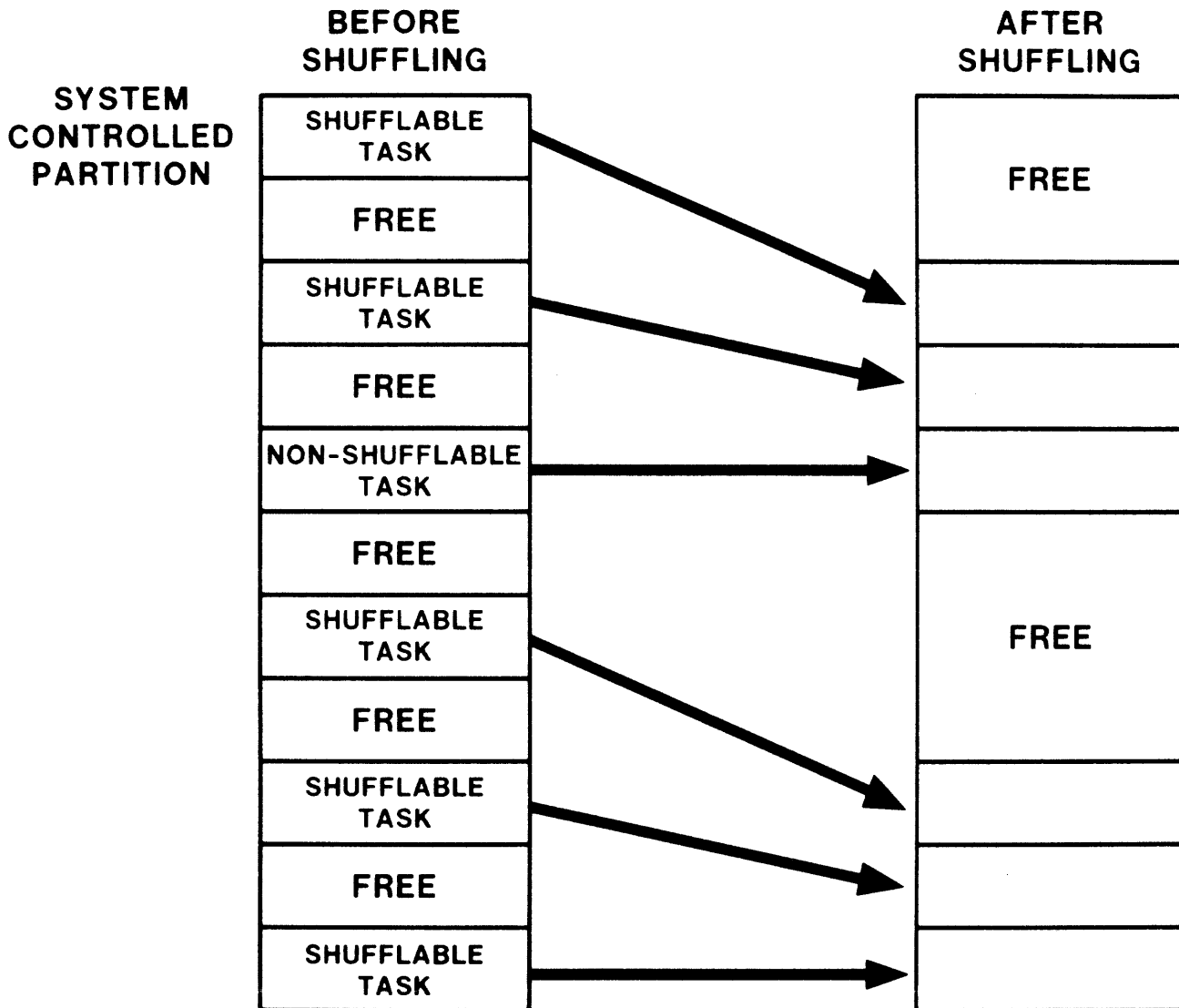


Figure 6-14 Shuffling Tasks

**USING VIRTUAL MEMORY**

**Attaching**

- Makes region available to attaching task
- Steps in attaching to a region:

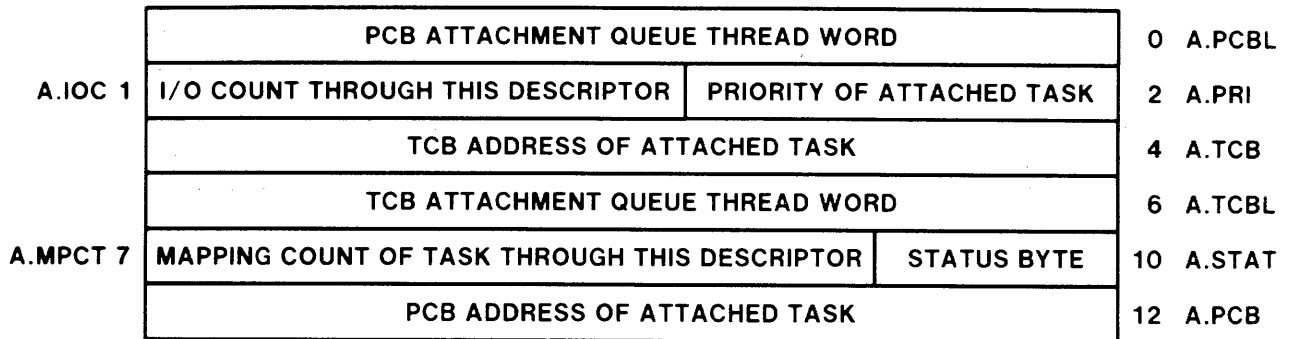
An Attachment Descriptor Block (ADB) is created

ADB is linked to the PCB for the region using A.PCB in the ADB, and P.ATT in the PCB

ADB is linked to the TCB for the task using A.TCB in the ADB, and T.ATT in the TCB

ADB is linked into the ADB list for the partition using A.PCBL in the ADB

ADB is linked into the ADB list for the task using A.TCBL in the ADB



**ATTACHMENT DESCRIPTOR BLOCK**

BIT	MASK	
3	10	AS.DEL - TASK HAS DELETE ACCESS (1=YES)
2	4	AS.EXT - TASK HAS EXTEND ACCESS (1=YES)
1	2	AS.WRT - TASK HAS WRITE ACCESS (1=YES)
0	1	AS.RED - TASK HAS READ ACCESS (1=YES)

**ATTACHMENT DESCRIPTOR STATUS BITS**

Figure 6-15 The Attachment Descriptor Block

PHYSICAL AND VIRTUAL MEMORY

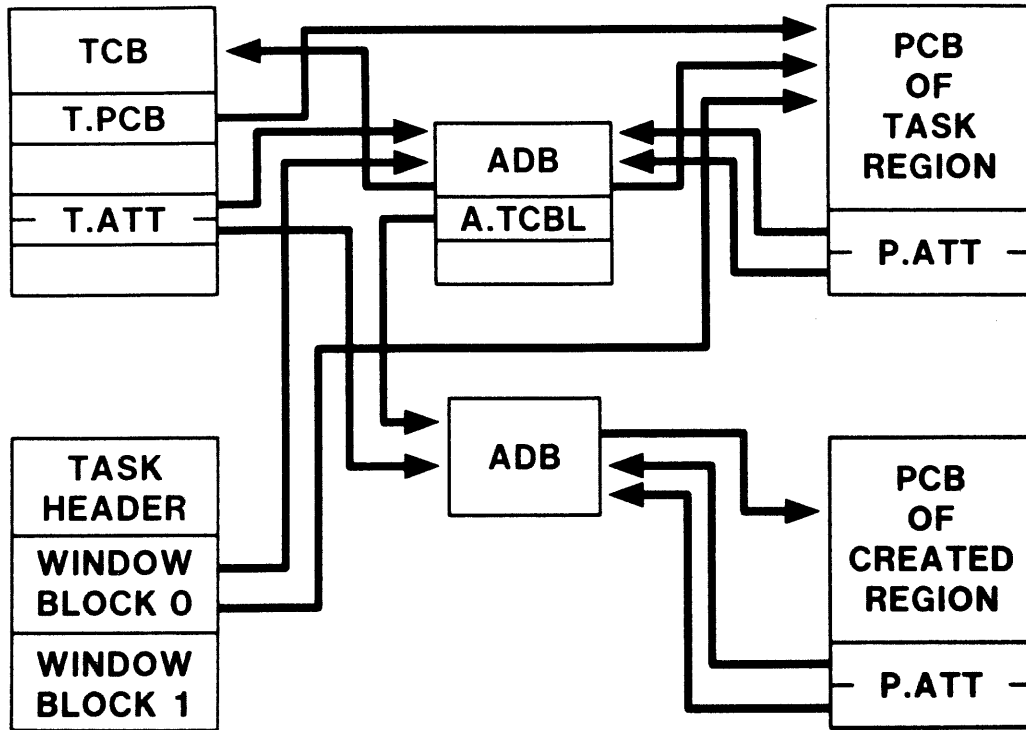


Figure 6-16 Attaching a Task to a Region



## PHYSICAL AND VIRTUAL MEMORY

### Mapping

- Task virtual address window block contains information needed to load APRs to allow access to physical region
- Task is mapped to a region if a window block contains the needed access information for the region

Pointers to the PCB and ADB for the region

High and low virtual address limits for the region

Window size and offset in the physical region in 32 word blocks

Number of APRs needed for the window and PDR information

PHYSICAL AND VIRTUAL MEMORY

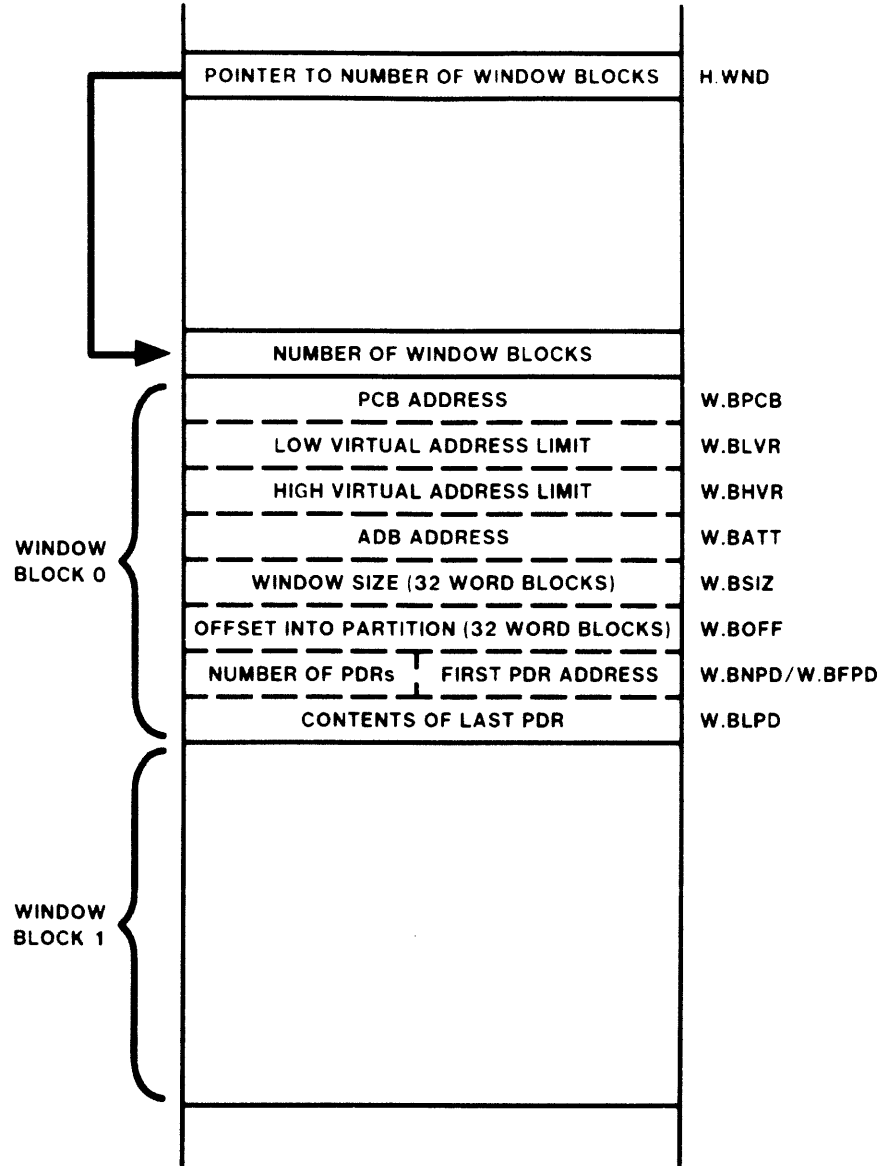


Figure 6-17 Task Virtual Address Window Blocks

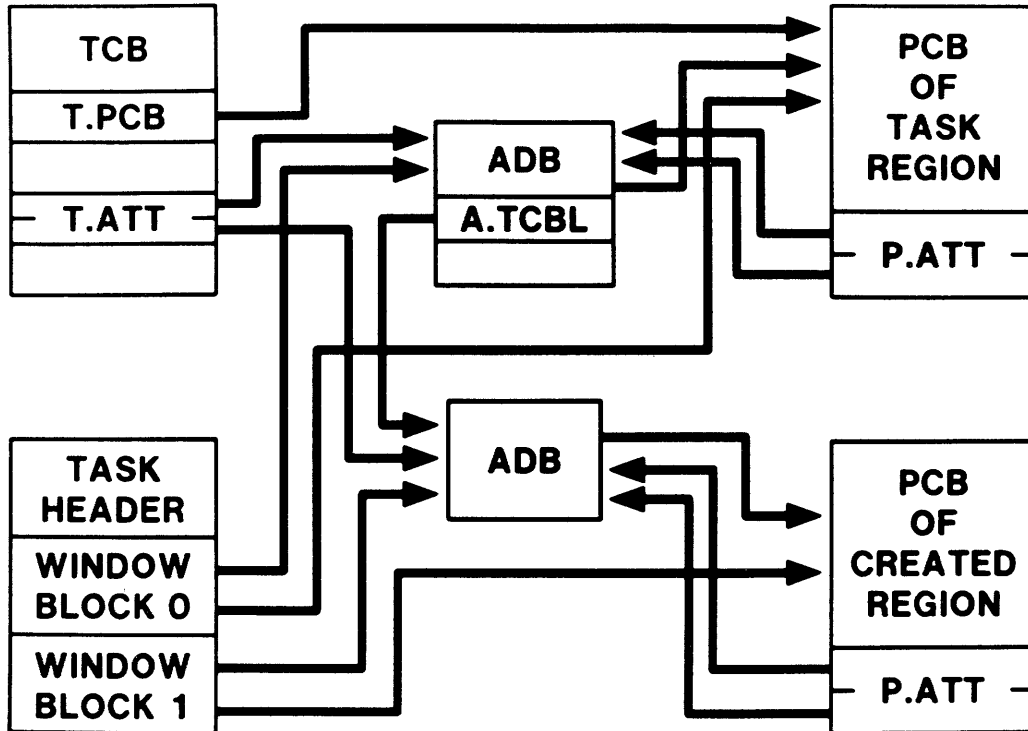


Figure 6-18 Mapping a Task Address Window to a Region



# **TASK MANAGEMENT**



## TASK MANAGEMENT

### INTRODUCTION

The basic unit of executable code under RSX-11M is the task. Most tasks are user written, but some are system-supplied, such as the task-loader, MCR, etc. The Executive must manage the task scheduling and allocate needed resources to requesting tasks. This module describes the techniques used to manage tasks.

### OBJECTIVES

1. Describe the content and functions of the task label blocks and task header.
2. Diagram the data structures used to manage task scheduling.
3. Describe the process of task termination.

### RESOURCES

1. RSX-11M System List and Data Structures
2. RSX-11M/M-PLUS Executive Reference Manual





## THE TASK IMAGE

### The Task Image File

- Created by the taskbuilder
- Includes: label block group, checkpoint area (optional), task header, and task image

### The Label Block Group

- Label block 0
  - Task and resident library data
  - Used to set up TCB and task addressing windows in header
- Label block 1
  - Table of LUN assignments for LUN 1 through LUN 128
  - Used to create Logical Unit Table(LUT) in header
- Label block 2
  - Continuation of Table of LUN assignments for LUN 129 through LUN 255 (if needed)
  - Used to create LUT in header
- Label block 3
  - Segment load list (optional)
  - Resident libraries that contain memory resident overlays

### The Checkpoint Area

- Used to provide checkpoint space when no space available in the system checkpoint files
- Size equal to size of header plus the task image

TASK MANAGEMENT

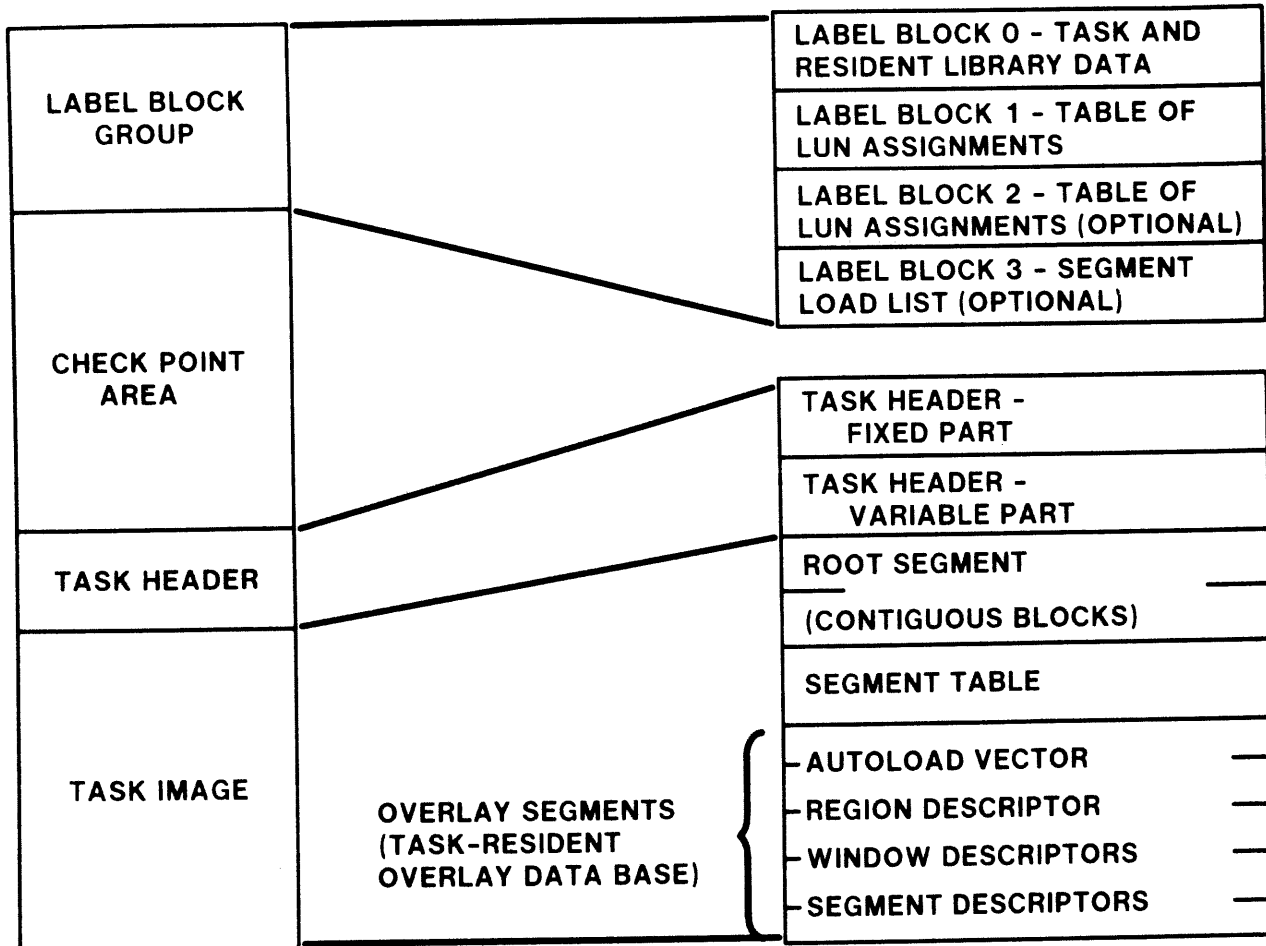


Figure 7-1 Task Image File

## TASK MANAGEMENT

### The Task Header

- Consists of two parts: fixed and variable
- Fixed part contains
  - Event Flag mask word and address
  - Initial values for PS, PC and SP
  - Low-Core context: \$DSW, and impure storage area addresses for FCS, FORTRAN, etc.
  - Pointers to specific areas within the variable part
- Variable part contains
  - Window blocks
  - Logical unit table
  - Task context
- Window Block
  - Describes task mapping
  - Associates window with region
    - Contains pointer to PCBs of regions used by task
    - Pointers loaded at task installation
  - Used to load APRs for task
  - Initialized when task is installed
- Logical Unit Table
  - Contains a two word entry for each logical unit used by the task
    - Word one: address of the UCB of the device assigned to the logical unit (UCB address loaded at task installation)
    - Word two: address of the FILES-11 window block of an open file

# TASK MANAGEMENT

## The Task Image

- Task code
- Overlay information

Autoload vectors

Region and window descriptors for memory-resident overlays

Segment descriptors

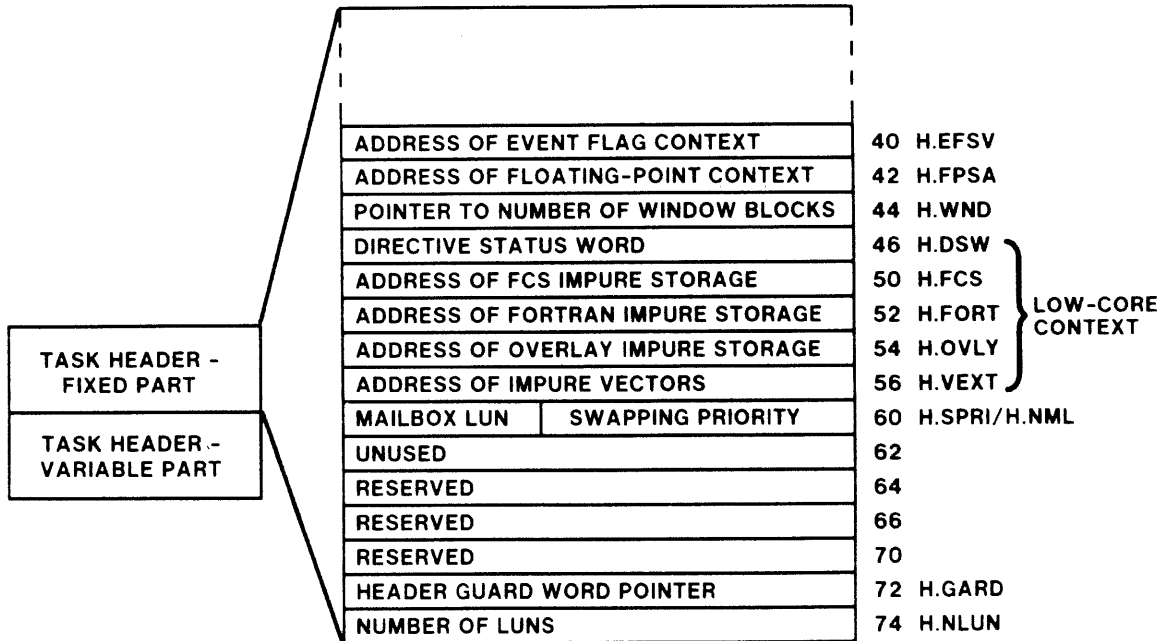


Figure 7-2 The Task Header: Fixed Part

# TASK MANAGEMENT

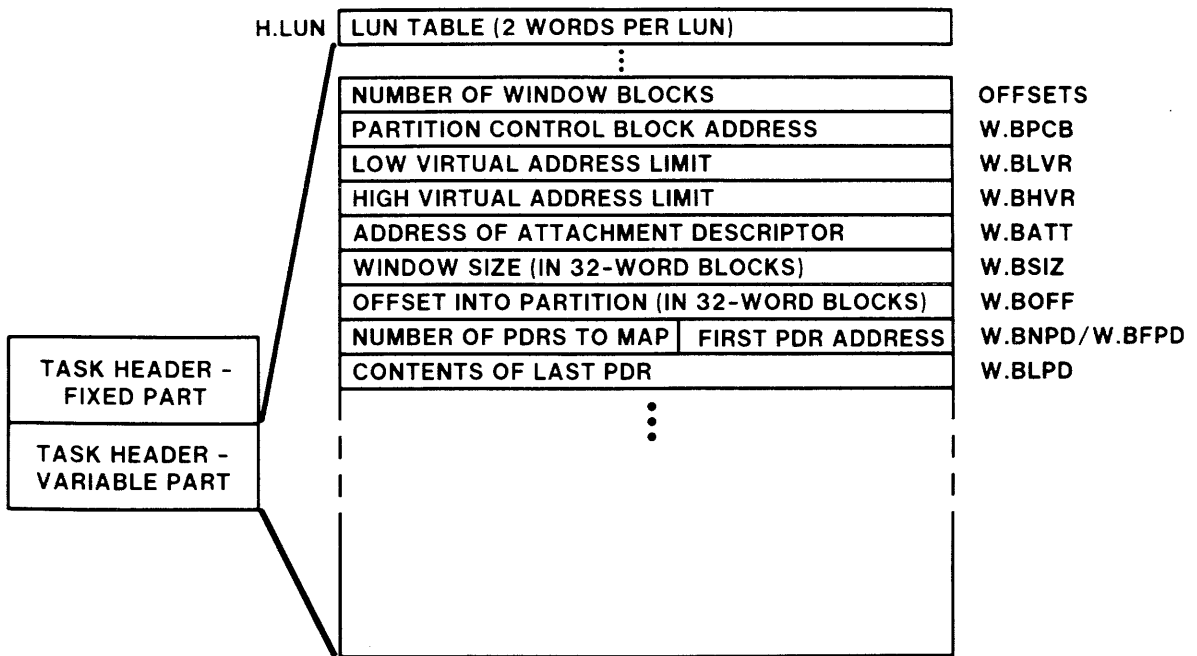


Figure 7-2 The Task Header: Beginning of Variable Part

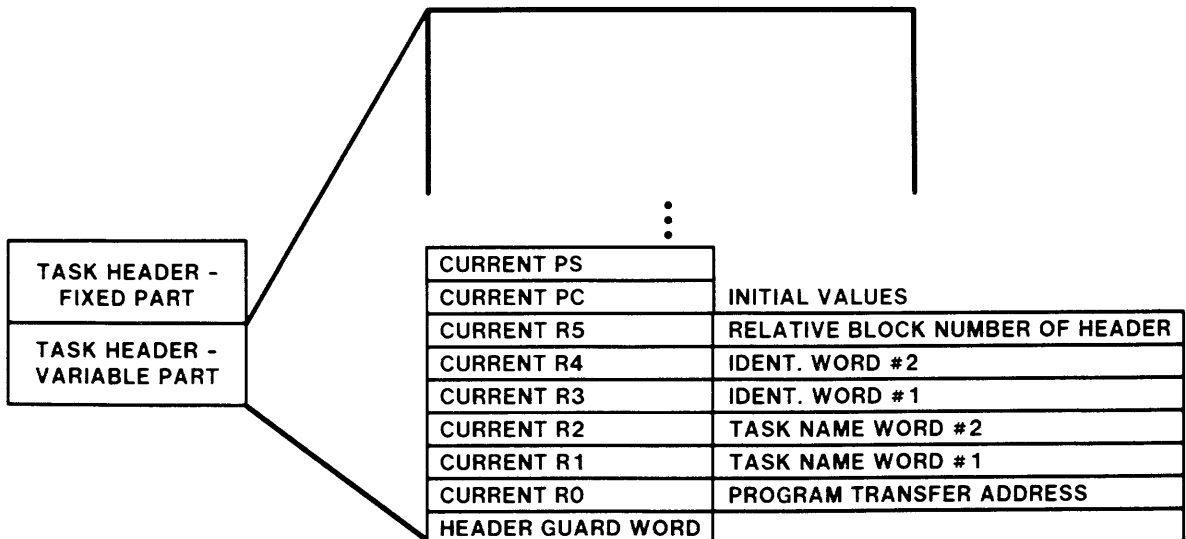


Figure 7-2 The Task Header: End of Variable Part

## TASK MANAGEMENT

### RUNNING A TASK

- Performed by MCR RUN command

Directives

RUN\$  
RQST\$  
SPWN\$

- If task not installed, use MCR command

Task is installed with name equal to terminal, TTnn

Task is executed

Task is removed on exit

- Two types of requests:

Immediate request - is executed as soon as possible

Time-dependent request

Executed at a specified time

Rescheduled to run periodically

- Steps in running a task

Task is installed

Task is activated

Memory is allocated to task

Task is loaded

Task is scheduled

Task is terminated

## TASK MANAGEMENT

### Installing

- Task is installed by MCR command
  - Permanent installation by INS command
  - Temporary installation by RUN command
- TCB is created and initialized
- Location T.PCB in TCB points to:
  - The PCB of the partition or subpartition for which it was built (if partition is user-controlled)
  - The PCB of the main partition (if partition is system-controlled)
- Locations T.LDV and T.LBN point to the load device and logical block number of the task image file
- Access rights to resident commons and libraries are checked
- Task TCB is inserted into the STD by routine \$QINSP in module QUEUE
- Window blocks in header are initialized from the label blocks
- LUT is initialized from the label blocks and UCB addresses are loaded

## TASK MANAGEMENT

### Activating

- Task placed in the Active Task List (ATL)
- If task not installed and not privileged, it is temporarily installed

### Allocating Memory

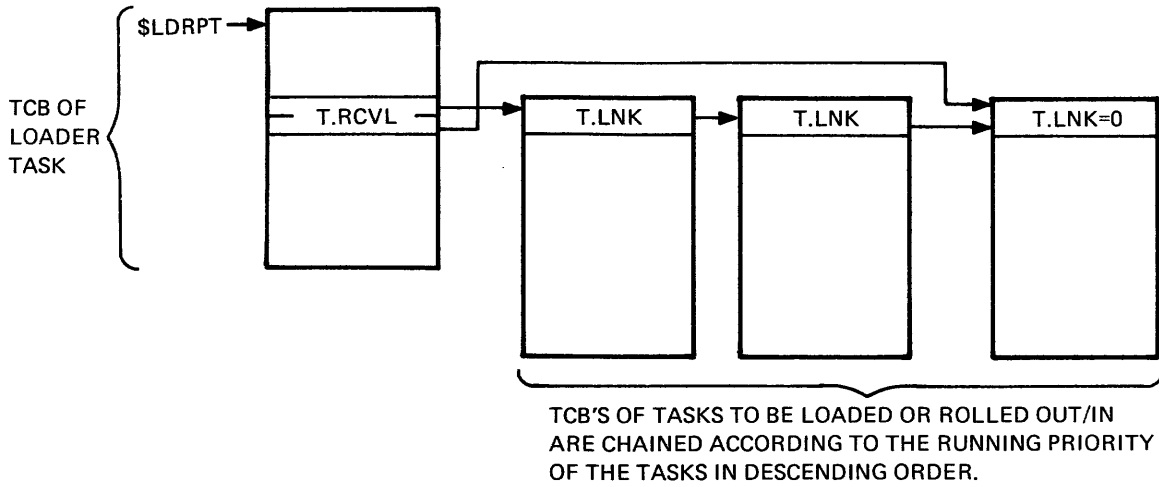
- Partition wait-queue used to schedule memory use
  - Ordered by task priority
  - Linked using T.LNK, the utility link word
  - Starts at P.WAIT in PCB
- TCB placed in partition wait-queue
  - When task is requested
  - When task is checkpointed

### Loading

- Task placed in loader queue
  - Utility link word, T.LNK, links TCBS in queue
  - Location P.WAIT in PCB is queue listhead
- In mapped system, task header copied into DSR
  - Executive updates copy in DSR
  - \$DSW only data in task copy that is updated



# TASK MANAGEMENT



TS.CKP	TS.OUT	
0	0	INVALID
0	1	INITIAL LOAD
1	0	CHECKPOINT WRITE
1	1	CHECKPOINT READ

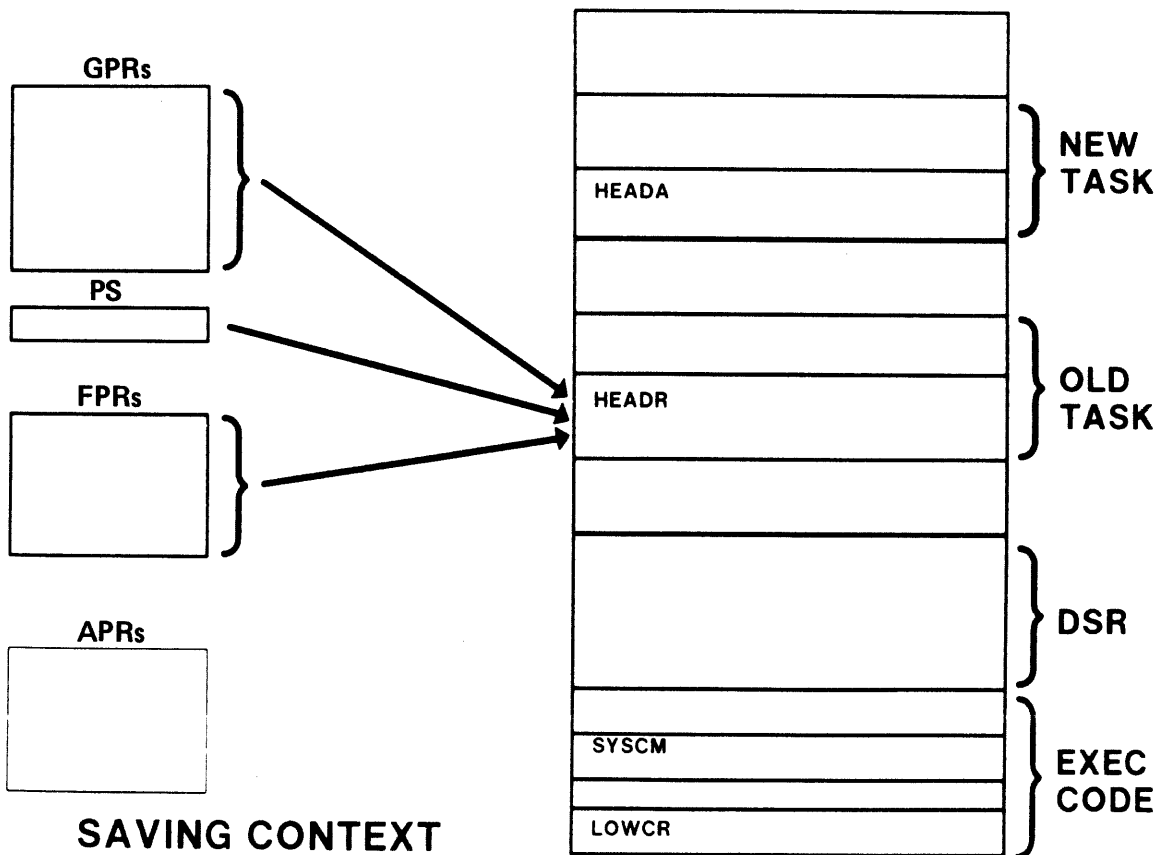
LOADER QUEUE

TK-1813

Figure 7-3 The Loader Queue

### Context Switching

- Current task's context stored in task header
- Task context includes:
  - General registers (R0 - R5)
  - Processor Status Word
  - Stack pointer (R6)
  - Program counter (R7)
  - Floating-point registers
- Mapping context for current task is not saved
- New task's context is loaded from its header
- Mapping context for new task created using window blocks and PCBs



**SAVING CONTEXT**

Figure 7-4 Context Switching: Saving Context

# TASK MANAGEMENT

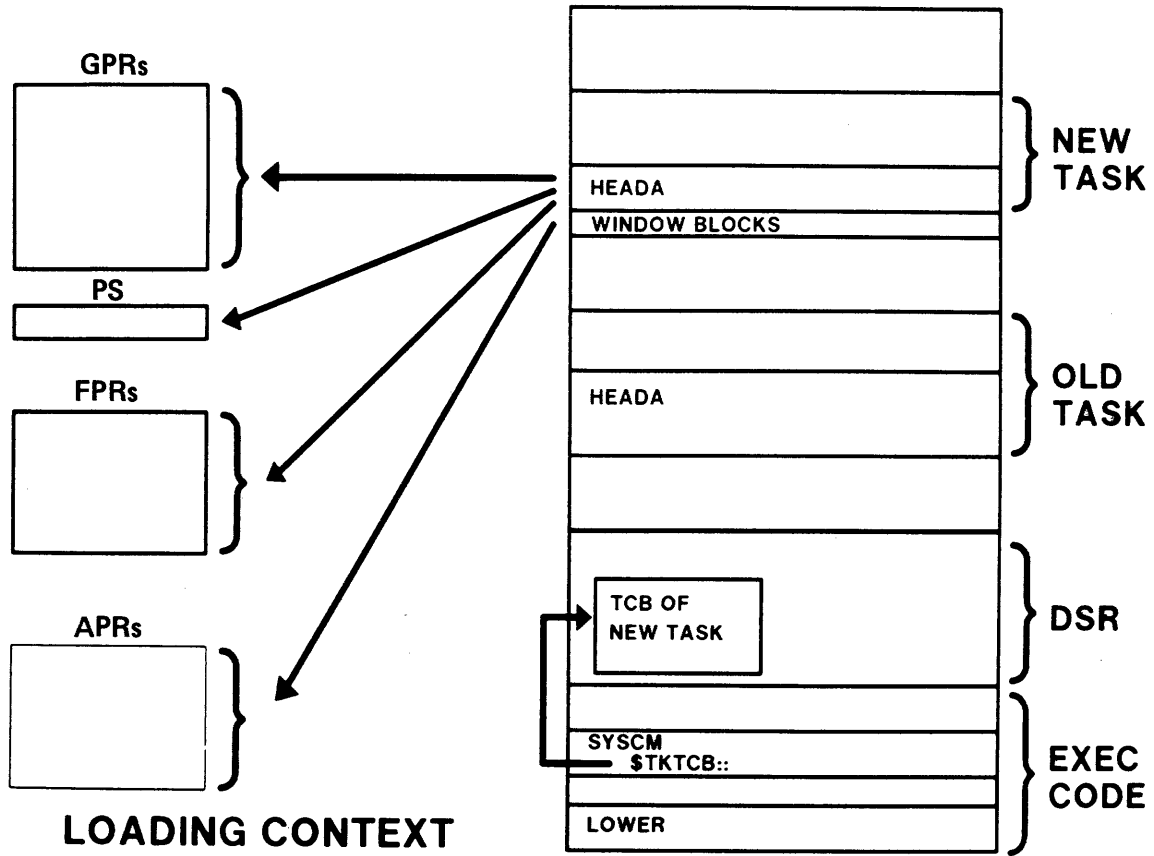


Figure 7-4 Context Switching: Loading Context

TASK MANAGEMENT

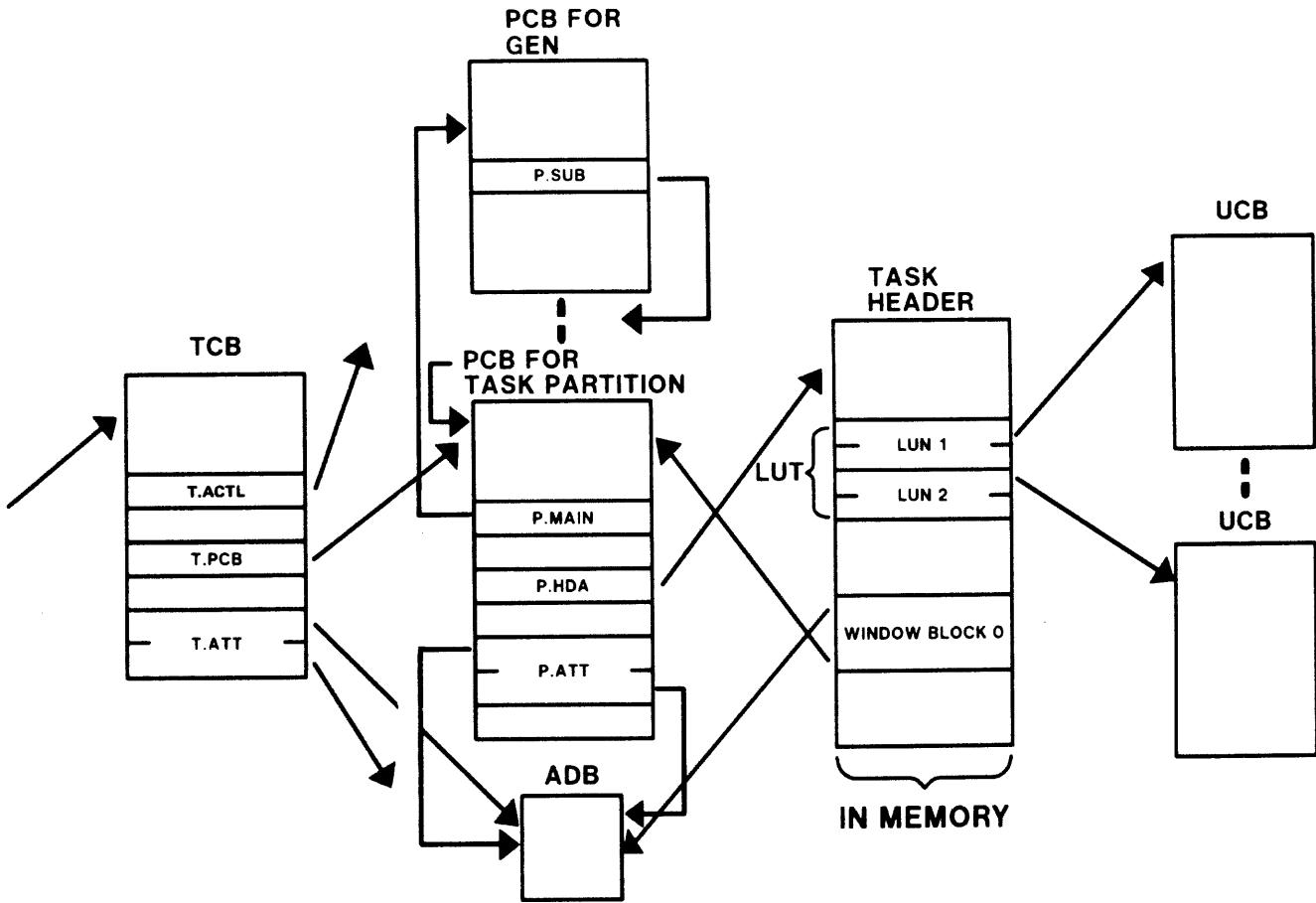


Figure 7-5 The Data Structures for an Active Task

## TASK MANAGEMENT

### SCHEDULING A TASK

#### Priority

- Scheduling request sets value in \$RQSCH
- Value can be:
  - The beginning of the ATL (e.g., after a significant event)
  - Address of particular TCB (e.g., after a conditional scheduling request)
- Scheduling algorithm scans the ATL beginning at the TCB whose address is in \$RQSCH
- System chooses:
  - First resident unblocked task
  - First task with a pending AST

#### Round Robin

- Tasks of the same priority share the CPU
- Is a SYSGEN option
- Parameters set at SYSGEN
  - Round robin scheduling time interval
  - Priority range for round robin
- For each priority in priority range
  - Sublist of tasks of that priority is scanned
  - TCBs of blocked, suspended or waiting tasks are skipped
  - TCB of first eligible task is placed last in list of tasks with same priority

TASK MANAGEMENT

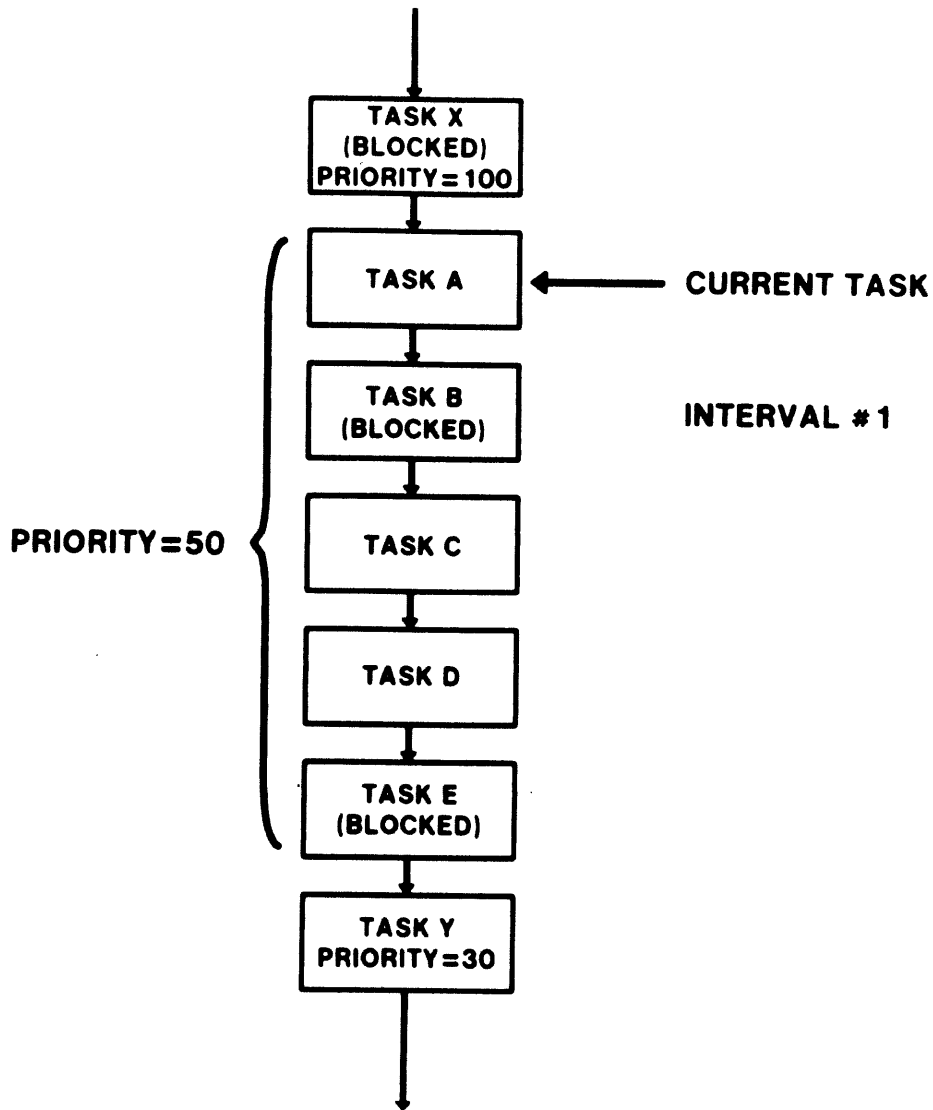


Figure 7-6 Round Robin Scheduling: Interval #1

# TASK MANAGEMENT

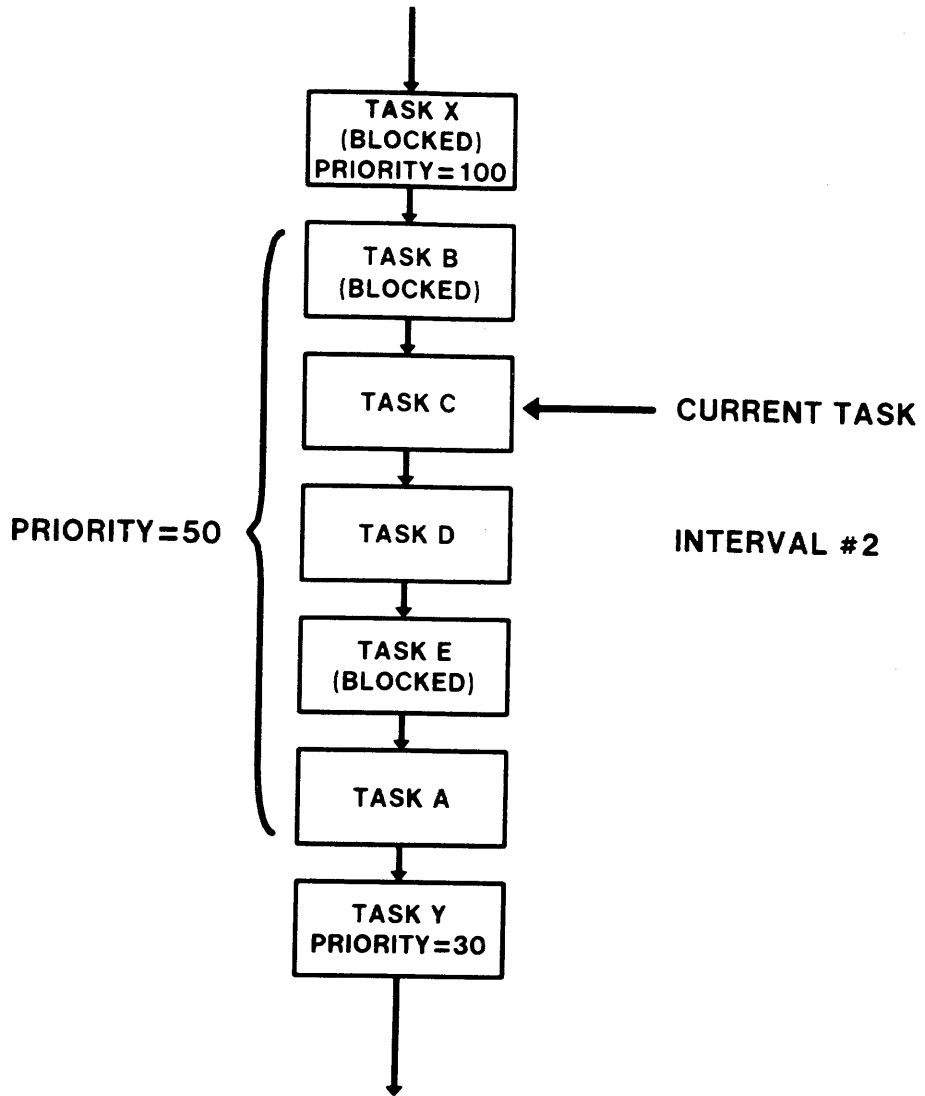


Figure 7-6 Round Robin Scheduling: Interval #2

## Disk Swapping

- Allows tasks of similar priority to share memory
- Is a SYSGEN option
- Parameters set at SYSGEN

Swapping priority

Time interval for swapping

- Steps in disk swapping

When task loaded, swapping priority is set at H.SPRI in the task header

At the end of each swapping interval, H.SPRI is decremented

H.SPRI is not decremented beyond the negative of the swapping priority

For checkpointing, H.SPRI is added to the running priority

When task is checkpointed, H.SPRI is set back to the swapping priority



## TASK MANAGEMENT

### **Clock Scheduling**

- Provides facility for tasks to run
  - At specific times
  - After specific time intervals
- When clock interrupt occurs, the clock queue is scanned
- Types of time dependent requests
  - Mark time request
  - Task request with periodic rescheduling
  - Single shot task request
  - Single shot internal subroutine

# TASK MANAGEMENT

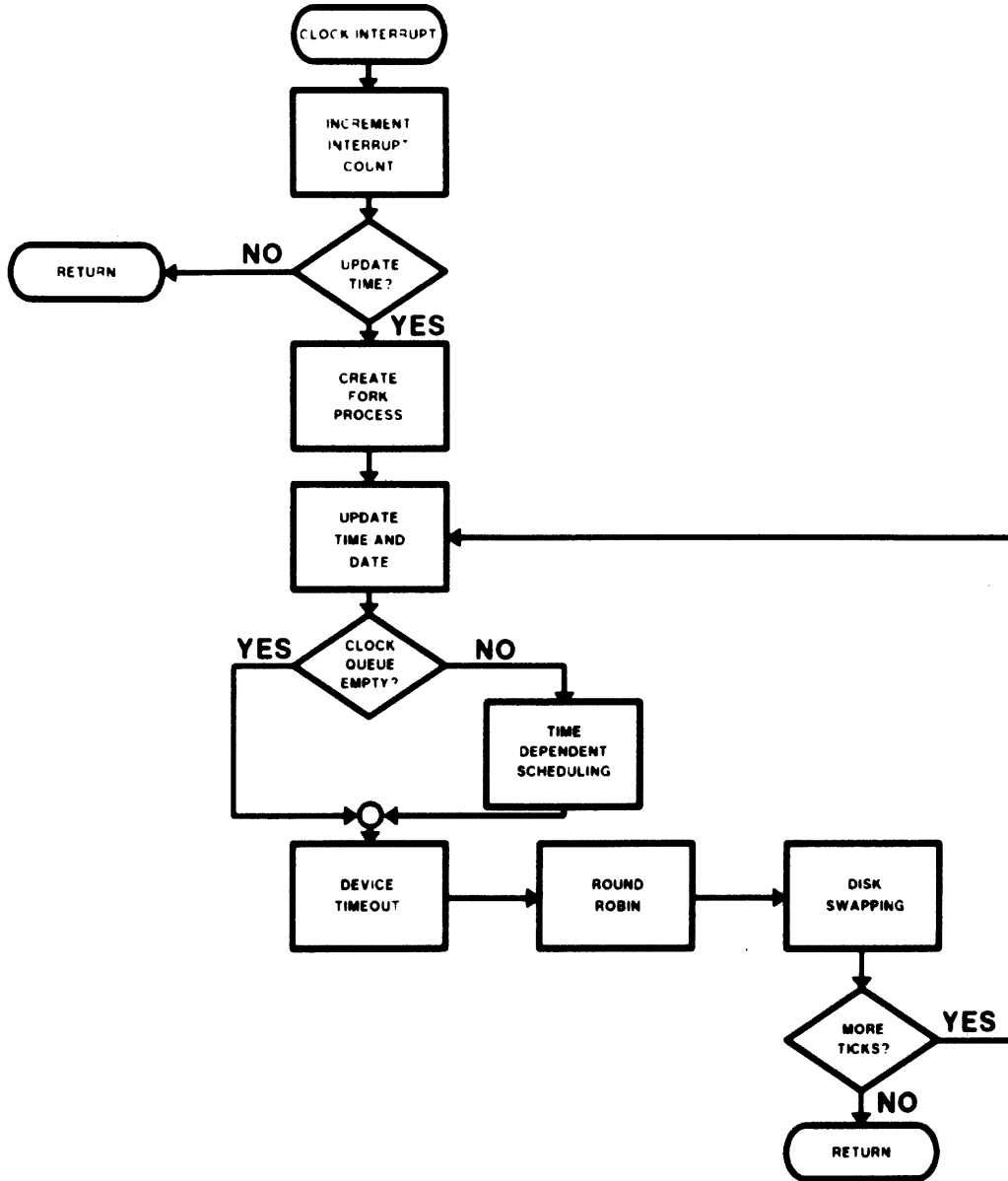


Figure 7-7 Time-Dependent Scheduling

## TASK MANAGEMENT

### AST Processing

- AST is used to notify a task when an asynchronous event has occurred
- Three phases in processing an AST

#### Specifying the AST

Allocate an AST control block

Fill in the type of AST at A.CBL

Link the block to the TCB at T.SAST

#### Declaring the AST

Queue the AST control block to the AST queue at T.ASTL

#### Scheduling the AST

Conditional schedule request is made

After context switch to task, RESCH in SYSXT attempts to dequeue an AST

Stopped task is activated to process the AST, then stopped again

- When an AST is scheduled

Necessary data is pushed onto the task stack

AST executes before return to task code

TASK MANAGEMENT

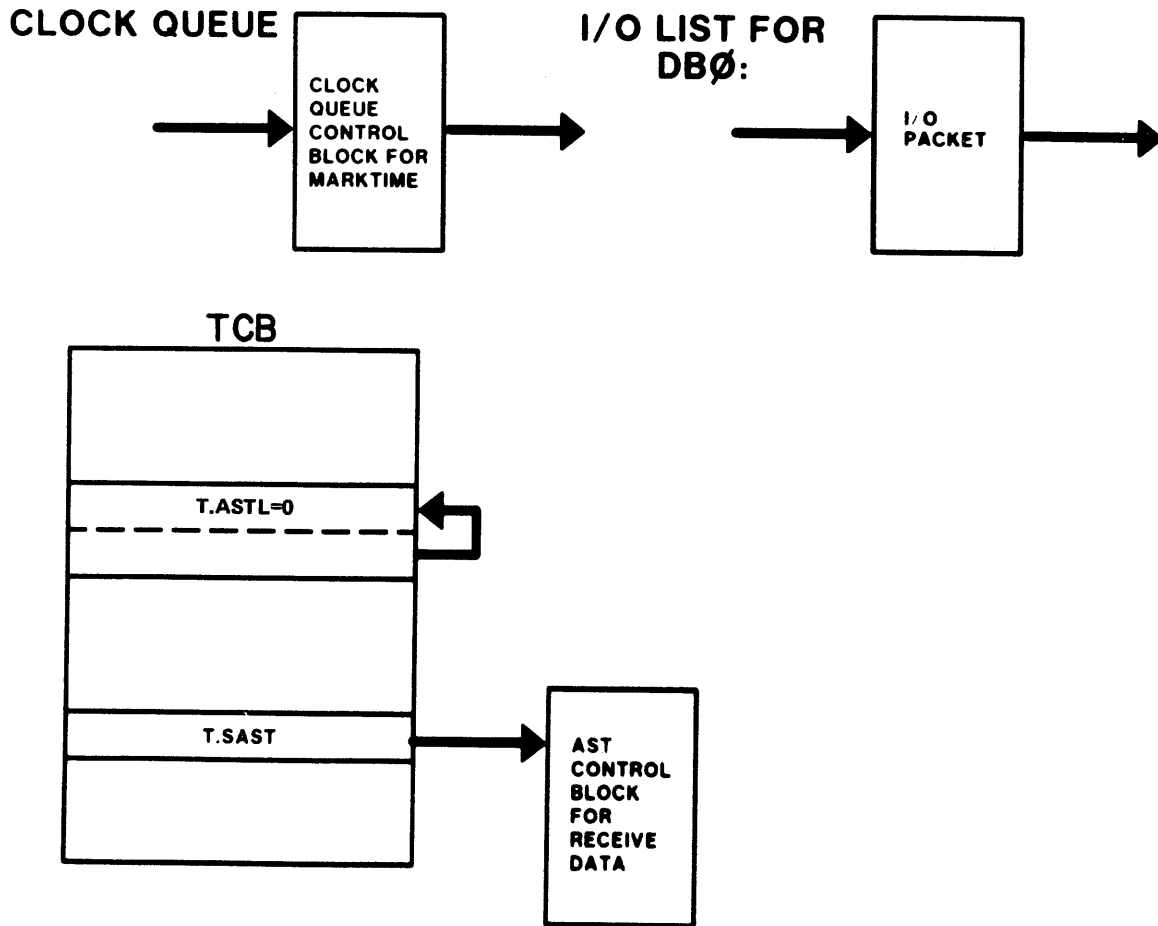


Figure 7-8 AST Processing: Sources of ASTs

# TASK MANAGEMENT

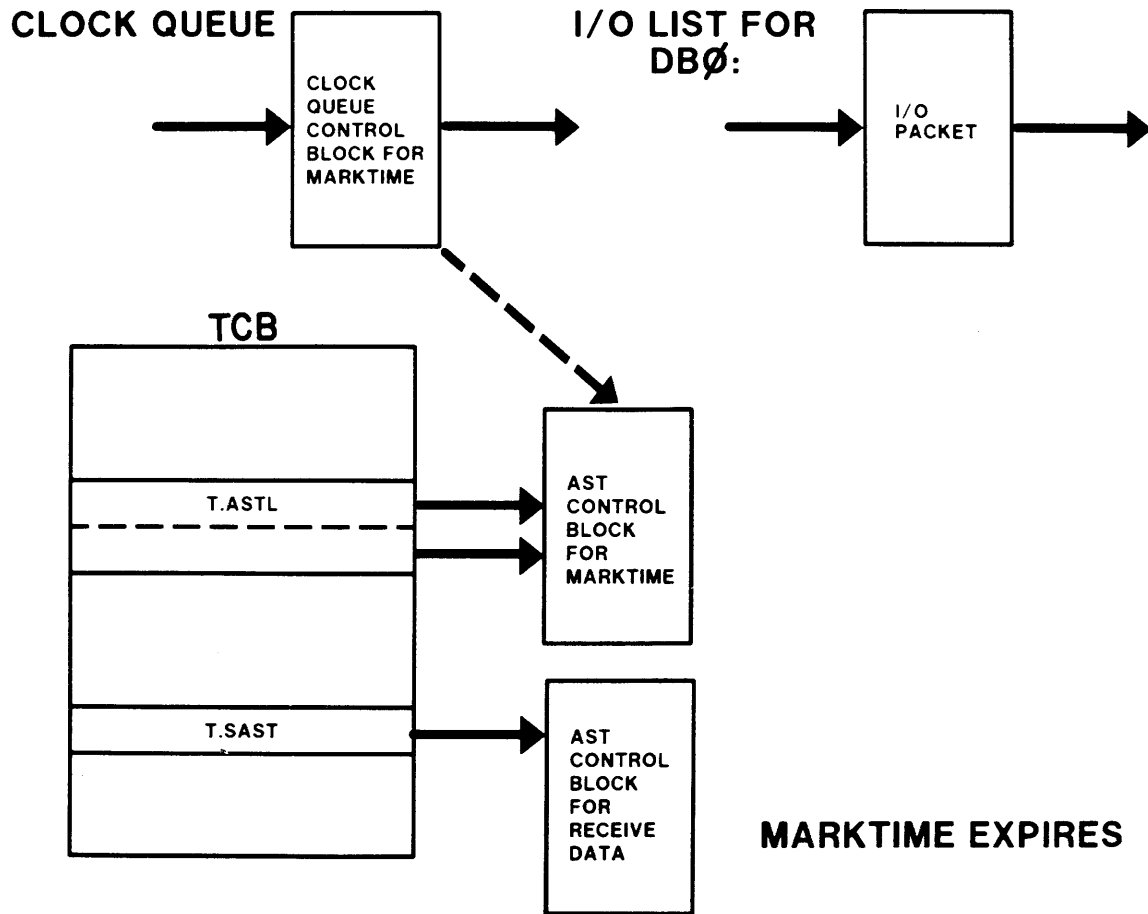


Figure 7-8 AST Processing: Marktime Expiration

TASK MANAGEMENT

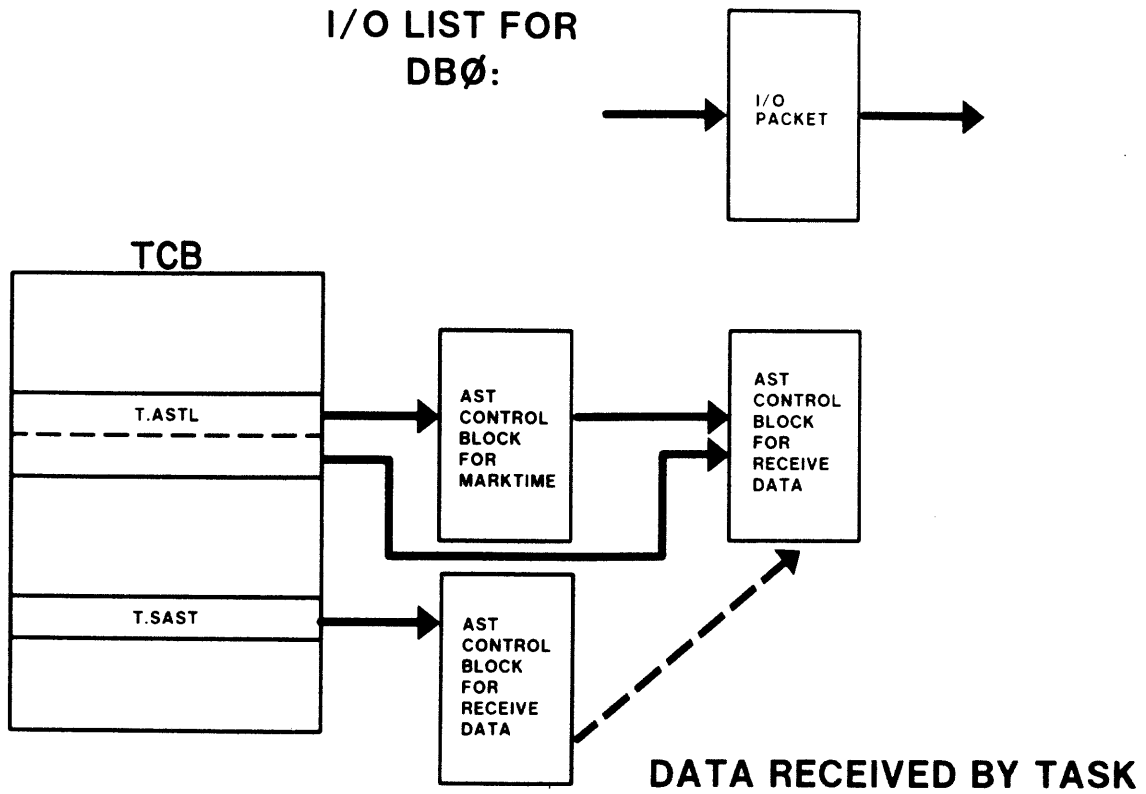


Figure 7-8 AST Processing: Completion of a Receive Data

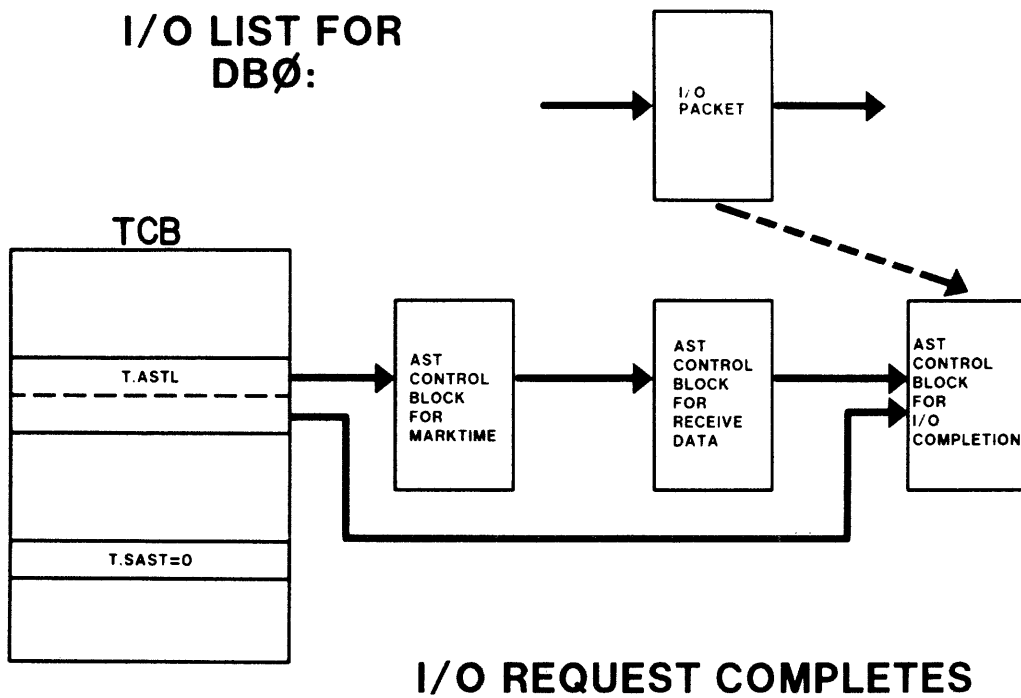


Figure 7-8 AST Processing: Completion of an I/O Operation

## TASK MANAGEMENT

### TASK TERMINATION

- Normal termination

  - Task issues an exit directive

- Abnormal termination

  - Another task issues an abort directive

  - Task is aborted by an MCR abort command

  - Task is aborted because of an SST

- Actions performed at task termination

  - Halt task

  - Cleanup system database

  - Cancel mark time requests

  - Break links to offspring tasks

  - Disconnect interrupt vectors, if any

  - If T3.REM = 1, deallocate TCB

  - Deallocate header in pool if mapped system

  - If abnormal exit, run TKTN

  - Declare a significant event

- I/O Rundown

  - Kill all I/O on each assigned LUN

  - Detach all attached devices

  - Close all files opened by task

## Synchronous System Traps

- Trap vector for each type
- System response to SST

Kernel mode: Crash system

User mode: Abort task if no user SST vector

Execute user-supplied routine if user SST vector

Table 7-1 Synchronous System Traps

Trap Vector	Trap Routine	Service Routine	Cause
4	\$TRP04	\$TRP04	Odd or nonexistent memory address error
250	\$SGFLT	\$SGFLT	Memory protect violation
14	\$TRACE	\$TRACE	T-bit or BPT instruction
20	\$IOTRP	\$IOTRP	IOT instruction
10	\$ILINS	\$ILINS	Reserved instruction
30	\$EMTRP	\$EMSST	Non-RSX EMT instruction
34	\$TRTRP	\$TRTRP	TRAP instruction
244	\$FPPR8 (or \$FPPR7)	\$FPPR8	Synchronous floating-point exception



# TASK MANAGEMENT

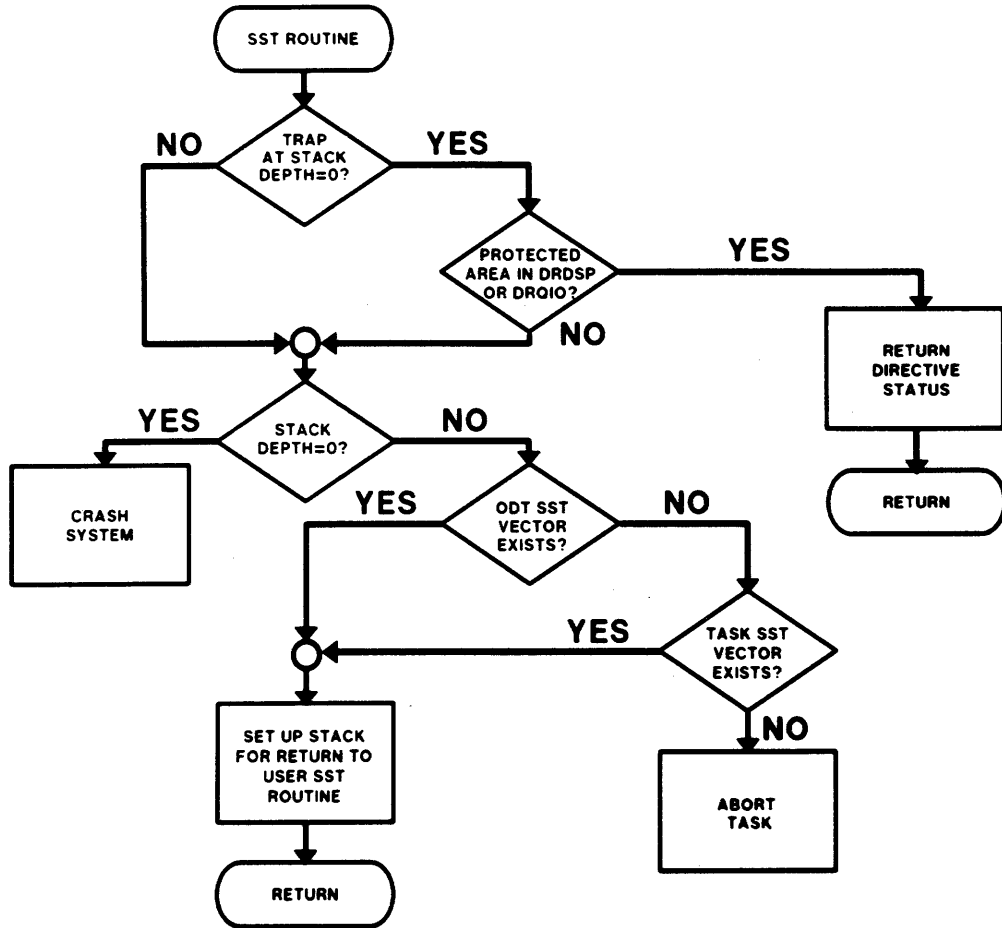


Figure 7-9 SST Processing



# SYSTEM SYNCHRONIZATION



## SYSTEM SYNCHRONIZATION

### INTRODUCTION

A large number of activities are in progress at any given time while an RSX-11M system is in use. System synchronization is the term given to the system processing which keeps these activities from interfering with each other. One important activity which must be controlled is access to the system data base.

### OBJECTIVES

1. Describe how a software trap is processed by the system.
2. Describe how a hardware interrupt is processed by the system.
3. Describe FORK processing.
4. Describe how a privileged task gets access to the system data base and code.

### RESOURCE

1. RSX-11M System Lists and Data Structures



## SYSTEM SYNCHRONIZATION

### OVERVIEW

- Executive is driven by interrupts and traps

Idle until interrupt or trap occurs

- System operation

Executive booted into memory by ROM

ROM starts Executive by initializing PS and PC

Executive initializes the environment

Enables memory management unit

Turns on clock

Drivers called at powerfail entry points

Executive drops into idle loop and waits for interrupts

Command typed in at a terminal

Interrupt occurs

Command passed to MCR or DCL

MCR or DCL runs a task

Task may issue traps

Clock may interrupt functions

## System Synchronization Functions

- Provides serial access to system database
  - Process accessing system database 'owns' the database until finished
  - 'Race' conditions are avoided
- Provides orderly method of allocating CPU use between user and system

## Software States

- User State
  - User code executing
  - Processor in USER mode
  - Processor fully interruptable - Hardware priority is 0
- System State
  - Only state in which the shared system database should be accessed
  - Processor in KERNEL mode
  - Processor fully interruptable - Hardware priority is 0
- Interrupt Service State
  - Used to perform critical operations after an interrupt
  - Processor in KERNEL mode
  - Processor not fully interruptable - Hardware priority between 4 and 7



## SYSTEM SYNCHRONIZATION

### Software Processes

- Process - A stream of code in KERNEL mode performing a complete logical job

Can be in the Executive or in a privileged task

- There are three types of processes contained in the Executive

#### Trap process

Services a software trap

Performed in system state

#### Interrupt Process

Services a hardware interrupt

Performed in interrupt service state

#### FORK Process

Allows process or task to get access to system database

Performed in system state

## The Stack Depth Indicator

- One word at location \$STKDP in the Executive module SYSCM
- Indicates software state and number of interrupts which have occurred in KERNEL mode

Value of +1 indicates processing in user state

Value of 0 indicates processing in system or interrupt service state

Trap or interrupt occurred from user state

Negative value indicates processing in interrupt service state

Trap occurred from system state

- Each time trap or interrupt occur, \$STKDP is decreased by 1
- Each time a trap or interrupt process completes, \$STKDP is increased by 1

## Traps and Interrupts

- CPU hardware performs following steps

New program counter and processor status are obtained from the vector

Current program counter and processor status are pushed onto current stack

Current stack is KERNEL stack if mapped system  
Current stack is USER stack if unmapped system

- New program counter contains address of trap service routine
- New processor status causes  
Processor to change to KERNEL mode  
Processor priority to change to level 7

SYSTEM SYNCHRONIZATION

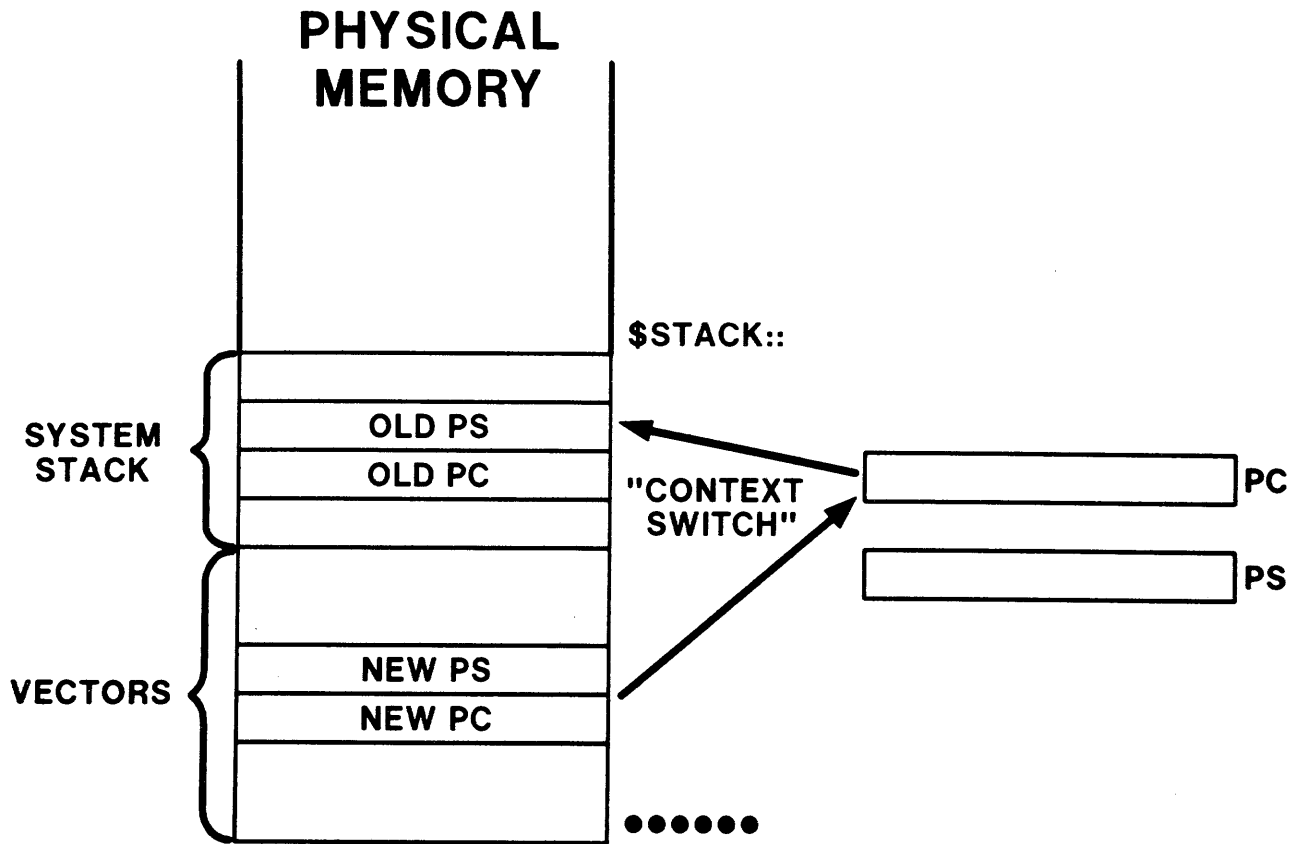


Figure 8-1 Handling Traps and Interrupts by the Hardware

# SYSTEM SYNCHRONIZATION

## TRAP PROCESSING

1. Trap caused by execution of a 'trap' instruction or synchronous system trap detected by the Executive
2. Each type of trap corresponds to a unique two word vector in low memory
3. Most common trap is 'EMT 377', the result of a directive call
4. EMT instructions

Cause a transfer to location \$EMTRP in module DRSUB

Processing occurs in module \$DRDSP, the Directive Dispatcher

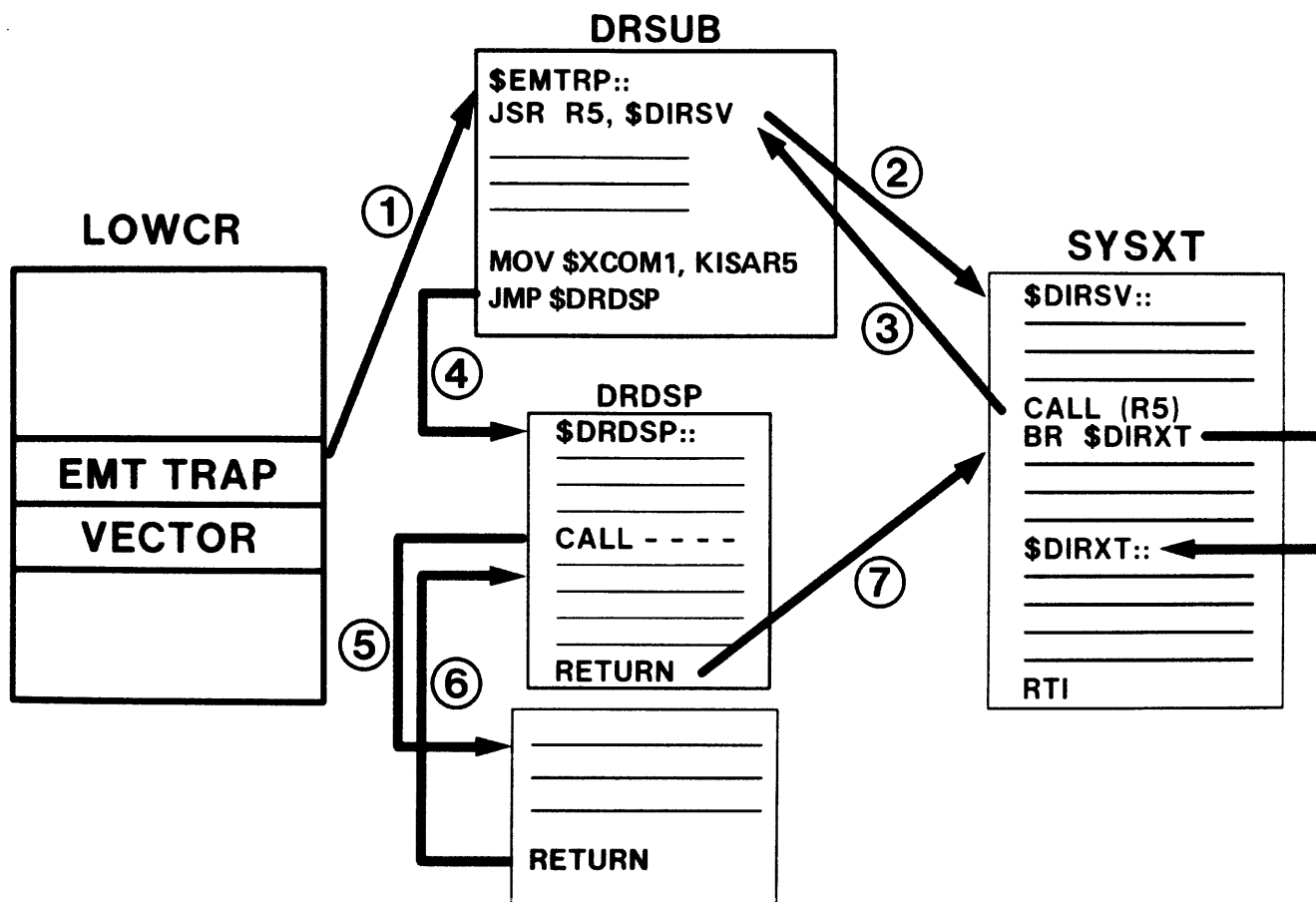


Figure 8-2 EMT Instruction Execution

## SYSTEM SYNCHRONIZATION

### The Directive Save Routine

- Code begins at label \$DIRSV in module SYSXT
- Called by trap processing routine upon entry
- Processing in directive save routine
  - Stack depth indicator is decremented to 0
  - R5 is saved on current stack by JSR instruction
  - R4 is saved on current stack
  - On unmapped system, loads R6 with pointer to system stack
  - R3, R2, R1 and R0 are saved on system stack
  - Performs coroutine call back to DRSUB

### The Directive Exit Routine

- Code begins at label \$DIRXT in module SYSXT
- Raises processor priority to 7 to lock out interrupts
- Checks for waiting FORK process
  - If so: maps driver using KERNEL APR 5  
transfers control to next FORK process
- Increments \$STKDP (Should now be +1)
- Restores general purpose registers
- Executes RTI instruction to return to USER mode

SYSTEM SYNCHRONIZATION

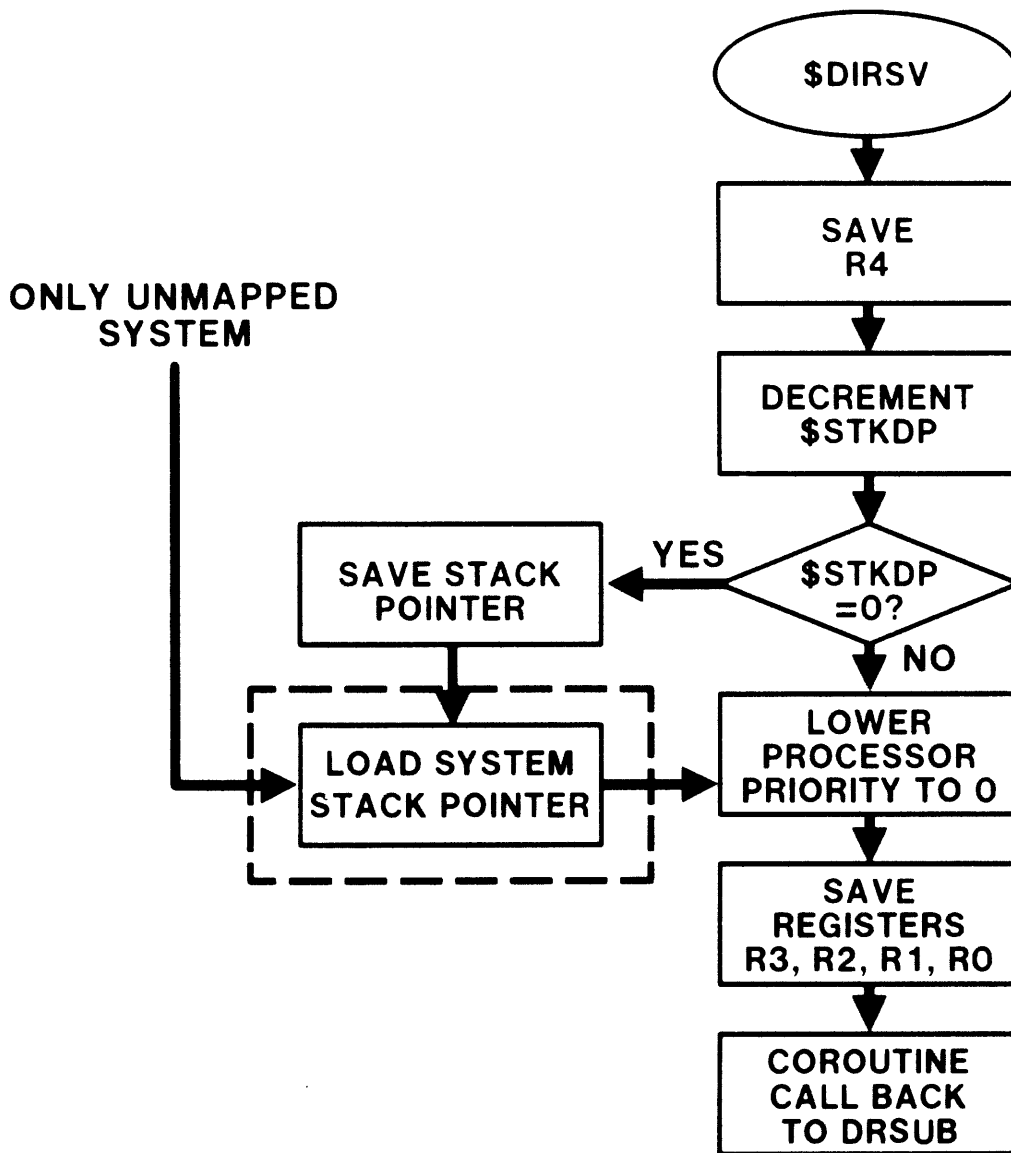


Figure 8-3 The Directive Save Routine

SYSTEM SYNCHRONIZATION

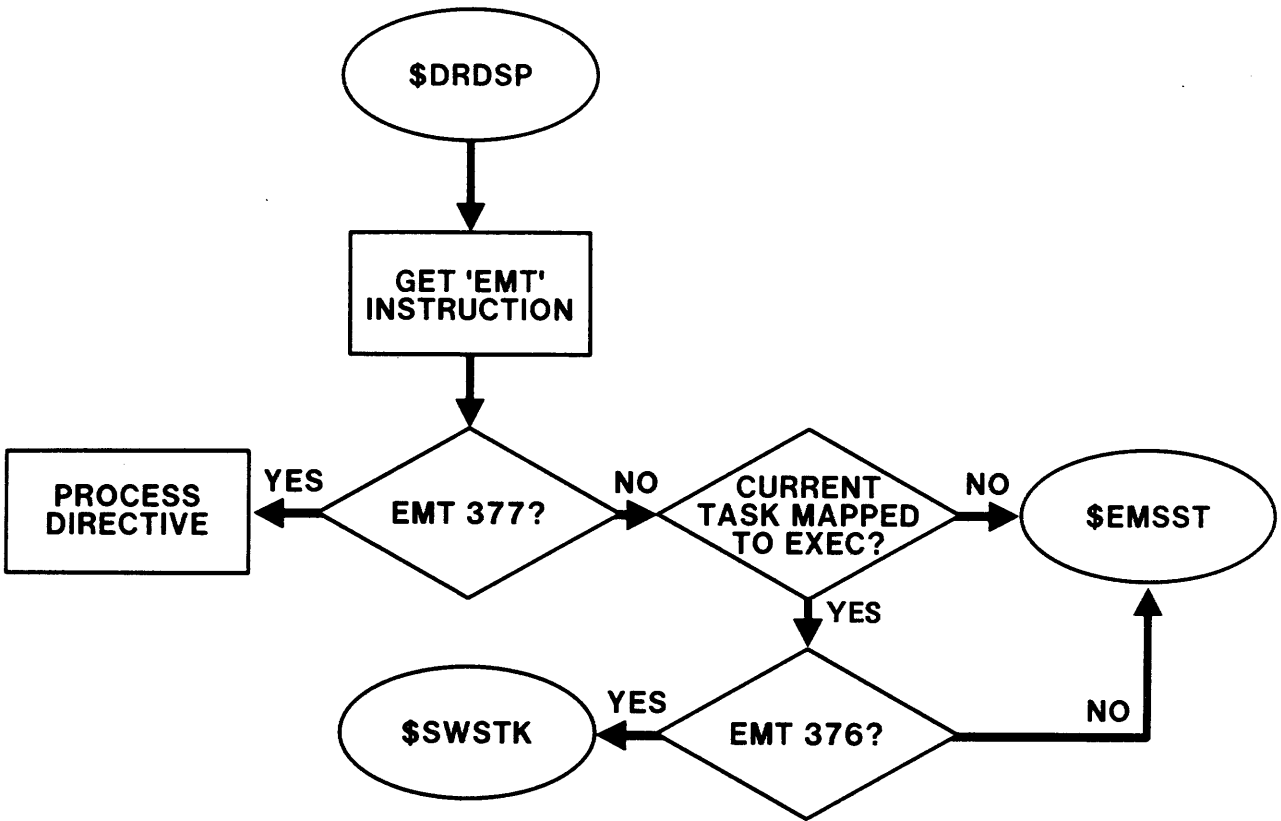


Figure 8-4 Common Processing in the Directive Dispatcher

# SYSTEM SYNCHRONIZATION

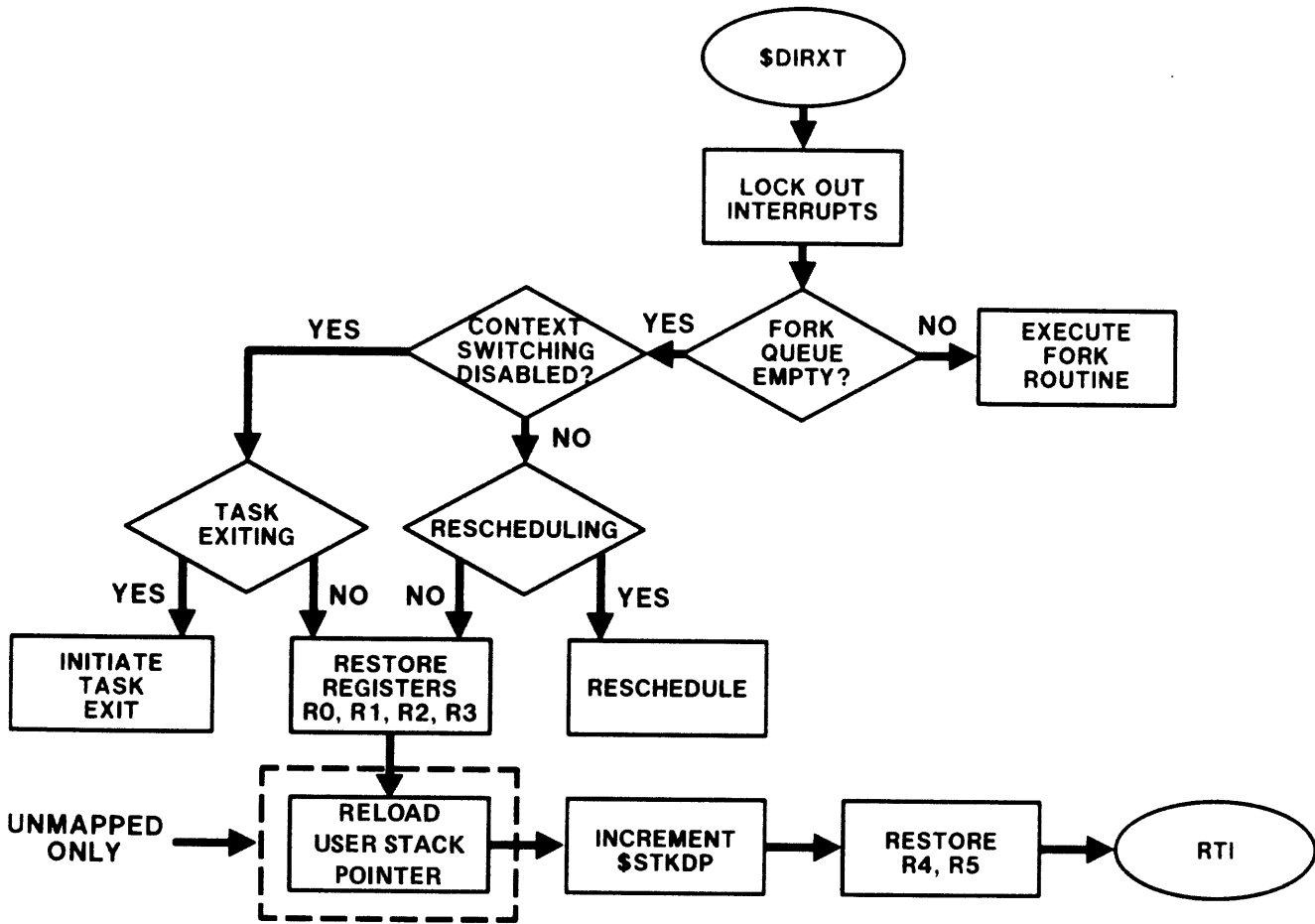


Figure 8-5 The Directive Exit Routine



## SYSTEM SYNCHRONIZATION

### INTERRUPT PROCESSING

- Interrupt caused by hardware event
- Device driver allows interrupt by setting 'interrupt-enable' bit device register
- Each device controller has its own 2-word interrupt vector in low memory

### The Interrupt Save Routine

- Code begins at label \$INTSV in module SYSXT
- Entry is with processor priority at level 7 to lock out other interrupts
- Called by interrupt service routine upon entry
- Processing in interrupt save routine

Stack depth indicator is decremented by one

R5 is saved on the current stack by JSR R5,\$INTSV

R4 is saved on the current stack

On unmapped system, SP is loaded with the address of the system stack if entry is from user mode

Processor priority is lowered to priority of the interrupting device

Performs coroutine call back to the interrupt service routine

- Several versions of this routine are available in module SYSXT
  - \$INTSV - Used by devices without error logging
  - \$INTSE - Used by devices with error logging
  - \$INTSC - Used by connect-to-interrupt routines

SYSTEM SYNCHRONIZATION

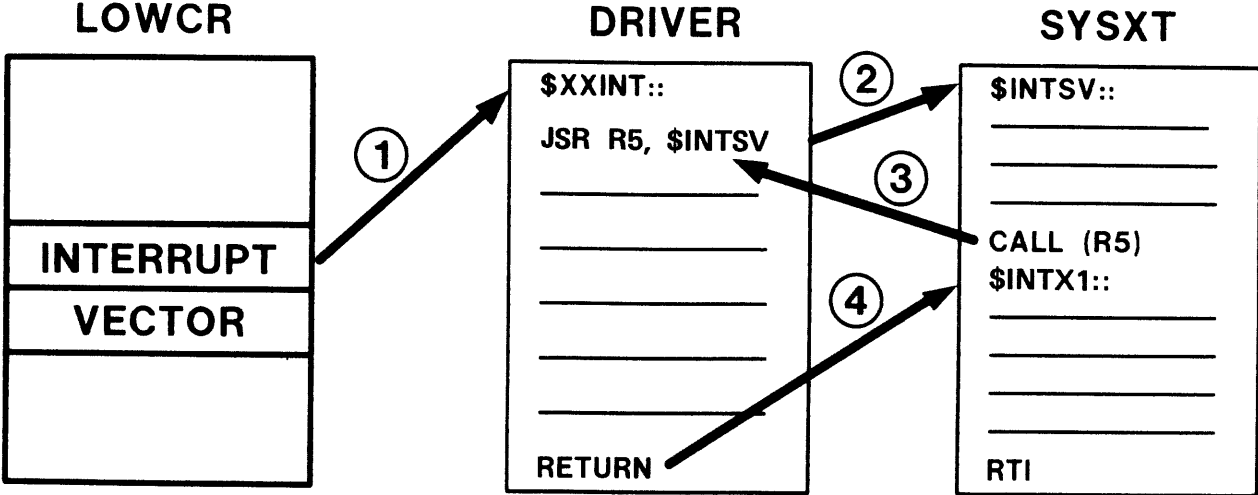


Figure 8-6 Interrupt Processing

## SYSTEM SYNCHRONIZATION

### Device Driver Processing

- Usually divided into three processing sections
- Processor Status Word in vector causes entry into interrupt service routine at priority 7
  - All interrupts are blocked
  - Usually \$INTSV is called and lowers priority
- Critical processing is performed at the priority of the device
  - For a terminal, the last input character is processed and the interrupt-enable bit is set for the next character
  - If the system data base must be accessed, a FORK process is created
- A device driver can access the system data base only as a FORK process
  - A FORK process executes at processor priority 0

### The Interrupt Exit Routine

- Code begins at label \$INTX1 in the module SYSXT
- Raises processor priority to 7 to lock out interrupts
- Checks for waiting FORK process
  - If one: lowers priority to 0
  - saves R0 - R3 on system stack
  - executes the \$DIRXT routine
- Increments \$STKDP
- Restores general registers
- Executes RTI instruction to return to USER mode

SYSTEM SYNCHRONIZATION

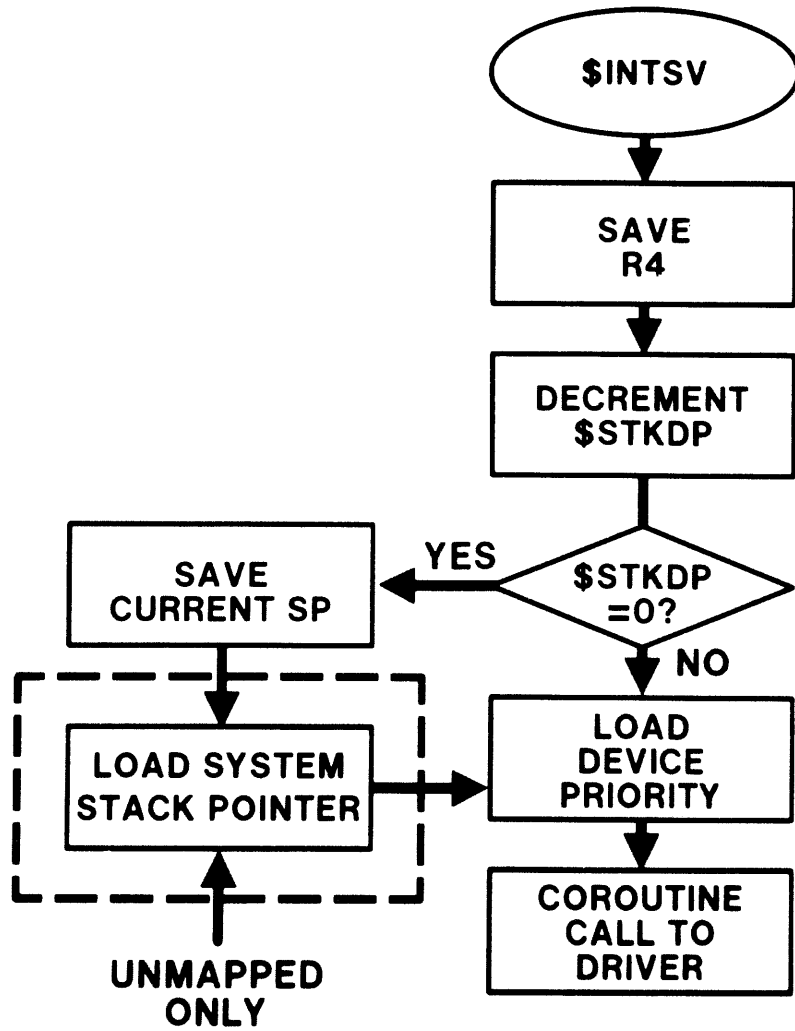


Figure 8-7 The Interrupt Save Routine

SYSTEM SYNCHRONIZATION

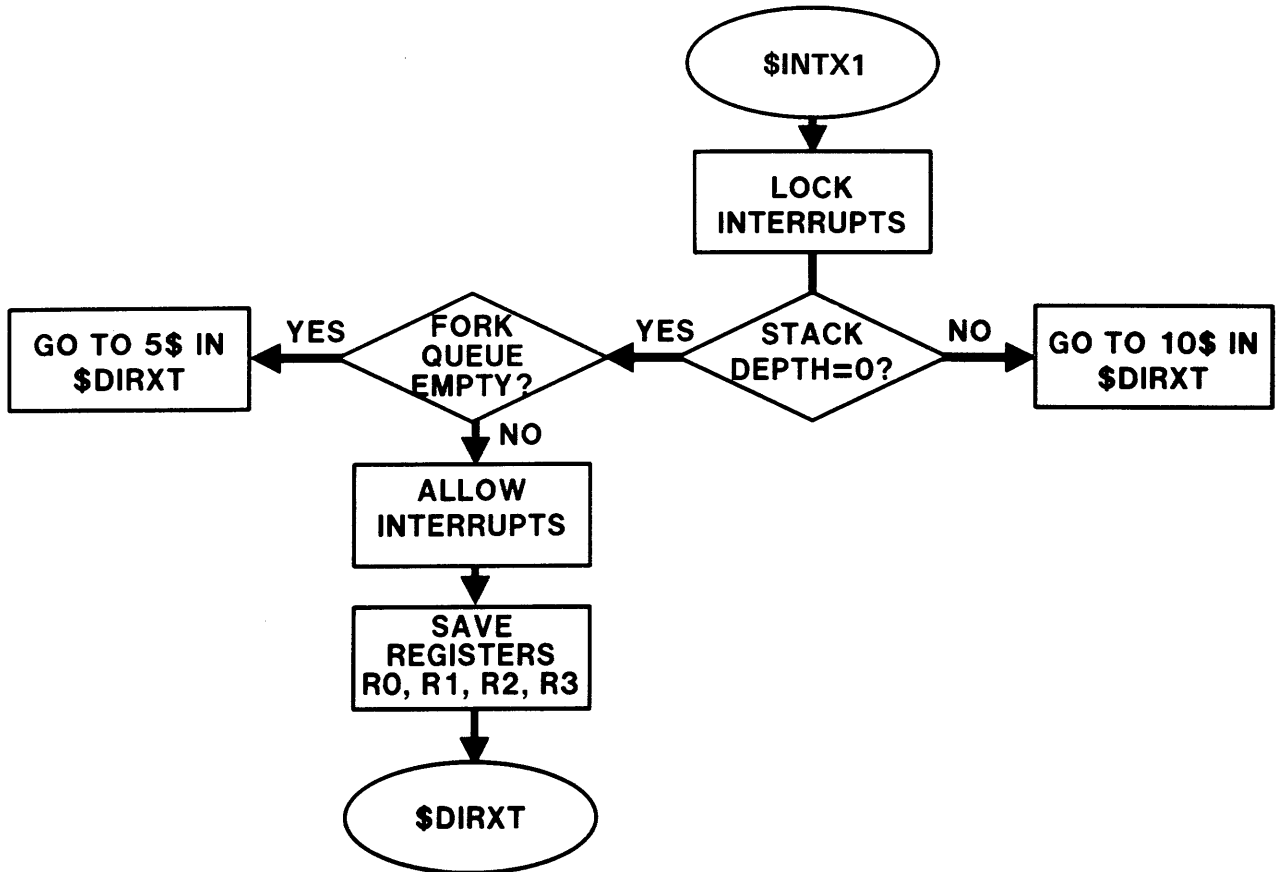


Figure 8-8 The Interrupt Exit Routine

## **FORK PROCESSING**

- Provides serial access to the system data base
  - Processes needing access are queued
  - No process gains access until the current process is finished with the system data base
- Usually process is part of a device driver, but any privileged task can create a FORK process
- Created by routines in module SYSXT
  - \$FORK - Used by device drivers
  - \$FORK0 - Creates FORK process without saving R4 and R5
  - \$FORK1 - Creates FORK process saving R4 and R5
  - \$FORK2 - Used by connect-to-interrupt routines

### **The FORK Block**

- Four word block containing
  - Link word for FORK list
  - Saved PC
  - Saved R5
  - Saved R4
- FORK block for device driver contained in the SCB

### **The FORK List**

- FORK blocks are linked into FIFO queue called FORK list
- Begins at list head in SYSCM at location \$FRKHD

SYSTEM SYNCHRONIZATION

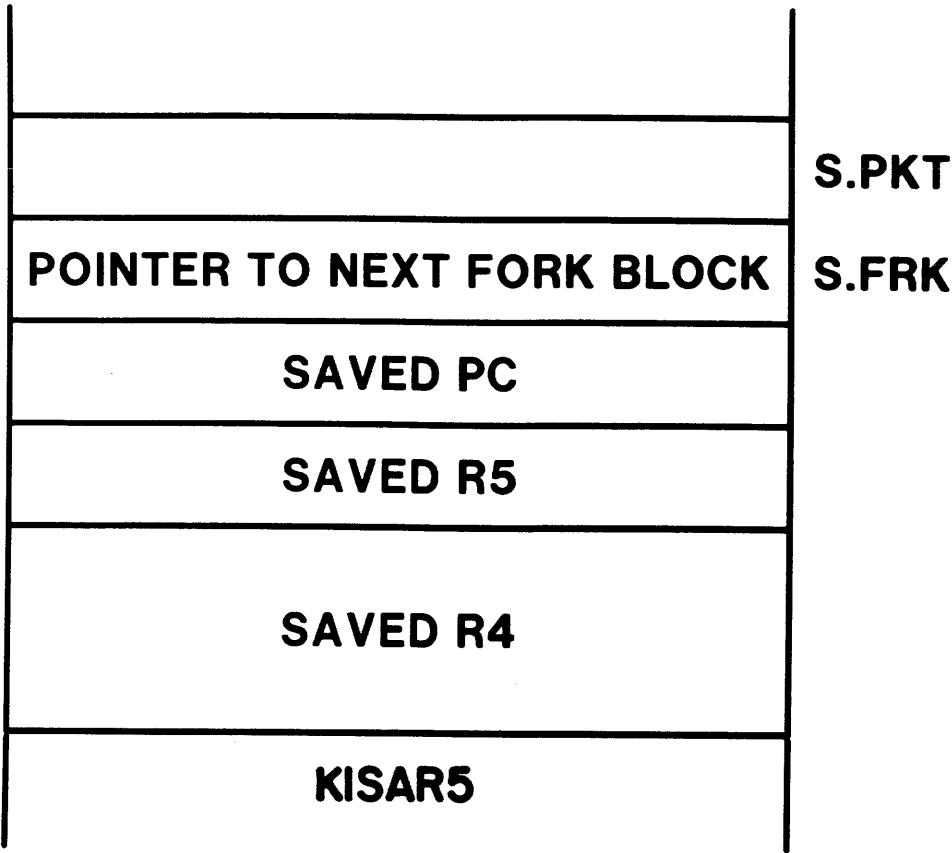


Figure 8-9 The FORK Block in the SCB

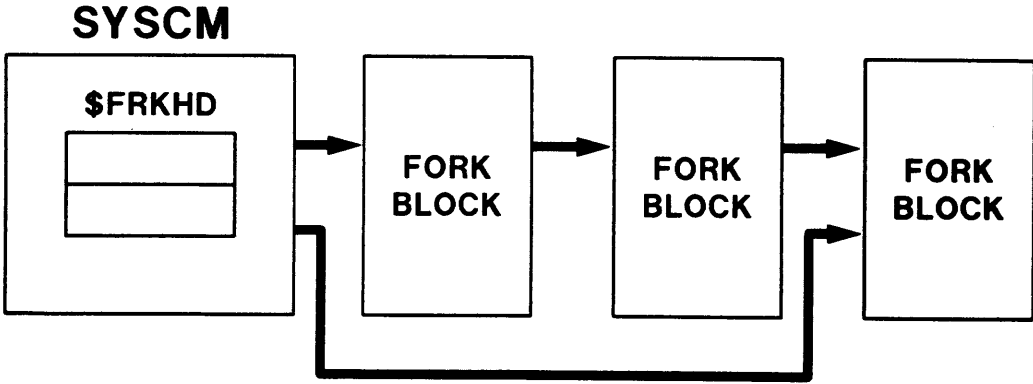


Figure 8-10 The FORK List

SYSTEM SYNCHRONIZATION

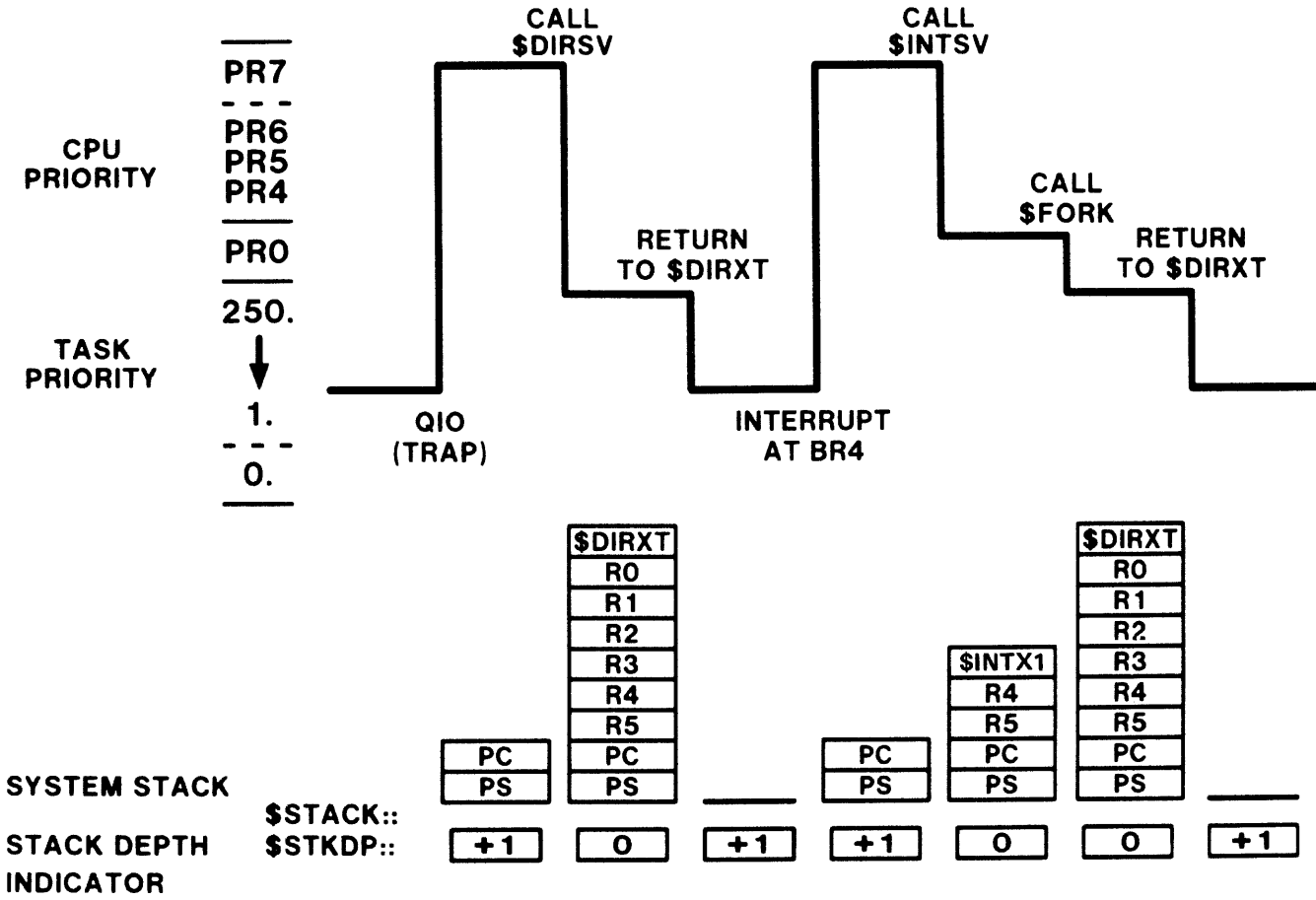


Figure 8-11 Interrupting a Task



# SYSTEM SYNCHRONIZATION

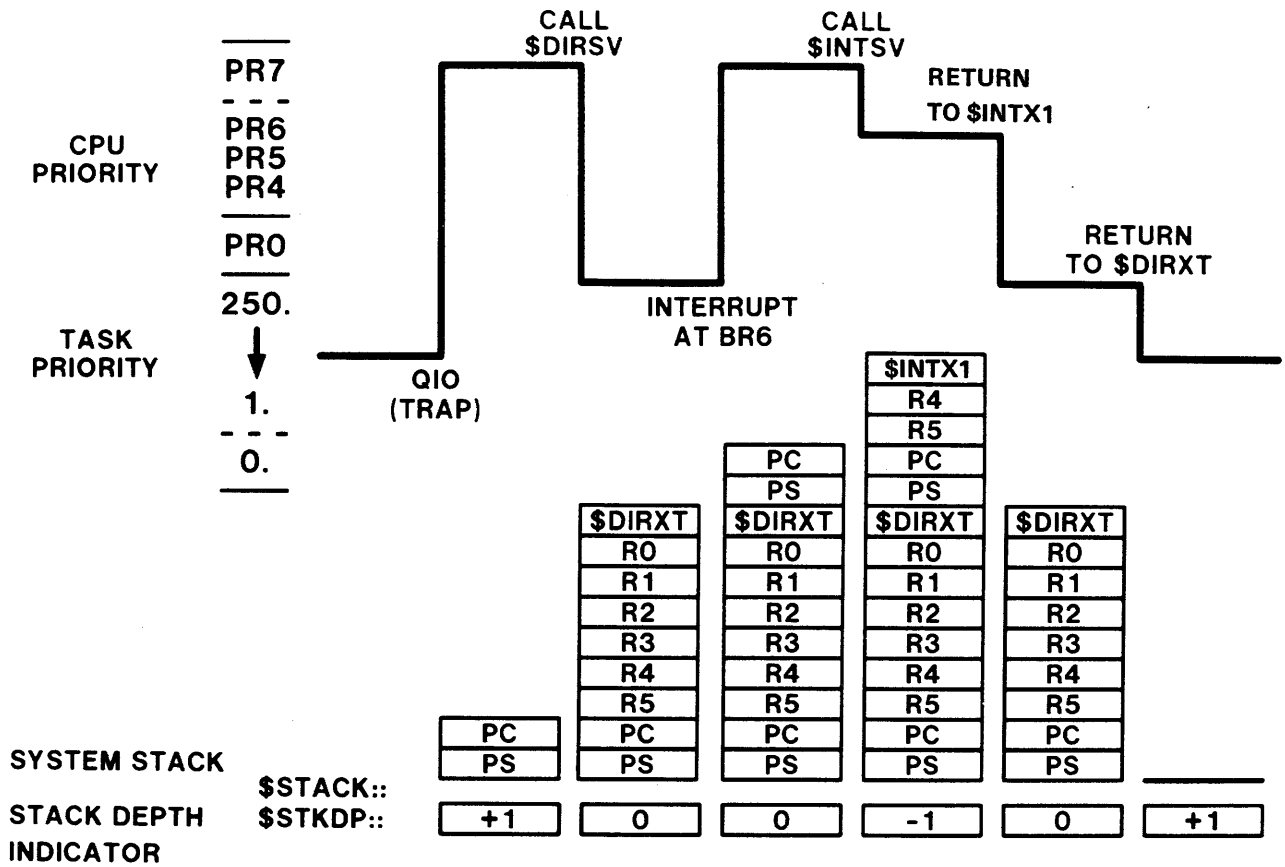


Figure 8-12 Interrupt Executive Processing a Directive

# SYSTEM SYNCHRONIZATION

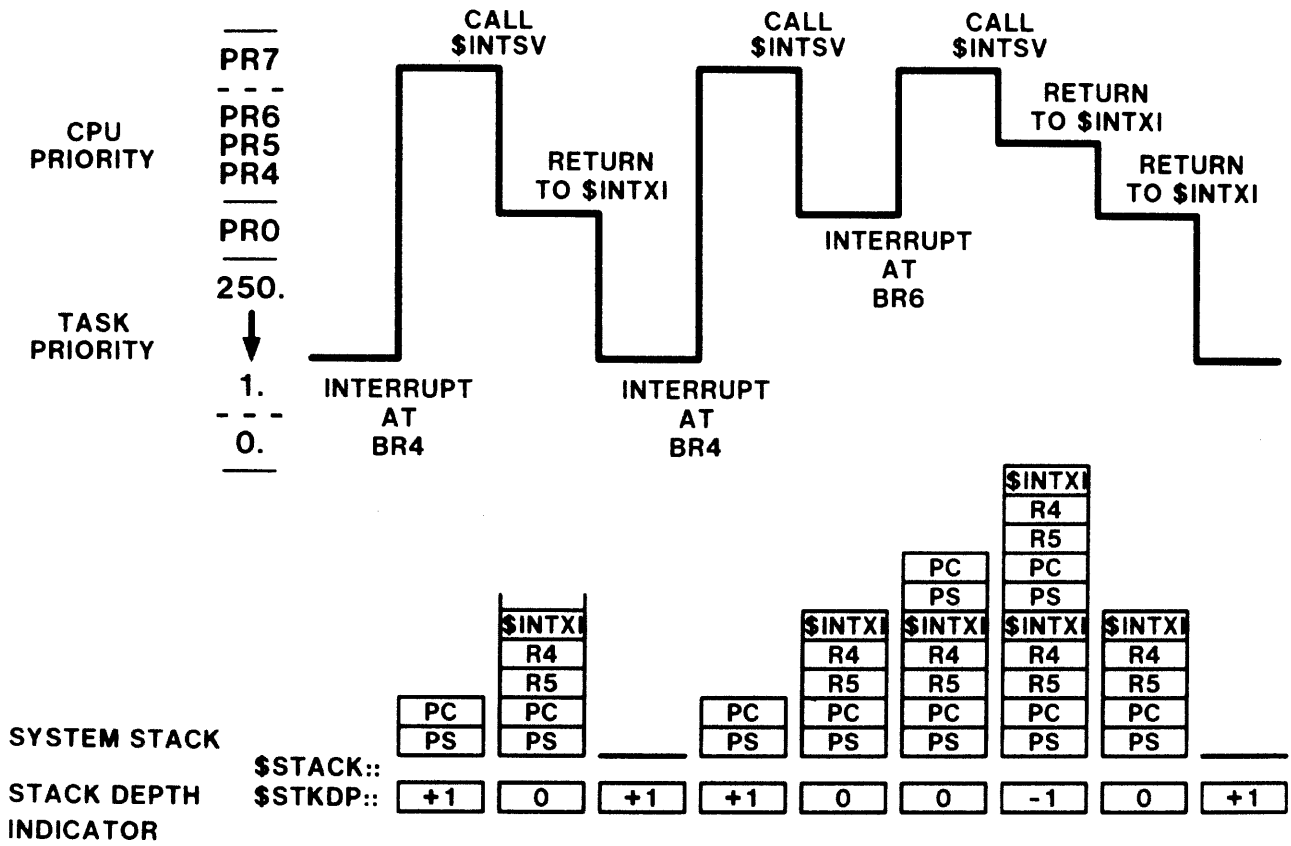


Figure 8-13 Interrupt Executive Processing an Interrupt

# SYSTEM SYNCHRONIZATION

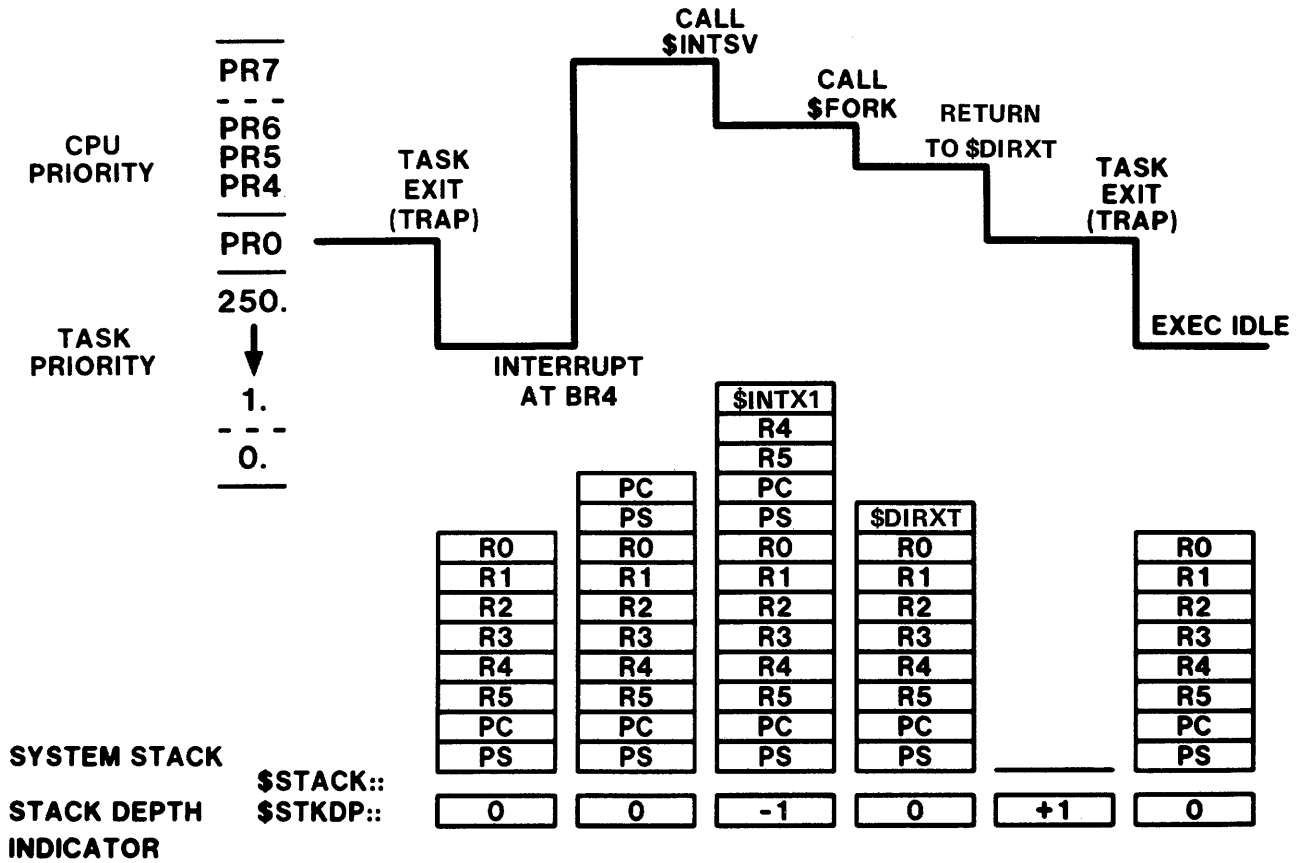


Figure 8-14 Interrupt Executive in an Idle Loop

## SYSTEM SYNCHRONIZATION

### PRIVILEGED TASKS

- Privilege bit is set in second status word in TCB
  - Task can use privileged directives
  - Task can perform privileged I/O functions
  - Task can perform logical block transfers to/from mounted volumes
- Task is built privileged by using the /PR switch when taskbuilding
  - /PR:Ø creates privileged task whose mapping is the same as that of a nonprivileged task
  - /PR:n creates privileged task which maps to the Executive
    - n = 4 if Executive is 16K words
    - n = 5 if Executive is 2ØK words

## SYSTEM SYNCHRONIZATION

### Processing a Privileged Task

- Privileged task must switch to KERNEL mode to access system data base
- Switch to KERNEL mode is performed by CALL \$SWSTK,LABEL instruction

CALL macro translates this to EMT 376

CALL macro is in SY:[11,10]RSXMC.MAC

LABEL is a location in the privileged task to return when leaving KERNEL mode

- In module DRDSP, a jump to location \$SWSTK in module SYSXT is executed
- The routine \$SWSTK

Moves the contents of USER mode APRs 5 and 6 to KERNEL mode APRs 5 and 6

Moves the address of LABEL to location SP+16 on the stack

SYSTEM SYNCHRONIZATION

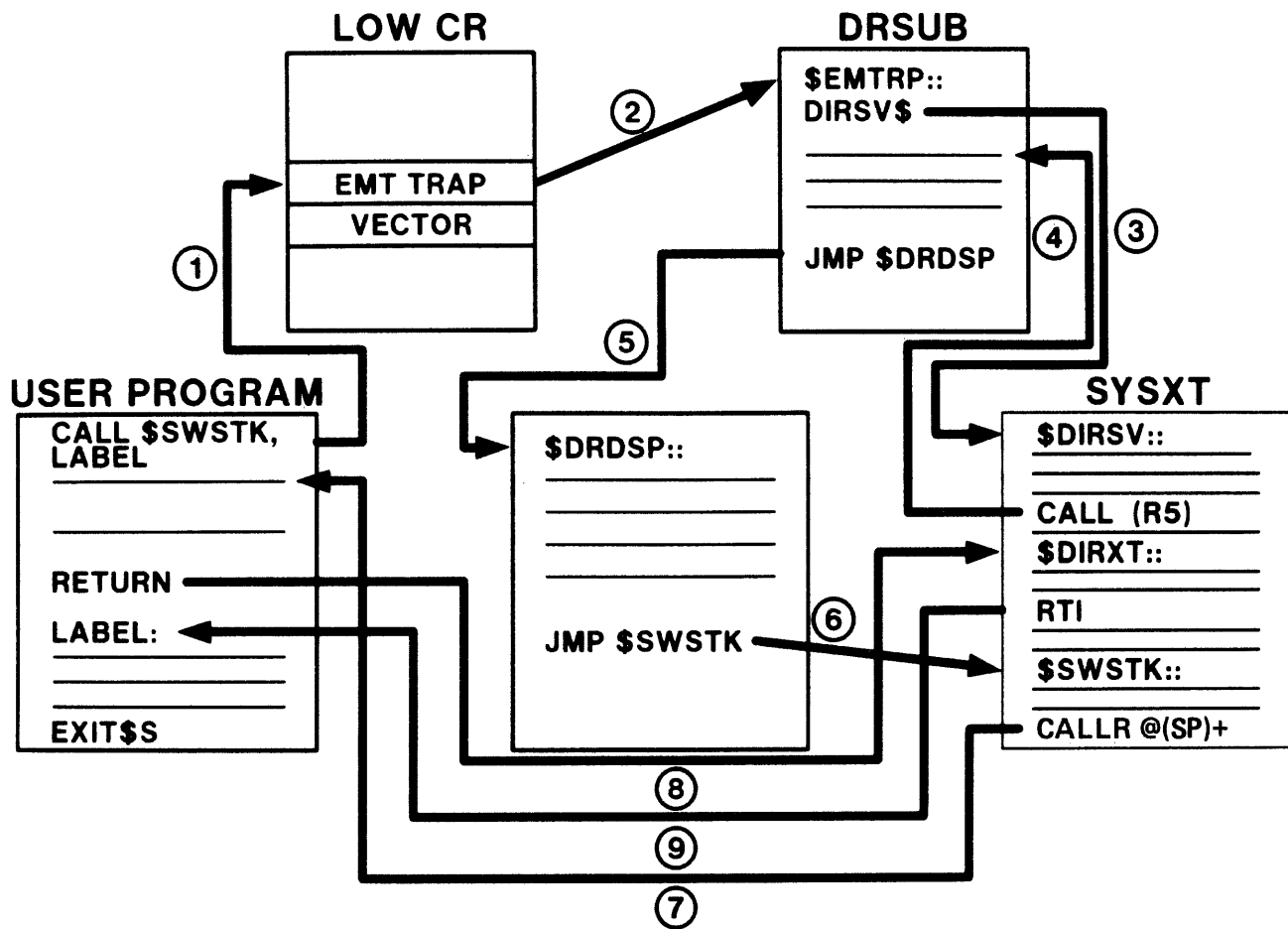


Figure 8-15 Privileged Task Processing

# SYSTEM SYNCHRONIZATION

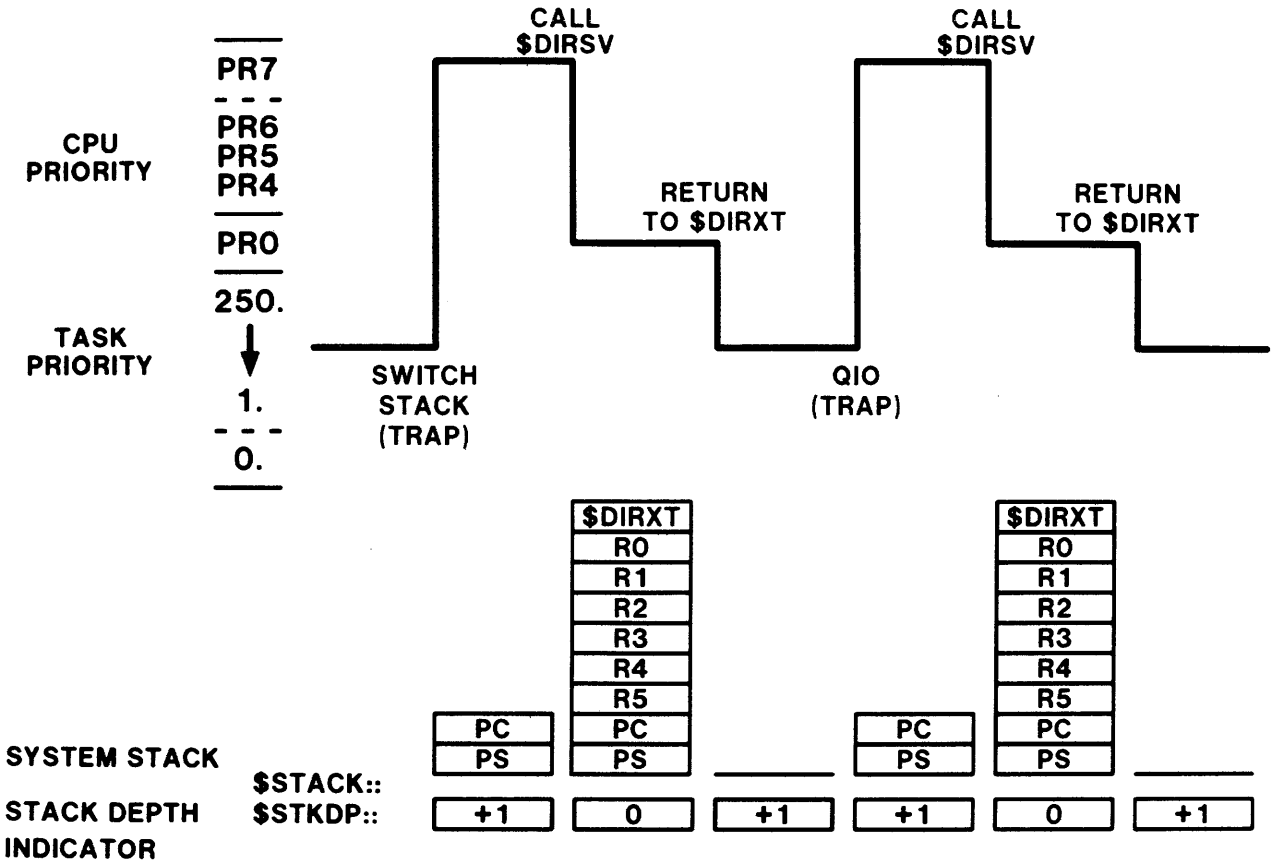


Figure 8-16 Privileged Task Switches Stack and Returns

SYSTEM SYNCHRONIZATION

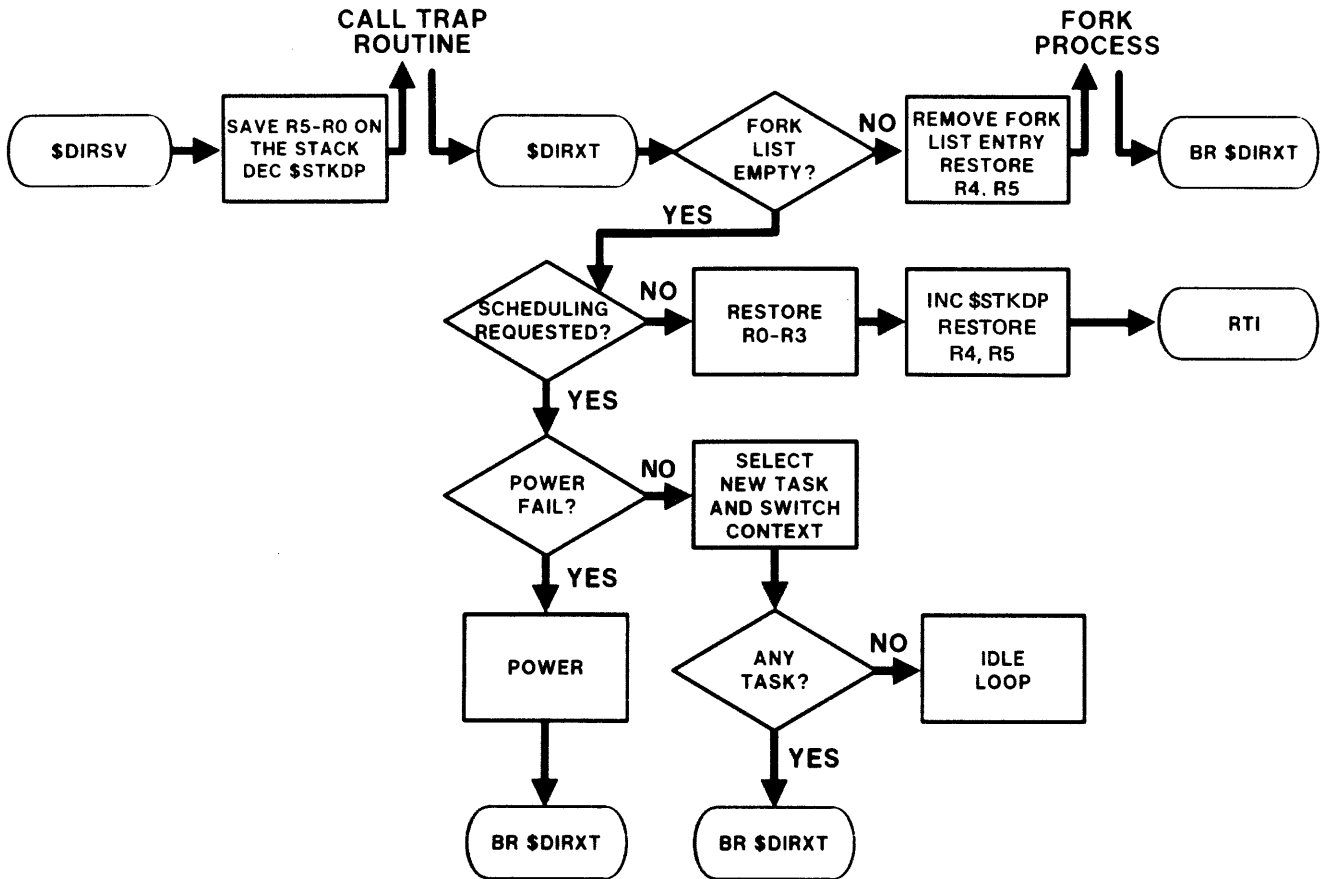


Figure 8-17 System Synchronization Logic: \$DIRSV



SYSTEM SYNCHRONIZATION

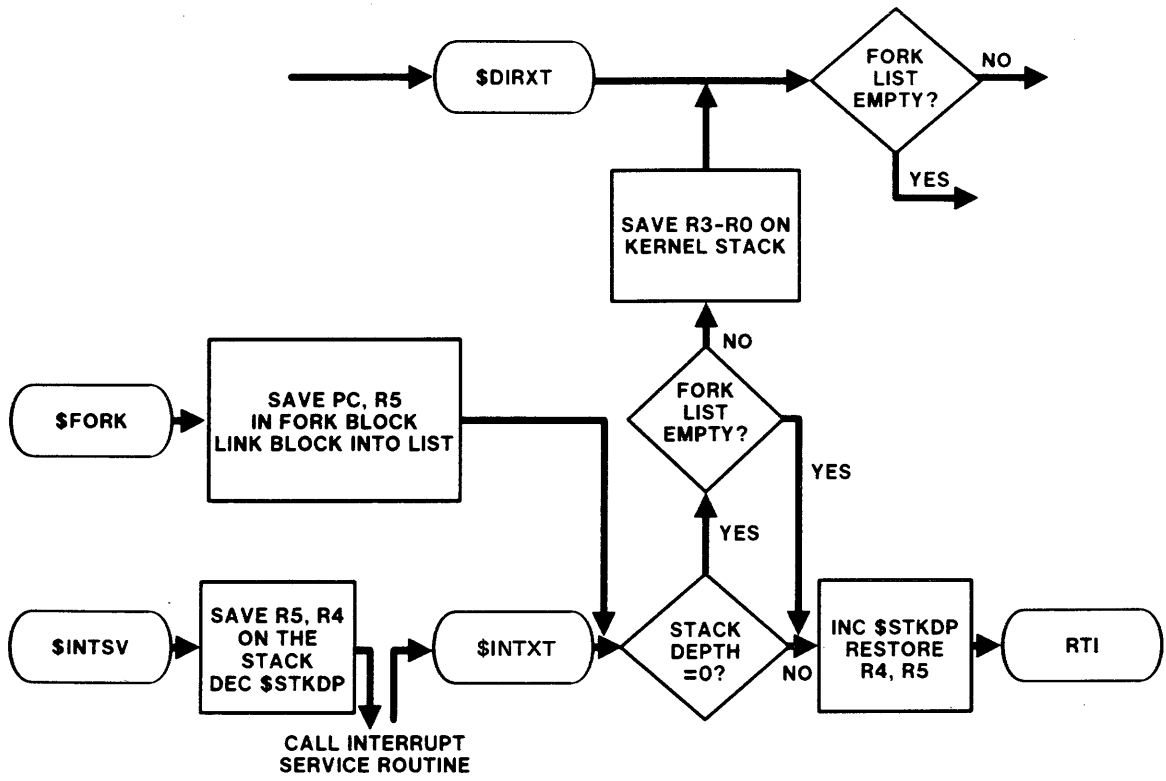


Figure 8-17 System Synchronization Logic: `$DIRXT`, `$FORK`, and `$INTSV`



## **WRITING PRIVILEGED TASKS**



## INTRODUCTION

In many practical environments, it is often necessary to write tasks which must interact with the Executive in ways not planned by the designers of the operating system. The tool used in these situations is the privileged task. (In this module, "privileged task" refers to a task which maps to the Executive.) A privileged task has access to both the system data base and Executive code and can therefore act as an extension of the operating system.

To write and use privileged tasks, the programmer must understand the operating system, the system data base and the methods that the Executive uses to synchronize access to the system data base. The previous modules, together with this module, provides that understanding.

## OBJECTIVES

1. Assemble and taskbuild privileged tasks.
2. Use a privileged task to access the system data base.
3. Use Executive routines to perform tasks.

## RESOURCES

1. RSX-11M System Lists and Data Structures



## OVERVIEW

### Why Write a Privileged Task

- To acquire the privileged attribute
  - Allows task to issue privileged directives
  - Allows access to any file without protection checks
  - Allows task to issue logical block I/O to a mounted volume
  
- Tasks which map to the Executive have access to:
  - Routines contained in the Executive
  - Executive data base including
    - System Common (SYSCM)
    - System device tables (SYSTB)
    - Dynamic Storage Region (POOL)
  
  - The I/O Page
    - Device registers
    - Memory management registers

## Privileged Task Structure

- Consists of at least three sections

### First section

Executes in USER mode

Contains the transfer point of the task

Contains code for processing before transferring to system state

### Second section

Executes in KERNEL mode

Contains code which accesses Executive data

### Third section

Executes in USER mode

Contains return location from KERNEL mode

Contains code for processing data obtained from the Executive in the second section

- USER Mode APRs

For system with 16K word Executive

APRs 0 - 3 are used to map the Executive

APRs 4 - 6 are used to map the privileged task

APR 7 is normally used to map the I/O page but can map an added 4K words of the task if needed

Privileged task can be

12K words if I/O page is needed in USER mode

16K words if I/O page is not needed in USER mode



## WRITING PRIVILEGED TASKS

- For system with 20K word Executive

APRs 0 - 4 are used to map the Executive

APRs 5 and 6 are used to map the privileged task

APR 7 is normally used to map the I/O page but can map an added 4K words of the task if needed

Privileged task can be

8K words if I/O page is needed in USER mode

12K words if I/O page is not needed in USER mode

## Restrictions on Privileged Tasks

- Parameter Passing

User state to system state

Values can be passed in registers R0 - R5

Values can be passed in memory locations

System state to user state

Values can only be passed in memory locations since registers are restored

- Time spent in system state should be minimal

Interrupt processing affected since the FORK queue is not serviced

No other user task can execute

- No trap can occur in system state

No directives can be executed

Traps in system state cause a system crash

- Privileged instructions should be used with care

## CREATING A PRIVILEGED TASK

### Assembling a Privileged Task

- To assemble a privileged task to map to the Executive:  
`>MAC File,File=[1,1]EXEMC/ML,[11,10]RSXMC/PA:1,[USER UIC]File`

- EXEMC.MLB

Contains

Macros defining offsets

Bit values for all system data structures

Not needed if no reference is made to these structures

- RSXMC.MAC

Contains

Conditional assembly symbols defining the system

Several commonly used macros such as CALL and CALLR

Always needed to interpret CALL \$\$WSTK

### Taskbuilding a Privileged Task

- The following command is needed to taskbuild a privileged task which maps to the Executive

```
>TKB File/PR:n=File,[1,1]EXELIB/LB,[1,54]RSX11M.STB
```

- EXELIB.

Executive object library

Contains global symbols for resolving offsets in data structures not resolved during assembly

- RSX11M.STB

Executive symbol table file

Allows resolution of Executive global symbols used in privileged task

## SAMPLE PRIVILEGED TASKS

### Tracing Through System Lists

- Function of privileged task
  - Calculate and display size of free pool
- The pointer \$CRAVL is used to access the list of free pool blocks
- \$SWSTK is used to switch to system state
- Time spent in system state is minimal
  - System data accessed in system state
- I/O performed in user
  - No traps in system state
- Size of free pool is saved before return to user state
  - Registers cannot be used to pass data from system to user state

## WRITING PRIVILEGED TASKS

Table 9-1 Pointers to System Lists

Pointer*	System List
\$LOGHD	Logical device assignment list
\$CRAVL	Free pool block listhead
\$ACTHD	Active task list listhead
\$CFLPT	Pointer to first checkpoint file PCB
\$FRKHD	FORK queue listhead
\$CLKHD	Clock queue listhead
\$PARHD	Pointer to partition list
\$TSKHD	Pointer to system task directory
\$GGEF	Pointer to group global event flags list
\$ERHEA	Error logging message queue listhead
\$PKAVL	Pointer to list of preallocated I/O packets
\$UMRHD	Mapping assignment block listhead
\$UMRWT	UMR wait queue listhead
\$MOULS	Mounted device listhead

\*All pointers are located in SYSCM

## WRITING PRIVILEGED TASKS

Table 9-2 Pointers to Data Structures

Pointer*	Description
\$HEADR	Pointer to current task header
\$TKNPT	Pointer to TKTN TCB
\$SHFPT	Pointer to shuffler TCB
\$MCRPT	Pointer to MCR TCB
\$TKTCB	Pointer to current task TCB
\$LDRPT	Pointer to loader TCB

\*All pointers are located in SYSCM

```

1          .TITLE POOLA
2          ;+
3          ;** - POOLA - DISPLAY POOL SIZE
4          ;
5          ; THIS TASK WILL CALCULATE AND DISPLAY THE TOTAL SYSTEM
6          ; DYNAMIC STORAGE REGION SIZE
7          ;-
8          .MCALL QIOW$,EXIT$,DIR$
9          .NLIST BEX
10 000000  OUTQID: QIOW$ IO.WVB,1,1,,,,<OUTBUF,0,40>
11 000030  ARG1ST: .BLKW 1 ; ARG LIST FOR $EDMSG
12 000032      124      117      124  OUTMES: .ASCIZ /TOTAL POOL = %D./
13          000045  BUFFL = .-OUTMES+20.
14 000053  OUTBUF: .BLKB BUFFL
15          .EVEN
16 000120  START:
17 000120  005001  CLR R1 ; FOR TOTAL FREE SPACE
18 000122  012700  000000G  MOV ##CRAVL,R0 ; POINT TO FIRST DSR PACKET
19 000126  CALL $SWSTK,30$ ; SWITCH TO SYSTEM STATE
20 000132  066001  000002  10$: ADD 2(R0),R1 ; ADD IN SIZE OF THIS PACKET
21 000136  011000  MOV (R0),R0 ; GET LINK TO NEXT PACKET
22 000140  001374  BNE 10$ ; IF NE NOT END OF LIST
23 000142  006201  ASR R1 ; CONVERT TO WORDS
24 000144  010167  177660  MOV R1,ARG1ST ; SAVE SIZE OF DSR
25 000150  000207  RETURN ; RETURN TO USER STATE
26          ;
27          ; FORMAT AND PRINT OUTPUT
28          ;
29 000152  012700  000053'  30$: MOV #OUTBUF,R0 ; SET OUTPUT STRING
30 000156  012701  000032'  MOV #OUTMES,R1 ; AND INPUT STRING
31 000162  012702  000030'  MOV #ARG1ST,R2 ; AND ARGUMENT LIST
32 000166  CALL $EDMSG ; FOR EDIT MESSAGE
33 000172  010167  177620  MOV R1,OUTQID+Q.IOPL+2 ; UPDATE MESSAGE SIZE
34 000176  DIR$ #OUTQID ; WRITE OUT MESSAGE
35 000204  EXIT$S ; AND EXIT FROM PROGRAM
36          .END START

```

Example 9-1 Tracing Through System Lists  
(Sheet 1 of 2)

236

WRITING PRIVILEGED TASKS



ARBLST 000030R	G\$\$TTK= 000000	L\$\$F11= 000002	Q.IOSE= 000010	T\$\$BTW= 000000
A\$\$CHK= 000000	H\$\$RTZ= 000074	L\$\$11R= 000000	R\$\$CON= 000000	T\$\$CCA= 000000
A\$\$CLI= 000020	ID.WVB= ***** GX	M\$\$CRB= 000124	R\$\$DER= 000000	T\$\$CDM= 000000
A\$\$CNT= 000000	I\$\$CSZ= 000200	M\$\$CRX= 000000	R\$\$DSP= 000000	T\$\$CON= 000000
A\$\$CPS= 000000	I\$\$RAR= 000000	M\$\$EXT= 000000	R\$\$EIS= 000000	T\$\$CTR= 000000
A\$\$NSI= 000000	I\$\$RDN= 000000	M\$\$FCS= 000000	R\$\$EXV= 000000	T\$\$CUP= 000000
A\$\$PRI= 000000	K\$\$CNT= 177546	M\$\$MGE= 000000	R\$\$H0V= 000000	T\$\$C11= 000001
A\$\$TRP= 000000	K\$\$CSR= 177546	M\$\$MUF= 000000	R\$\$H11= 000004	T\$\$ESC= 000000
BUFFL = 000045	K\$\$DAS= 000000	M\$\$NET= 002627	R\$\$JP1= 000004	T\$\$GMC= 000000
C\$\$CDA= 000002	K\$\$IEN= 000115	M\$\$DVR= 000000	R\$\$JS1= 000004	T\$\$GTS= 000000
C\$\$CKP= 000000	K\$\$LDC= 000001	M\$\$XLN= 000400	R\$\$K11= 000001	T\$\$KMG= 000000
C\$\$INT= 000000	K\$\$TFS= 000074	N\$\$LDV= 000001	R\$\$LKL= 000001	T\$\$LWC= 000000
C\$\$DRE= 001000	LD\$CO = 000000	N\$\$MOV= 000041	R\$\$L11= 000001	T\$\$M03= 000002
C\$\$RSH= 177564	LD\$DB = 000000	N\$\$UMR= 000030	R\$\$MPL= 000000	T\$\$RED= 000000
C\$\$RUN= 000000	LD\$DD = 000000	OUTBUF 000053R	R\$\$M11= 000004	T\$\$RNE= 000000
D\$\$H11= 000003	LD\$DK = 000000	OUTMES 000032R	R\$\$NDC= 000006	T\$\$RFR= 000000
D\$\$IAG= 000000	LD\$DL = 000000	OUTRIO 000000R	R\$\$NDH= 000226	T\$\$RST= 000000
D\$\$ISK= 000000	LD\$DM = 000000	F\$\$D70= 000000	R\$\$NDL= 000001	T\$\$RUB= 000000
D\$\$L11= 000001	LD\$DR = 000000	F\$\$GMX= 000000	R\$\$SND= 000000	T\$\$SMC= 000000
D\$\$M11= 000003	LD\$DS = 000000	F\$\$LAS= 000000	R\$\$X21= 000001	T\$\$UTO= 000036
D\$\$PAR= 000000	LD\$DT = 000000	F\$\$MAX= 000400	R\$\$11M= 000000	T\$\$USB= 000001
D\$\$SHF= 000000	LD\$DY = 000000	F\$\$OFF= 000000	R\$\$611= 000001	U\$\$DAS= 000000
D\$\$WCK= 000000	LD\$LP = 000000	F\$\$OOL= 000000	START 000120R	U\$\$MHI= 000000
D\$\$YNC= 000000	LD\$MM = 000000	F\$\$P45= 000000	S\$\$ECC= 000000	U\$\$MLO= 140000
D\$\$YNM= 000000	LD\$NL = 000000	F\$\$RFL= 000000	S\$\$HDW= 000000	U\$\$MRN= 170230
D\$\$ZMD= 000000	LD\$RI = 000000	F\$\$RTY= 000000	S\$\$LIB= 000000	V\$\$CTR= 000774
D\$\$Z11= 000001	LD\$TT = 000000	F\$\$SRF= 000000	S\$\$NM1= 042513	V\$\$TLD= 000120
E\$\$DVC= 000000	LD\$VT = 000000	F\$\$WND= 000000	S\$\$NM2= 046522	V\$\$TLM= 000205
E\$\$NSI= 000000	LK.SFN= 000002	Q\$\$DPT= 000005	S\$\$NM3= 052111	V\$\$TRM= 000000
E\$\$PER= 000000	LK.WAT= 000010	Q.IDAE= 000012	S\$\$OPT= 000000	X\$\$DBT= 000000
E\$\$XPR= 000000	L\$\$ASG= 000000	Q.IDEF= 000006	S\$\$UBD= 000000	X\$\$HDR= 000000
F\$\$LPP= 000000	L\$\$DBG= 000000	Q.IDFN= 000002	S\$\$WPC= 000036	\$CRAVL= ***** GX
F\$\$LVL= 000001	L\$\$DRV= 000000	Q.IOLU= 000004	S\$\$WPR= 000005	\$EDMSG= ***** GX
G\$\$TTP= 000000	L\$\$LDR= 000000	Q.IOFL= 000014	S\$\$WRG= 000000	\$\$\$ARG= 000003
G\$\$TSS= 000000	L\$\$PTD= 000170	Q.IOFR= 000007	S\$\$YSZ= 044000	\$\$\$DST= 000014

. ABS. 000000 000  
000212 001  
ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 11375 WORDS ( 45 PAGES)  
DYNAMIC MEMORY: 12692 WORDS ( 48 PAGES)  
ELAPSED TIME: 00:00:12  
%POOLA=LB:[2,54]RSXMC/PA:1,[1,1]EXEMC/ML,DB2:[305,306]POOLA

Example 9-1 Tracing Through System Lists  
(Sheet 2 of 2)

## Calling Executive Routines

- Function of privileged task

To simulate issuing an MCR command from a terminal

- Privileged task must construct MCR command block

Terminal UCB is located by searching device list

MCR command block (84 bytes) is allocated from pool by using routine \$ALOCB

Block is queued to MCR by using routine \$QMCRL

Block is deallocated on I/O error by calling \$DEACB

- Time spent in system state is minimized by returning to user state to perform calculations, etc.

Table 9-3 Executive Pool Routines\*

Entry Point	Description	Inputs	Outputs
\$ALOCB	Allocates a variable length core buffer First fit Length in multiples of four bytes	R1 = Size of buffer	C-bit = 0 Block allocated C-bit = 1 Insufficient space R0 - Address of block R1 - Length of block
\$DEACB	Deallocates a variable length core buffer	R0 = Address of block R1 = Block size	None

\*All routines are in Executive module CORAL

## WRITING PRIVILEGED TASKS

Table 9-4 Executive Queueing Routines\*

Entry Point	Description	Inputs	Outputs
\$QINSF	Inserts entry at end of FIFO queue  Saves R0, R1	R0 = Address of listhead R1 = Address of new entry	None
\$QINSP	Inserts entry in a priority ordered queue  Saves R0, R1	(Same as \$QINSF)	None
\$QINSB	Inserts entry at beginning of queue  All registers are saved	(Same as \$QINSF)	
\$QRMVF	Removes entry from beginning of queue  Saves R0	R0 = Address of listhead	C-bit = 0 Entry removed C-bit = 1 Empty list R1 - Address of entry
\$QRMVT	Removes entry with a specified TCB address	R0 = Address of listhead R1 = TCB address	C-bit = 0 Entry removed C-bit = 1 Entry not found R1 - Address of entry
\$QMCRL	Queues a command line to CLI of issuing terminal	R1 = Address of command line	None

\*All routines are in Executive model QUEUE

# WRITING PRIVILEGED TASKS

Table 9-5 Other Executive Routines

Entry Point	Description	Inputs	Outputs
\$SRSTD	Searches STD for specified task  Module: REQSB	R3 = Address of RAD50 task name	C-bit = 0 Task found C-bit = 1 Task not found R0 = TCB address of task
\$SRNAM	Search the partition list for a named partition  Module: PLSUB	R3 = Address of RAD50 name	C-bit = 0 Partition found C-bit = 1 Not found R2 = PCB address
\$CEFI	Converts an event flag number to an event flag address  Module: EXESB	R0 = Event flag number R5 = TCB address of task	R0 = Mask word R1 = Event flag address

```

1          .TITLE  TERM
2          ;+
3          ;
4          ; THIS TASK ASKS THE USER FOR A TERMINAL NUMBER AND A
5          ; COMMAND LINE.  IT THEN PASSES THE COMMAND TO MCR
6          ; AS IF HAD ORIGINATED AT THE SPECIFIED TERMINAL.  IT
7          ; PERFORMS THIS TASK BY USING SYSTEM SUBROUTINES, $ALOCB
8          ; AND $QMCRL, TO ALLOCATE A BLOCK FROM POOL AND PASS IT
9          ; TO MCR.
10         ;
11         ; THE TASK MUST BE BUILT PRIVILEGED AND MAP TO THE EXECUTIVE.
12         ;
13         ; TO ASSEMBLE:
14         ;
15         ; >MAC TERM=[1,1]JEXEMC/ML,[11,10]JRSXMC/PA:1,[YOUR UIC]TERM
16         ;
17         ; TO BUILD:
18         ;
19         ; >TKB TERM/PR:5=TERM,[1,54]JRSX11M.STB/SS
20         ;
21         ;+
22         .MCALL  EXIT$S,QIOW$S,DCBDF$
23 000000    DCBDF$
24         ;
25         ; TERMINAL MESSAGES
26         ;
27 000000    012    015    105  PRMT:  .ASCII  <12><15>/ENTER A TERMINAL NUMBER: /      ;PROMPT
28 000003    116    124    105
29 000006    122    040    101
30 000011    040    124    105
31 000014    122    115    111
32 000017    116    101    114
33 000022    040    116    125
34 000025    115    102    105
35 000030    122    072    040
36 28 000033    000033    PLEN  =      .--PRMT      ;LENGTH OF PROMPT
37 29 000033    105    116    124  MESS1: .ASCII  /ENTER A COMMAND FOR MCR/
38 000036    105    122    040
39 000041    101    040    103
40 000044    117    115    115
41 000047    101    116    104
42 000052    040    106    117
43 000055    122    040    115
44 000060    103    122
45 30 000027    000027    LENT1  =      .--MESS1
46 31 000062    116    125    115  MESS1: .ASCII  /NUMBER IS NOT OCTAL, TRY AGAIN!/
47 000065    102    105    122
48 000070    040    111    123
49 000073    040    116    117
50 000076    124    040    117
51 000101    103    124    101
52 000104    114    054    040
53 000107    124    122    131
54 000112    040    101    107
55 000115    101    111    116
56 000120    041
57 32 000037    000037    LEN1   =      .--MESS1

```

241

WRITING PRIVILEGED TASKS

```

33 000121      124      105      122  ERMES:  .ASCII  /TERMINAL NOT FOUND!/
    000124      115      111      116
    000127      101      114      040
    000132      116      117      124
    000135      040      106      117
    000140      125      116      104
    000143      041
34 000023      000023
35 000144      116      117      040  ERL      =      .--ERMES
    000147      120      117      117  POOL:    .ASCII  /NO POOL AVAILABLE!/
    000152      114      040      101
    000155      126      101      111
    000160      114      101      102
    000163      114      105      041
36 000022      000022
37 000166      111      057      117  FL      =      .--POOL
    000171      040      105      122  IOERR:  .ASCII  !I/O ERROR ON COMMAND INPUT!
    000174      122      117      122
    000177      040      117      116
    000202      040      103      117
    000205      115      115      101
    000210      116      104      040
    000213      111      116      120
    000216      125      124
38 000032      000032
39
40
41
42
43 000220
44 000224
45 000230      124      124
46 000232      177777
47 000234      000000
48 000236      000000
49 000240      000000
50 000242      000000
51 000244      000000
52 000246      000000
53
54
55
56 000250
57 000322
58 000374      016703  177626
59 000400      012700  000220
60 000404      005002
61 000406
62
63
64 000412      005702
65 000414      001402
66 000416      000167  000436
67 000422
68 000426      012700  000000G
69 000432      011000
70 000434      001422

```

```

IOL      =      .--IOERR
          .EVEN
          #MAKE SURE OF WORD BOUNDARY
;
; PROGRAM DATA
;
BUF:      .BLKB  4          #BUFFER FOR TERMINAL NUMBER
IOSB:     .BLKW  2          #I/O STATUS BLOCK
NAM:      .ASCII  /TT/     #TERMINAL NAME
ERRCNT:   .WORD  -1        #ERROR INDICATOR
          .ADDRESS OF COMMAND LINE IN POOL
PLACE:    .WORD  0          #ADDRESS OF POOL BLOCK
UCB:      .WORD  0          #SAVED UCB ADDRESS
DCB:      .WORD  0          #SAVED DCB ADDRESS
LOW:      .WORD  0          #SAVED LOW UNIT NUMBER
HIGH:     .WORD  0          #SAVED HIGH UNIT NUMBER
;
; BEGINNING OF CODE
;
TERM:     QIOW$S  #IO.WVB,#5,#1,,,<#PRMT,#PLEN,#40>  #PROMPT
          QIOW$S  #IO.RVB,#5,#1,,#IOSB,<#BUF,#4> #GET 'TT' NUMBER
          MOV     IOSB+2,R3  #SAVE CHARACTER COUNT
          MOV     #BUF,R0   #SET UP FOR CALL TO CONVERSION
          CLR     R2        #ROUTINE - FROM ASCII TO
          CALL    #COTB     # BINARY(OCTAL)
          # R1 WILL CONTAIN CONVERTED NUMBER
          # R2 WILL CONTAIN TERMINATOR
          TST     R2        #TEST FOR ERROR
          BEQ     CONT     #IF NOT CONTINUE
          JMP     ERR1     #GO TO ERROR ROUTINE
          CONT:   CALL    #SWSTK,BACK #SWITCH TO SYSTEM STATE
          MOV     ##DEVHD,R0 #PICK UP LISTHEAD FOR DCB LIST
          L1:    MOV     (R0),R0 #GO TO NEXT DCB
          REG     R0        ##IF NONE FINISH UP

```

WRITING PRIVILEGED TASKS

242

Example 9-2 Calling Executive Routines  
(Sheet 2 of 5)

```

71 000436 026760 177566 000004      CMP      NAM,D.NAM(R0)          ;;LOOK FOR 'TT' DCB
72 000444 001372                      BNE      L1                    ;;IF NOT 'TT' GET NEXT DCB
73 000446 116067 000006 177570      MOV     D,UNIT(R0),LOW        ;;GET LOW UNIT NUMBER
74 000454 116067 000007 177564      MOV     D,UNIT+1(R0),HIGH    ;;GET HIGH UNIT NUMBER
75 000462 020167 177560              CMP     R1,HIGH              ;;COMPARE INPUT WITH HIGH
76 000466 003361                      BGT     L1                    ;;IF INPUT LARGER GET NEXT DCB
77 000470 010067 177546              MOV     R0,DCB              ;;SAVE DCB ADDRESS
78 000474 062767 000001 177530      ADD     #1,ERRCNT           ;;INDICATE NO ERROR HERE
79 000502                                RETURN                          ;;RETURN TO USER STATE
80 000504                                GO:                               ;
81 000504 005767 177522              BACK:  TST     ERRCNT         ;NOW IN USER STATE
82 000510 001402                      BEQ     1$                   ;TEST FOR ERROR
83 000512 000167 000430              JMP     ERR2                 ;CONTINUE IF OK
84 000516 016700 177520              1$:   MOV     DCB,R0          ;GO TO ERROR ROUTINE
85 000522 016002 000002              MOV     D,UCB(R0),R2       ;GET DCB ADDRESS
86 000526 010104                      MOV     R1,R4              ;GET ADDRESS OF FIRST UCB
87 000530 166704 177510              SUB     LOW,R4             ;MOVE FOR CALCULATIONS
88                                          ;FIND THE NUMBER WITHIN UCBS
89 000534 016005 000010              MOV     D,UCBL(R0),R5     ; FOR CURRENT DCB
90 000540 070504                      MUL     R4,R5              ;GET UCB LENGTH
91 000542 060502                      ADD     R5,R2              ;CALCULATE OFFSET FOR UCB
92 000544 010267 177470              MOV     R2,UCB           ;CALCULATE BEGINNING OF UCB
93 000550 012767 177777 177454      MOV     #-1,ERRCNT        ;SAVE UCB ADDRESS
94 000556                                CALL    $SWSTK,BACK2       ;RESET ERROR COUNT
95 000562 012701 000124              MOV     #84.,R1          ;SWITCH TO SYSTEM STATE
96 000566                                CALL    $ALOCB            ;SET BLOCK SIZE
97 000572 103404                      BCS     NONE              ;ALLOCATE BLOCK FROM POOL
98 000574 005267 177432              INC     ERRCNT           ;NO ROOM IN POOL
99 000600 010067 177432              MOV     R0,PLACE        ;INDICATE NO ERROR HERE
100 000604                                NONE:  RETURN              ;SAVE ADDRESS OF POOL BLOCK
101 000606                                BACK2: ;RETURN TO USER STATE
102 000606 005767 177420              TST     ERRCNT         ;BACK IN USER STATE
103 000612 001402                      BEQ     1$                   ;CHECK FOR ERROR
104 000614 000167 000406              JMP     ERR3                 ;CONTINUE IF OK
105 000620 012700 000124              1$:   MOV     #84.,R0       ;GO TO ERROR ROUTINE
106 000624 016701 177406              MOV     PLACE,R1          ;SET LENGTH OF BLOCK
107 000630 112721 000040              2$:   MOVB   #40,(R1)+      ;GET ADDRESS OF BLOCK
108 000634 077003                      SOB     R0,2$              ;PLACE BLANKS IN BLOCK
109 000636 016767 177374 177370      MOV     PLACE,COMM       ;LOOP UNTIL THROUGH
110 000644 062767 000004 177362      ADD     #4,COMM          ;CALCULATE LOCATION OF COMMAND
111 000652                                ; LOCATION IN BLOCK
112 000724 005067 177274              CLRW   #IO.WVB,#5,#1,,, <#MES1,#LENT1,#40> ;PROMPT FOR COMMAND
113 000730 005067 177272              CLR    IO$B              ;
114 000734                                CLR    IO$B+2            ;
115 001006 103002                      CLRW   #IO.RVB,#5,#1,,IO$B,, <COMM,#80.> ;INPUT COMMAND
116 001010 000167 000272              BCC    3$                   ;CONTINUE IF OK
117 001014 105767 177204              JMP     ERR4                 ;BRANCH IF QIO ERROR
118 001020 002002                      TSTB   IO$B              ;CHECK FOR I/O ERROR
119 001022 000167 000260              BGE    4$                   ;CONTINUE IF OK
120 001026                                JMP     ERR4                 ;BRANCH IF ERROR
121 001032 016701 177200              3$:   CALL    $SWSTK,BACK3    ;SWITCH TO SYSTEM STATE
122 001036 016761 177176 000002      MOV     PLACE,R1         ;GET ADDRESS OF BLOCK
123 001044                                MOV     UCB,2(R1)         ;;PLACE UCB ADDRESS IN BLOCK
124 001050                                CALL    $QMCR           ;;QUEUE BLOCK TO MCR
125 001052                                RETURN                    ;;LEAVE SYSTEM STATE
126 001052                                BACK3: ;BACK IN USER STATE
127                                EXIT$S                    ;EXIT

```

243

WRITING PRIVILEGED TASKS

```

128 ; ROUTINE TO HANDLE BAD TERMINAL NUMBER
129 ;
130 001060 ERR1: QIOW$S #IO.WVB,#5,#1,,,,<#MESS1,#LEN1,#40> #PRINT MESSAGE
131 001132 012700 000220' MOV #BUF,R0 #GET INPUT BUFFER ADDRESS
132 001136 005020 CLEAR: CLR (R0)+ #CLEAR BUFFER
133 001140 077302 SOB R3,CLEAR #R3 CONTAINS CHARACTER COUNT
134 001142 000167 177102 JMP TERM #TRY AGAIN
135 ;
136 ; ROUTINE TO HANDLE NON-EXISTENT TERMINAL
137 ;
138 001146 ERR2: QIOW$S #IO.WVB,#5,#1,,,,<#ERMES,#ERL,#40> #PRINT MESSAGE
139 001220 EXIT$S #EXIT
140 ;
141 ; ROUTINE TO HANDLE POOL ALLOCATION FAILURE
142 ;
143 001226 ERR3: QIOW$S #IO.WVB,#5,#1,,,,<#POOL,#PL,#40> #PRINT MESSAGE
144 001300 EXIT$S #EXIT
145 ;
146 ; ROUTINE TO HANDLE I/O ERRORS ON COMMAND INPUT
147 ; THE POOL BLOCK MUST BE DEALLOCATED!
148 ;
149 001306 ERR4: QIOW$S #IO.WVB,#5,#1,,,,<#IOERR,#IOL,#40> #PRINT MESSAGE
150 001360 CALL $SWSTK,FIN ;;SWITCH TO SYSTEM STATE
151 001364 016700 176646 MOV PLACE,R0 ;;GET ADDRESS OF BLOCK
152 001370 012701 000124 MOV #84,,R1 ;;SET BLOCK LENGTH
153 001374 CALL $DEACB ;;DEALLOCATE BLOCK
154 001400 RETURN ;;LEAVE SYSTEM STATE
155 001402 FIN: #BACK IN USER STATE
156 001402 EXIT$S #EXIT
157 000250' .END TERM

```

Example 9-2 Calling Executive Routines  
(Sheet 4 of 5)



A\$\$BIO= 000000	D.MSK 000014	K\$\$IEN= 000113	PRMT 000000R	T\$\$BTW= 000000
A\$\$BRT= 000000	D.NAM 000004	K\$\$LDC= 000144	P\$\$BPR= 000063	T\$\$BUF= 000000
A\$\$CHK= 000000	D.PCB 000034	K\$\$TPS= 000144	P\$\$CTL= 000000	T\$\$CCA= 000000
A\$\$CLI= 000004	D.UCB 000002	LD\$CO = 000000	P\$\$FRS= 000310	T\$\$CCO= 000000
A\$\$CFS= 000000	D.UCBL 000010	LD\$DD = 000000	P\$\$GMX= 000000	T\$\$CFW= 000000
A\$\$NSI= 000000	D.UNIT 000006	LD\$DK = 000000	P\$\$HIL= 003100	T\$\$CTR= 000000
A\$\$PRI= 000000	D.VCAN= 000002	LD\$DL = 000000	P\$\$LAS= 000000	T\$\$CUP= 000000
A\$\$TRP= 000000	D.VDEB= 177776	LD\$DM = 000000	P\$\$LOL= 001130	T\$\$C11= 000001
BACK 000504R	D.VINI= 000000	LD\$DR = 000000	P\$\$OFF= 000000	T\$\$ESC= 000000
BACK2 000606R	D.VOUT= 000004	LD\$DS = 000000	P\$\$P45= 000000	T\$\$GMC= 000000
BACK3 001052R	D.VPWF= 000006	LD\$DT = 000000	P\$\$RFL= 000000	T\$\$GTS= 000000
BUF 000220R	ERL = 000023	LD\$LP = 000000	P\$\$RTY= 000000	T\$\$HFF= 000000
B\$\$LV1= 030463	ERMES 000121R	LD\$MM = 000000	P\$\$SRF= 000000	T\$\$HLD= 000000
B\$\$LV2= 020040	ERRCNT 000232R	LD\$TT = 000000	Q\$\$OFT= 000005	T\$\$J16= 000001
CLEAR 001136R	ERR1 001060R	LENT1 = 000027	R\$\$DER= 000000	T\$\$KMG= 000000
CDMM 000234R	ERR2 001146R	LEN1 = 000037	R\$\$EXV= 000000	T\$\$LWC= 000000
CONT 000422R	ERR3 001226R	LOW 000244R	R\$\$JS1= 000001	T\$\$RED= 000000
C\$\$CDA= 000002	ERR4 001306R	L\$\$ASG= 000000	R\$\$K11= 000001	T\$\$RNE= 000000
C\$\$CHE= 000000	E\$\$ACT= 000000	L\$\$DRV= 000000	R\$\$LKL= 000001	T\$\$RPR= 000000
C\$\$CKP= 000004	E\$\$DVC= 000000	L\$\$LDR= 000000	R\$\$L11= 000001	T\$\$RST= 000000
C\$\$CSR= 177404	E\$\$LOG= 000000	L\$\$PTO= 000036	R\$\$MDF= 000000	T\$\$RUB= 000000
C\$\$INT= 000000	E\$\$XPR= 000000	L\$\$P11= 000001	R\$\$M11= 000001	T\$\$SMC= 000000
C\$\$ONS= 000001	FIN 001402R	L1 000432R	R\$\$NDC= 000005	T\$\$SYN= 000000
C\$\$ORE= 002022	F\$\$LFP= 000000	MESS1 000062R	R\$\$NDH= 000226	T\$\$TRW= 000000
C\$\$OTM= 000000	F\$\$LVL= 000001	MES1 000033R	R\$\$NDL= 000001	T\$\$UTB= 000000
C\$\$RSH= 177564	GO 000502R	M\$\$CRB= 000124	R\$\$POI= 000000	T\$\$UTO= 000170
C\$\$RUN= 000000	G\$\$EFN= 000000	M\$\$CRX= 000000	R\$\$SND= 000000	T\$\$U5B= 000001
C\$\$SMT= 000000	G\$\$TFP= 000000	M\$\$EIS= 000000	R\$\$11M= 000000	T\$\$VBF= 000000
C\$\$TTY= 177564	G\$\$TSS= 000000	M\$\$EXT= 000000	R\$\$6DF= 000000	T\$\$30P= 000000
DCB 000242R	G\$\$TTK= 000000	M\$\$FCS= 000000	R\$\$611= 000001	UCB 000240R
D\$\$H11= 000001	HIGH 000246R	M\$\$MGE= 000000	S\$\$ECC= 000000	U\$\$MHI= 000000
D\$\$IAG= 000000	H\$\$RTZ= 000074	M\$\$MUF= 000000	S\$\$NM1= 051522	U\$\$MLO= 160000
D\$\$ISK= 000000	IOERR 000166R	M\$\$OVR= 000000	S\$\$NM2= 030530	U\$\$MRN= 170234
D\$\$L11= 000002	IOL = 000032	NAM 000230R	S\$\$NM3= 046461	V\$\$CTR= 000400
D\$\$M11= 000001	IOSB 000224R	NONE 000604R	S\$\$TIM= 000000	V\$\$RSN= 000040
D\$\$PAR= 000000	ID.RVB= ***** GX	N\$\$LDV= 000001	S\$\$TOP= 000000	X\$\$DBT= 000000
D\$\$SHF= 000000	ID.WVB= ***** GX	N\$\$MOV= 000041	S\$\$WLK= 000000	\$ALOCB= ***** GX
D\$\$WCK= 000000	I\$\$RAR= 000000	N\$\$UMR= 000034	S\$\$WPC= 000036	\$COTB = ***** GX
D\$\$YNC= 000000	I\$\$RDN= 000000	PL = 000022	S\$\$WPR= 000005	\$DEACB= ***** GX
D\$\$YNM= 000000	K\$\$AST= 000000	PLACE 000236R	S\$\$YSZ= 022000	\$DEVHD= ***** GX
D.DSP 000012	K\$\$CNT= 172542	PLEN = 000033	TERM 000250R	\$QMCRL= ***** GX
D.LNK 000000	K\$\$CSR= 172540	POOL 000144R	T\$\$ACR= 000000	\$\$\$ARG= 000002

. ABS. 000036 000  
 001410 001  
 ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 10113 WORDS ( 40 PAGES)  
 DYNAMIC MEMORY: 16120 WORDS ( 62 PAGES)  
 ELAPSED TIME: 00:00:14  
 TERM,TERM/--SP=C1,1JEXEMC/ML,C11,10JRSXMC/PA:1,C7,1JTERM



# SYSTEM CRASHES



## SYSTEM CRASHES

### INTRODUCTION

Only certain carefully defined SSTs are allowed in system state. System crashes occur when a software fault is recognized within system state. The processor trap mechanism signals the system crash. CDA is a SYSGEN option which aids the system programmer in tracing system faults. When a fault occurs, the Executive trap handling facility saves the register context in memory, then passes control to the crash routine, which dumps the memory to a disk or tape. The CDA utility may be used to format the dump information into a convenient report.

### OBJECTIVES

1. To analyze a report generated by CDA to determine the cause of a system crash.

### RESOURCES

1. RSX-11M/M-PLUS Crash Dump Analyzer
2. RSX-11M System Lists and Data Structures



## SYSTEM CRASHES

### CRASH PROCESSING

#### Causes of Crashes

- Processor traps in system state
  - Powerfail and parity error traps do not cause crash
  - Other processor traps cause system crash
  - System automatically crashes
- Processor HALTs or enters infinite loop
  - System must be manually crashed
- Manually crashing the system
  - Physical location 40 contains the instruction JMP \$CRASH
  - Processor halted
  - Address 40 loaded
  - Processor restarted

#### Crash Sequences

- Three different crash sequences
  - Initiated by IOT
  - Initiated by EMT or TRAP
  - Initiated by other trap
    - Odd address
    - Illegal instruction
    - Memory management fault
    - Floating-point fault/PIRQ

## Crash Sequences

- IOT

Used when system detects an inconsistent system state

Sequence:

IOT trap vectors to the module SSTSR

R0 - R5 are not saved

Only PS and PC are pushed onto the stack

Jump to \$CRASH in module CRASH is executed

Executive issues IOT only in modules DRDSP and SSTSR

- EMT or TRAP

Results from EMT or TRAP attempt in system state

Sequence:

Directive save operation is performed

Executive issues IOT

Continue as with the IOT

- Other Traps

Traps vector to module SSTSR

Directive save operation is performed

If Memory Management Fault, the status registers SR0, SR1, and SR2 are pushed onto the stack

One word fault code is pushed onto the stack

Byte count of the information saved is pushed onto the stack

Executive jumps to \$CRASH



## SYSTEM CRASHES

### Obtaining a Crash Dump Analysis

- If XDT is present, respond with X to continue with crash
- Registers are printed on the console printer; the system halts
- Mount crash dump volume and press the continue switch
- After memory contents is saved, boot the system
- Run CDA to produce the analysis

Inputs: The copy of memory created at the crash or by a previous execution of CDA

The symbol definition file for the system

Outputs: A listing file containing the analysis of the dump

A binary file which is a copy of the contents of the crash dump volume

- Command Format:

```
>CDA <CR>  
CDA>[listfile/sw],[binaryfile/sw]=symbolfile/STB,  
crash-input[/sw]
```

- Two types of switches can be used

Analysis switches - determine which CDA routines are applied to the input

Function switches - provide control options

## CRASH DUMP ANALYSIS

### Finding the Cause of a System Crash

- Usually requires
  - Output from the CDA utility
  - Map of the operating system
  - Listings and maps of relevant tasks
  
- Common steps in interpreting a crash dump
  - Get KERNEL stack pointer
  - Examine KERNEL stack and \$STKDP for sequence of events (i.e., traps and interrupts)
  - Find PC and PS when trap occurred (from KERNEL stack)
  - Determine APRs in use and find which APR mapped the instruction at which the crash occurred
  - Use the Memory Map to locate the proper partition or region
  - Use the listing and map of the code occupying the region to locate the instruction
  
- System data base may have been corrupted long before crash occurred
  - 'Current Task' may not have caused crash

## SYSTEM CRASHES

Table 10-1 CDA Switches

### CDA Analysis Switches

/ACT Lists the TCBs for active tasks

/CLQ Lists the contents of the clock queue

/DEV Lists the information on all devices in the system

/HDR Lists the headers for all resident tasks

/PCB Lists the PCBs

/POOL Lists the contents of POOL

/STD Lists the contents of the STD

/ALL Lists the output of all analysis routines

/DUMP:a:b  
Lists the contents of memory between the 18-bit addresses a and b

/TASK=name:a:b  
Lists the virtual space of task 'name' between the 16-bit address a and b

Note: All analysis switches are used with the crash-input

### CDA Function Switches

/LIMIT:n Limits output listing to n pages  
Used on the list file

/MEMSIZ:n Saves nK words of memory in a binary file  
Used on the binary file

/STB Identifies the symbol definition file  
Used on the STB file for the system

## SYSTEM CRASHES

### Basic Information Provided in a CDA

#### The KERNEL Stack and \$STKDP

- The KERNEL stack provides a record of the system entrances since system state was entered
- Each trap and interrupt causes task context to be saved on the KERNEL stack
- \$STKDP indicates how many times context has been saved
- Contents of stack can be partitioned by locating the saved PSs

Each PS indicates the start of context saved by a trap or an interrupt

PS on stack located by position on stack

First entry on stack is PS from first trap or interrupt

Next PS will be nine words further on stack if trap or fork occurred

Next PS will be five words further on stack if interrupt occurred

Context pushed because SST contains 11 words plus extra trap specific words

If an SST occurred, it is always the last context on stack

#### Contents of the APRs

- Determines mapping between virtual and physical addresses

KERNEL APRs show mapping when crash occurred

USER APRs show mapping of current user task

# SYSTEM CRASHES

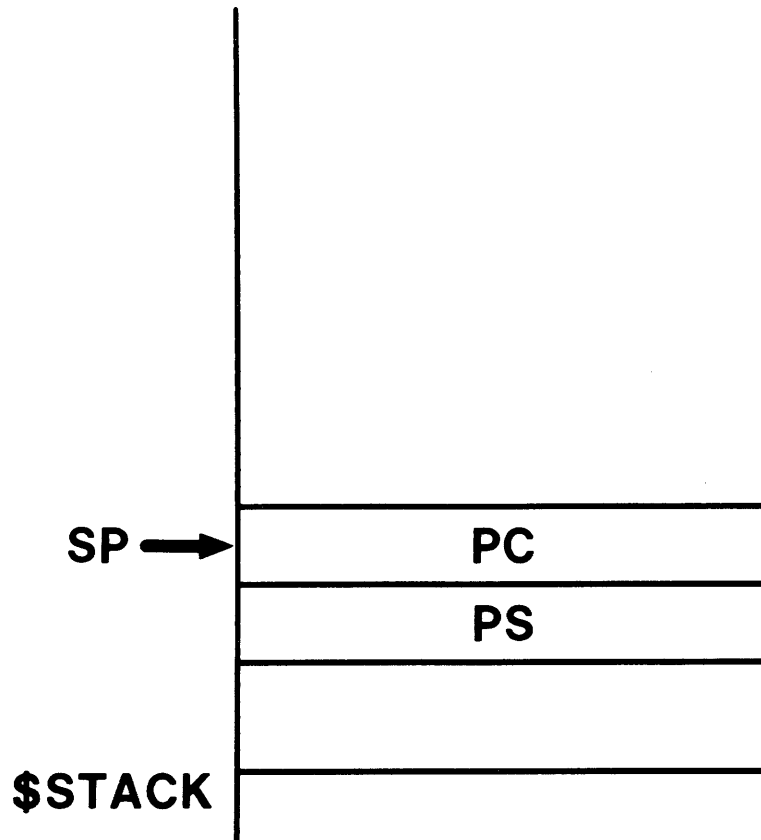


Figure 10-1. The Stack After a System Crash - IOT

SYSTEM CRASHES

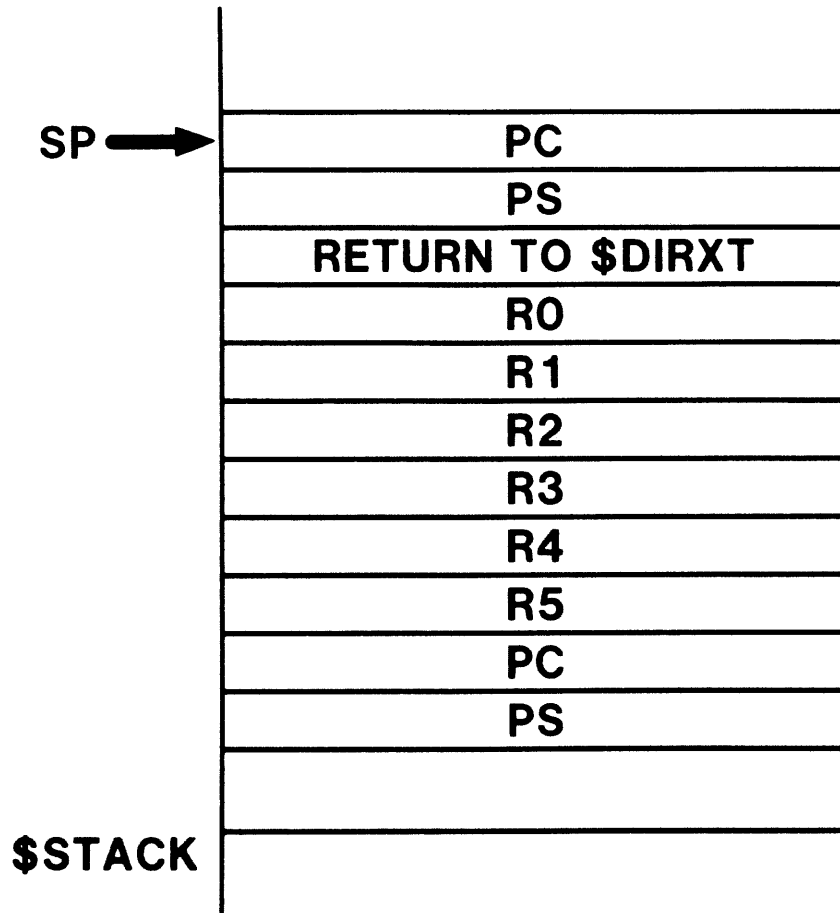


Figure 10-2 The Stack After a System Crash - EMT

# SYSTEM CRASHES

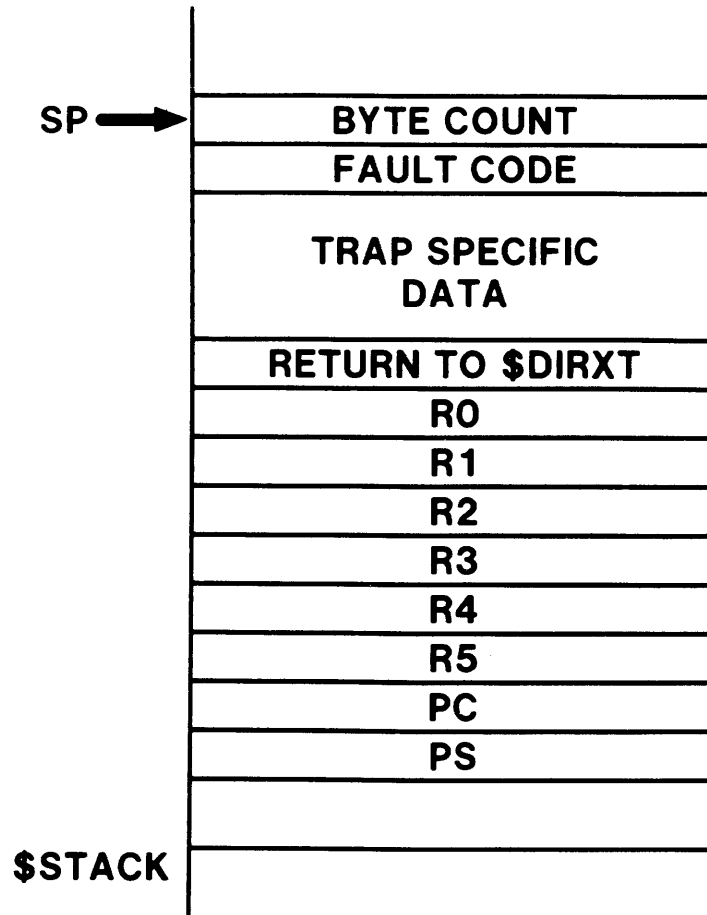


Figure 10-3 The Stack After a System Crash - SST

SYSTEM CRASHES

Table 10-2 Fault Codes for SSTs

Code	Number of Bytes	SST Trap
0	4	Traps through vector 4 (Odd address, etc.)
2	10	Segment fault
4	4	Trace or break-point instruction
6	4	IOT instruction
10	4	Illegal or reserved instruction
11	6	Non-RSX EMT trap instruction
16	14	Floating-point exception (11/40)



## SYSTEM CRASHES

KERNEL Stack Pointer = 000562

Location	Contents	
000556	024552	- PC at Crash
000560	000010	- PS at Crash      SST Information
000562*	000004	- Number of bytes
000564	000000	- SST Code
000566	003120	- Addr of \$DIRXT
000570	000001	- R0
000572	070514	- R1
000574	074460	- R2
000576	053204	- R3      Context at SST
000600	144000	- R4
000602	000000	- R5
000604	121204	- PC
000606	030000	- PS
000610	003126	- ADDR of \$DIRXT
000612	000000	- R0
000614	070514	- R1
000616	074460	- R2      Context at Trap
000620	053200	- R3
000622	144000	- R4
000624	000000	- R5
000626	121206	- PC
000630	170000	- PS

Example 10-1 A Sample KERNEL Stack

## SYSTEM CRASHES

### AN EXAMPLE

#### Situation

- Privileged task TT2 is executing.

Task prompts for terminal number.

User enters terminal number.

System crashes.

CDA prints message:

```
Pool link error at 000040 -- FWD ptr = 000167  
Size = 001736
```

## SYSTEM CRASHES

### Output from CDA

- Current task = RMDEMO

Error indicates

Error caused by another task  
Other task corrupted list of free pool blocks

- Contents of KERNEL stack indicate crash caused by IOT

Consistent with pool pointer = 000167

Note that 000167 is JMP instruction and 001736 is location of \$CRASH

- Any recently or currently active privileged tasks may have caused crash
- Examination of listing of task TT2 shows that task allocates and uses a block of pool

Address of pool stored at location PLACE in task

Task map indicates address of PLACE is 121430

- Dump of task obtained from binary crash file

Value of 054100 stored in PLACE

- Examination of pool dump indicates

Value 000040 entered in 84 words starting at 054100

Allocated block started at 054100 and contained 84 bytes

Error at location 000630 in task: MOV should be MOV B

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81    11:16      PAGE 1  
VOLATILE REGISTERS

AFTER CRASH:    PS=000340    SP(K)=000660    SP(U)=121164

BEFORE CRASH:    PC=141362    PS=030000

R0=137034    R1=137034    R2=131120    R3=000000    R4=000167    R5=137014

MMR0=000001    MMR1=000000    MMR2=002326    MMR3=000060

USER				UNIBUS	MAP
I	S	P	A	C	E
FDR	FAR	D	S	P	A
FDR	FAR	FDR	FAR	FDR	FAR
077506	000000	000000	000000	1	00000000
077406	000200	000000	000000	2	00020000
077406	000400	000000	000000	3	00040000
077406	000600	000000	000000	4	00060000
077406	001000	000000	000000	5	00100000
077506	004732	000000	000000	6	00146200
033006	005132	000000	000000	7	00166200
077406	177600	000000	000000	8	17000000
				9	17000000
				10	17000000
				11	17000000
				12	17000000
				13	17000000
				14	17000000
				15	17000000
				16	17000000
				17	17000000
				18	17000000
				19	17000000
				20	17000000
				21	17000000
				22	17000000
				23	17000000
				24	17000000
				25	17000000
				26	17000000
				27	17000000
				28	17000000
				29	00045100
				30	17760000
				31	00105100

SUPERVISOR			
I	S	P	A
FDR	FAR	D	S
FDR	FAR	FDR	FAR
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000
000000	000000	000000	000000

KERNEL			
I	S	P	A
FDR	FAR	D	S
FDR	FAR	FDR	FAR
077506	000000	000000	000000
077506	000200	000000	000000
077506	000400	000000	000000
077406	000600	000000	000000
077506	001000	000000	000000
077506	004732	000000	000000
077406	005132	000000	000000
077506	177600	000000	000000

Example 10-2    CDA - Volatile Registers

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER  
KERNEL STACK

V4.0

1-NOV-81

11:16

PAGE 2

## KERNEL STACK:

000400	000000	000000	000000	000000	000000	000000	000000	000000
000420	000000	000000	000000	000000	000000	000000	000000	000000
000440	000000	000000	000000	000000	000000	000000	000000	000000
000460	000000	000000	000000	000000	000000	000000	000000	000000
000500	000000	000000	000000	000000	000000	000000	000000	000000
000520	000000	000000	000000	000000	000000	000000	000000	000000
000540	000000	000000	000000	000000	000000	000000	000000	000000
000560	000000	000000	131514	131534	133054	133036	123156	001662
000600	006110	133304	044000	025312	132602	030000	026304	001000
000620	026304	001000	131542	160020	133040	010024	011604	124670
000640	000000	000002	000144	000000	036154	137014	141362	030000
000660	003236	000000	136256	131120	000000	136320	134554	142576
000700	170000							

Example 10-3 CDA - KERNEL Stack

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81    11:16      PAGE 3  
 SYSTEM COMMON

CRASH OCCURRED AT 11:12:27 1-NOV-81

CURRENT TASK = RMDEMO      TCB ADDRESS = 052110

\$SYSID = 31      \$EXSIZ = 120000      \$SYSIZ = 9216./288K      \$SYUIC = [1,54]

\$STKDP = 000000      \$COMEF: <33-48> 000000    <49-64> 000000

SYSTEM NAME = RSX11M      \$NTUIC = [1,54]

LOAD DEVICE = DR0      LBN = 00135325      FILE SIZE = 496.

SYSTEM FEATURE MASK (FIRST WORD) = 013377

BIT SET	MEANING
-----	-----
EXT	22-BIT EXTENDED MEMORY SUPPORT
MUP	MULTI-USER PROTECTION SUPPORT
EXV	20K EXEC SUPPORTED
DRV	LOADABLE DRIVER SUPPORT
PLA	PLAS SUPPORT
CAL	DYNAMIC CHECKPOINT SPACE ALLOCATION
PKT	PREALLOCATION OF I/O PACKETS
EXP	EXTEND TASK DIRECTIVE SUPPORTED
OFF	PARENT/OFFSPRING TASKING SUPPORTED
FDT	FULL DUPLEX TERMINAL DRIVER
DYM	DYNAMIC MEMORY ALLOCATION SUPPORTED

SYSTEM FEATURE MASK (SECOND WORD) = 167400

BIT SET	MEANING
-----	-----
DPR	DIRECTIVE PARTITION SUPPORT
IRR	INSTALL, REQUEST, AND REMOVE TASK SUPPORT
GGF	GROUP GLOBAL EVENT FLAG SUPPORT
RAS	RECEIVE/SEND DATA PACKET SUPPORT
RBN	ROUND ROBIN SCHEDULING SUPPORTED
SWP	EXECUTIVE LEVEL DISK SWAPPING SUPPORTED
STP	EVENT FLAG MASK IS IN THE TCB

SYSTEM FEATURE MASK (THIRD WORD) = 025214

BIT SET	MEANING
-----	-----
CLI	MULTIPLE CLI SUPPORT
EIS	SYSTEM REQUIRES THE EXTENDED INSTRUCTION SET
STM	SYSTEM HAS SET SYSTEM TIME DIRECTIVE
AST	SYSTEM HAS AST SUPPORT

Example 10-4 CDA - System Common  
 (Sheet 1 of 3)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER V4.0 1-NOV-81 11:16 PAGE 4  
 SYSTEM COMMON DUMP

ADDR	LABEL	VALUE	ADDR	LABEL	VALUE	ADDR	LABEL	VALUE
007750		010316	010110	\$PRIHL	003100	010250		000000
		000207		\$PRILL	001130			000000
	\$HEADR	052654		\$PFRSZ	000310			000000
		160400		\$POLBP	000063			000000
	\$COMEF	000000		\$POLFL	000000			000000
		000000		\$PARPT	017320			000000
	\$SYSID	030463		\$CLKHD	045716			000000
		020040		\$COPT	043630			000000
007770	\$TKNPT	110610	010130	\$PARHD	117734	010270		000000
	\$SHFPT	111040		\$LDRPT	117510			000000
	\$CKCNT	172542		\$TSKHD	117510			000000
	\$CKCSR	172540		\$XCOM1	001200			000000
	\$CKLDC	000144		\$XCOM2	001345			000000
	\$SYUIC	000454		\$GGEF	000000			000000
		000000		\$GFTCB	010150			000000
	\$EXSIZ	120000		\$GEFPT	010150		\$ERBAF	000000
010010	\$PWRFL	000000	010150	\$GEFDM	000254	010310		000000
	\$SIGFL	000000		\$IDLCT	000001			000000
	\$LOGHD	000000		\$IDLPT	170017			000000
	\$MCRCB	000000		\$DYPMN	020035			000000
	\$LSTLK	000000			020037			000000
		000003			020037			000000
	\$CRAVL	046464			017440			000000
		000000			017440			000000
010030	\$ACTHD	117510	010170		020040	010330		000000
	\$DICSV	001037		\$BTMSK	000001			000000
	\$TKTCB	052110			000002			000000
	\$LBUIC	000454			000004			000000
	\$ABTIM	041233			000010			000000
	\$RQSCH	000000			000020			000000
	\$STKDP	000000			000040			000000
	\$DEVHD	040746			000100			000000
010050	\$RNDCT	000005	010210		000200	010350		000000
	\$SWPCT	000036			000400		\$ERFID	000000
	\$ERRPT	000000			001000			000000
	\$CFLPT	050740			002000			000000
		000000			004000			000000
		026354			010000			000000
	\$INTCT	177777			020000		\$PRMOD	000106
	\$FRKHD	000000			040000		\$SYSIZ	022000
010070		010066	010230		100000	010370		000000
	\$FMASK	013377		\$ERHEA	000000			135325
		167400			010232			051104
		025214		\$ENTSQ	000000			000760
	\$HFMSK	000003		\$ERRSQ	000000			177777
	\$PTTCB	112314		\$ERFLA	000000			000015
	\$PRISZ	033364			000000		\$DPM	000037
	\$POLST	000401			000000			000030

Example 10-4 CDA - System Common  
 (Sheet 2 of 3)

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER  
SYSTEM COMMON DUMP

V4.0

1-NOV-81 11:16

PAGE 5

ADDR	LABEL	VALUE	ADDR	LABEL	VALUE	ADDR	LABEL	VALUE
010410		000074	010470	\$PKAVL	054034	010550	\$MCRPT	111750
		000074		\$PKNUM	002403			050712
	\$TKPS	000144		\$MXEXT	177777			000000
		000121		\$UMRHD	000000			000040
		000013		\$UMRPT	170200			003404
		000001			000034			005015
		000013		\$UMRWT	000000			000076
		000014			010504			005015
010430		000033	010510	\$TEMPO	111750	010570		041515
	\$TTNS	000063		\$TEMP1	052514			037122
	\$TLMTS	000200		\$TEMP2	130562			000000
		000000		\$TEMP4	000000			
		000014		\$AVRHD	000000			
		000001		\$MOULS	047064			
		000000		\$CXDBL	000000			
		000001		\$SYSNM	051522			
010450		000027	010530		030530			
		000000			046461			
		000073		\$CLICQ	000000			
		000000			010534			
		000073		\$CPTBL	010550			
		000000			052464			
	\$TIKLM	000143			000000			
		000000			000000			

Example 10-4 . CDA - System Common  
(Sheet 3 of 3)



SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER  
SYSTEM COMMON ALPHABETIZED DUMP

V4.0

1-NOV-81 11:16

PAGE 6

\$ABTIM 041233	\$ERLOF 000	\$MOULS 047064	\$STKIP 000000
\$ACTHD 117510	\$ERRPT 000000	\$MXEXT 177777	\$SWPCT 000036
\$AVRHD 000000	\$ERRSQ 000000	\$NTUIC 000454	\$SYSIZ 022000
\$CFLPT 050740	\$EXSIZ 120000	\$PARHD 117734	\$SYSNM 051522
\$CKCNT 172542	\$FMASK 013377	\$PARPT 017320	\$SYUIC 000454
\$CKCSR 172540	\$FRKHD 000000	\$FFRSZ 000310	\$TEMP0 111750
\$CKLDC 000144	\$GEFDM 000254	\$PKAVL 054034	\$TEMP1 052514
\$CLICQ 000000	\$GEFFT 010150	\$PKMAX 005	\$TEMP2 130562
\$CLKHD 045716	\$GFTCB 010150	\$PKNUM 003	\$TEMP4 000000
\$COPT 043630	\$GGEF 000000	\$POLBP 000063	\$TKNPT 110610
\$CPTBL 010550	\$HEADR 052654	\$POLFL 000000	\$TKPS 000144
\$CRAVL 046464	\$HFMSK 000003	\$POLST 000401	\$TKTCB 052110
\$CURPR 341	\$IDLCT 001	\$PRIHL 003100	\$TSKHD 117510
\$CXDBL 000	\$IDLFL 000	\$PRILL 001130	\$TTNS 000063
\$DEVHD 040746	\$IDLPT 170017	\$PRISZ 033364	\$UMRHD 000000
\$DICSV 001037	\$INTCT 177777	\$PRMOD 000106	\$UMRPT 170200
\$DPM 000037	\$LBUIC 000454	\$PTTCB 112314	\$UMRWT 000000
\$ENTSQ 000000	\$LDRPT 117510	\$PWRFL 000000	\$WTCSR 017320
\$ERBAF 000	\$LOGHD 000000	\$RNDCT 000005	\$WTDUM 017320
\$ERFID 000000	\$LSTLK 000000	\$RQSCH 000000	\$XCOM1 001200
\$ERFLA 000	\$MCRCB 000000	\$SHFPT 111040	\$XCOM2 001345
\$ERHEA 000000	\$MCRPT 111750	\$SIGFL 000000	

Example 10-5 CDA - System Common Alphabetized Dump



SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER  
POOL STATISTICS

V4.0

1-NOV-81

11:16

PAGE 8

000000	000000	000000	000000	000000	000000	000000	000000
000000	000000	000000	000000	000000	000000	000000	000000
000000	000000	000000	000000	000000	000000	000000	000000
000000	000000	000000	000000	000000	000000	000000	000000
000000	000000	000000	000000	000000	000000	000000	000000

Example 10-6 CDA - POOL Statistics  
(Sheet 2 of 2)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER V4.0 1-NOV-81 11:16 PAGE 19  
ACTIVE TASKS

TT2  
-----

TCB ADDRESS = 054440 PAR = GEN FCB ADDRESS = 055174  
LOAD ADDRESS = 00440400 LOAD DEVICE = SY0: LBN = 00117403  
PRI = 50. I/O COUNT = 1. UIC = [7,377] TI = TT2:  
MAX SIZE = 000031 EVENT FLAGS = <1-16> 000000 <17-32> 000000

T.STAT:

T.ST2: -CHK WFR  
T.ST3: -PMD REM PRV MCR  
T.TIO: 000000

TCB DUMP:

000000	000000	000462	000000	100100	000000	000000	054452	000000
000020	054456	000000	000000	044256	007754	000000	020001	074000
000040	000062	117403	046166	055174	000031	111404	000000	000000
000060	000031	047102	047102	000000	000000	000000	054532	000000
000100	054536	000000	000001	054462	000000			

Example 10-7 CDA - Active Tasks: TT2

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER  
TASK HEADERS

V4.0

1-NOV-81

11:16

PAGE 30

```

000040 000000 000000 055102 000001 126202 000000 000000 000000
000060 000376 000000 000000 000000 000000 055144 000007 046072
000100 000000 042360 000000 043630 000000 046166 000000 046072
000120 000000 046116 000000 046072 000000 000001 053654 120000
000140 132277 046430 000123 000000 000612 051006 170000 124636
000160 000000 177777 044000 000000 000056 120533 000000
    
```

TT2

```

HEADER ADDRESS = 054554      TCB ADDRESS = 054440
PS=170000      PC=122200
R0=000000  R1=054350  R2=044336  R3=000001  R4=000001  R5=000060  SP=121172
INITIAL PS = 170017  INITIAL PC = 121442  INITIAL SP = 121172
HEADER SIZE = 122.  NO. OF WINDOWS = 1.  NO. OF LUNS = 6.
CURRENT UIC = [7,377]      DEFAULT UIC = [7,377]
H.WND = 054702  H.GARD = 054744  H.VEXT = 000000  H.SPRI = -5.
DSW = 000001  H.FCS = 000000  H.FORT = 000000  H.OVLY = 000000
    
```

LOGICAL UNIT TABLE:

#	DEV	WINDOW	W.CTL	W.FCB	F.FNUM	F.FSEQ	F.STAT	NAC	NLCK
1	SY0:	000000							
2	SY0:	000000							
3	SY0:	000000							
4	SY0:	000000							
5	TIO:	000000							
6	CL0:	000000							

WINDOW BLOCKS:

PAR	VIRT LIMITS	ATT DESC	WND SIZE	OFFSET	1ST PDR	NO.	LAST PDR
GEN	120000 123077	047074	000031	000000	177612	1	014006

HEADER:

```

000000 121172 000172 053254 135600 003777 003777 170017 121442
    
```

Example 10-8 CDA - Tasks Headers: TT2  
(Sheet 1 of 2)

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81      11:16      PAGE 31  
TASK HEADERS

000020	121172	000000	000000	000000	000000	000000	000000	000000
000040	000000	000000	054702	000001	000000	000000	000000	000000
000060	000373	000000	000000	000000	000000	054744	000006	046166
000100	000000	046166	000000	046166	000000	046166	000000	046072
000120	000000	046116	000000	000001	055174	120000	123077	047074
000140	000031	000000	000612	014006	170000	122200	000060	000001
000160	000001	044336	054350	000000	000000			

Example 10-8 CDA - Tasks Headers: TT2  
(Sheet 2 of 2)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER V4.0 1-NOV-81 11:16 PAGE 82  
 POOL DUMP

```

053260 * 114250 * 053276 * 000001 * 115404 !XQ M5F A X2D!!( >V !
053270 * 000000 * 000106 * 114250 * 000000 ! A0 XQ !!! F ( !
053300 * 000401 * 115404 * 000000 * 001000 ! FQ X2D L2!!! !
053310 * 000016 * 121350 * 000000 * 000000 ! N ZBX !!! h" !
053320 * 000401 * 000000 * 000000 * 000000 ! FQ !!! !
053330 * 114730 * 121246 * 000000 * 000000 !XXX Z B !!X &" !
053340 * 066117 * 131574 * 000000 * 000000 !QMG ... !!01!3 !
053350 * 000033 * 000000 * 000000 * 000000 ! $ !!! !
053360 053640 000044 111404 041740 !N 2 6 WT6 J4P!! W$ `C!
053370 000000 000000 000001 111426 ! A WUN!!! !
053400 053640 000024 000000 000000 !N 2 T !!! W !
053410 000403 000000 053640 000010 ! FS N 2 H!! W !
053420 000000 000000 * 120412 * 000212 ! YOZ CR!! !
053430 * 143107 * 000000 * 000454 * 000454 !1.9 GT GT!!GF , , !
053440 * 170017 * 120750 * 120412 * 000000 !8PD Y6H YOZ !!! Ph! ! !
053450 * 000000 * 000000 * 000000 * 000000 ! !!! !
053460 * 000000 * 000000 * 000000 * 000000 ! !!! !
053470 * 053552 * 000002 * 143030 * 000000 !M9R B 1$2 !!JW F !
053500 * 143142 * 000000 * 000373 * 000000 !1/Z FK !!bF C !
053510 * 000000 * 000000 * 000000 * 053634 ! N .!! W!
053520 * 000006 * 046166 * 000000 * 043630 ! F LIN KRH!! vL G!
053530 * 000000 * 041006 * 000000 * 046166 ! JVV LIN!! B vL!
053540 * 000000 * 046072 * 000000 * 046116 ! LG4 LHN!! :L NL!
053550 * 000000 * 000002 * 046674 * 120000 ! B LQT YX !! <M !
053560 * 144277 * 052360 * 000243 * 000000 !2D1 MWX DC !!?HPT# !
053570 * 001212 * 021006 * 115404 * 160000 ! PJ EQO X2D 53X!! " \!
053600 * 175577 * 053270 * 000156 * 000147 ! IW M5 B0 BW!! (8Vn s !
053610 * 000616 * 066402 * 170000 * 121016 ! IB QQZ 8P Y7F!! m P " !
053620 * 000000 * 000000 * 143107 * 000060 ! 1.9 AH!! GF0 !
053630 * 000060 * 120431 * 000000 * 000000 ! AH Y1A !!0 !
053640 054224 000014 000000 000000 !NF6 L !! X !
053650 000403 000000 * 054374 * 000062 ! FS NIT AJ!! !X2 !
053660 * 026226 * 000000 * 055174 * 115274 !GEN NSD X0L!! , !Z< !
053670 * 004076 * 000123 * 000000 * 000123 !ALO BC BC!!> S S !
053700 * 000000 * 111404 * 000050 * 054750 ! WT6 A NOP!! ( HY!
053710 * 000000 * 046430 * 046430 * 000000 ! LMP LMP !! M M !
053720 * 000000 * 000062 * 000000 * 131574 ! AJ ...!! 2 !3!
053730 * 007537 * 000000 * 053732 * 000000 !BRO NBJ !!_ ZW !
053740 * 053736 * 177776 * 000001 * 044000 !NBN 8N A KT2!!W~ H!
053750 * 054440 * 100400 * 020000 * 050000 !NJP TYX ED2 L2 !! Y P!
053760 * 000062 * 142440 * 046142 * 115274 ! AJ 1UX LH4 X0L!!2 EbL< !
053770 * 000306 * 054440 * 000000 * 000000 ! DB NJP !!F Y !
054000 * 000306 * 000000 * 054002 * 000000 ! DB NCV !!F X !
054010 * 000000 * 000000 * 054012 * 000000 ! NCR !! X !
054020 * 054016 * 000000 * 000003 * 053742 !NCV C NBR!! X bw!
054030 * 000000 * 000000 + 055240 + 000044 ! NT 6!! Z$ !
054040 + 000020 + 000000 + 044416 + 000400 ! P K$V FP!! I !
054050 + 135154 + 005103 + 140054 + 000000 !/3D AY$ 0/6 !!1:C ,@ !
054060 + 005077 + 140144 + 000070 + 000000 !AYW 01L AP !!? d@B !
054070 + 000000 + 000000 + 000000 + 000000 ! !! !
054100 * 000040 * 000040 * 000040 * 000040 ! 2 2 2 2!! !
    
```

[ABOVE LINE REPEATED 9. TIMES]

```

054220 * 000040 * 000040 000040 000040 ! 2 2 2 2!! !
054230 000040 000040 000040 000040 ! 2 2 2 2!! !
    
```

Example 10-9 CDA - POOL Dump  
 (Sheet 1 of 2)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER V4.0 1-NOV-81 11:16 PAGE 83  
 POOL DUMP

```

054240      000040      000040      000040      000040      ! 2 2 2 2!!      !
054250      000040      000040      000040      000040      ! 2 2 2 2!!      !
054260      000040      000040      * 000040      * 000040      ! 2 2 2 2!!      !
054270      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054300      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054310      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054320      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054330      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054340      * 000040      * 000040      * 000040      * 000040      ! 2 2 2 2!!      !
054350      * 170000      * 125200      * 127542      * 000000      !8F $KH .BR !! P *b/ !
054360      * 000004      * 130034      * 131100      * 000110      ! D .GD .T2 A2!! 0@2H !
054370      * 000000      * 000000      * 000000      * 000773      ! L$!!      C !
054400      * 111404      * 055050      * 044000      * 000540      !WT6 NQ KT2 H2!! (Z H' !
054410      * 121246      * 004110      * 140046      * 000000      !Z B AM 0/0 !!&'H &@ !
054420      * 000005      * 140111      * 000056      * 000000      ! E 00Y AF !! I@. !
054430      * 000000      * 100000      * 000000      * 053654      ! TSH NAD!! ,w!
054440      * 000000      * 000462      * 000000      * 100100      ! GZ TT2!! 2 @ !
054450      * 000000      * 000000      * 054452      * 000000      ! NJZ !! *Y !
054460      * 054456      * 000000      * 000000      * 044256      !NJ0 KYF!! .Y .H!
054470      * 007754      * 000000      * 020001      * 074000      !BU6 ED3 SH !!1 x!
054500      * 000062      * 117403      * 046166      * 055174      ! AJ YQ$ LIN NSD!!2 vL!Z!
054510      * 000031      * 111404      * 000000      * 000000      ! Y WT6 !! !
054520      * 000031      * 047102      * 047102      * 000000      ! Y LT4 LT4 !! BNBH !
054530      * 000000      * 000000      * 054532      * 000000      ! NK4 !! ZY !
054540      * 054536      * 000000      * 000001      * 054462      !NK8 A NJ4!!CY 2Y!
054550      * 000000      * 001000      * 121172      * 000172      ! L2 Y94 CB!! z"z !
054560      * 053254      * 135600      * 003777      * 003777      !M4. 0 AKG AKG!! ,V ; !
054570      * 170017      * 121442      * 121172      * 000000      !8FD ZDB Y94 !! P"#z" !
054600      * 000000      * 000000      * 000000      * 000000      ! !! !
054610      * 000000      * 000000      * 000000      * 000000      ! !! !
054620      * 054702      * 000001      * 000000      * 000000      !NNR A !!BY !
054630      * 000000      * 000000      * 000373      * 000000      ! FK !! C !
054640      * 000000      * 000000      * 000000      * 054744      ! NOL!! dY!
054650      * 000006      * 046166      * 000000      * 046166      ! F LIN LIN!! vL vL!
054660      * 000000      * 046166      * 000000      * 046166      ! LIN LIN!! vL vL!
054670      * 000000      * 046072      * 000000      * 046116      ! LG4 LHN!! :L NL!
054700      * 000000      * 000001      * 055174      * 120000      ! A NSD YX !! :Z !
054710      * 123077      * 047074      * 000031      * 000000      !ZW9 LT. Y !!?&<N !
054720      * 000612      * 014006      * 170000      * 122200      ! I4 C30 BP ZL2!! P $!
054730      * 000060      * 000001      * 000001      * 044336      ! AH A A KZN!!0 CH!
054740      * 054350      * 000000      * 000000      * 120424      !NI Y06!!hX !!
054750      * 120502      * 000176      * 140354      * 135600      !Y2B CF 04. 0 !!B!~ 1@ ;!
054760      * 000454      * 000454      * 170017      * 121714      ! GT GT BFD ZHL!! , PL#!
054770      * 120506      * 000000      * 000000      * 000000      !Y2F !!F! !
055000      * 000000      * 000000      * 000000      * 000000      ! !! !
055010      * 000000      * 000000      * 055102      * 000001      ! NQZ A!! BZ !
055020      * 126202      * 000000      * 000000      * 000000      ! $XB !! , !
055030      * 000376      * 000000      * 000000      * 000000      ! FN !!~ !
055040      * 000000      * 055144      * 000007      * 046072      ! NRT G LG4!! dZ :L!
055050      * 000000      * 042360      * 000000      * 043630      ! KAH KRH!! PD G!
055060      * 000000      * 046166      * 000000      * 046072      ! LIN LG4!! vL :L!
055070      * 000000      * 046116      * 000000      * 046072      ! LHN LG4!! NL :L!
055100      * 000000      * 000001      * 053654      * 120000      ! A NAD YX !! ,w !
055110      * 132277      * 046430      * 000123      * 000000      !.61 LMP BC !!?4 MS !
055120      * 000612      * 051006      * 170000      * 124636      ! I4 MDB BP $EV!! R P )!
055130      * 000000      * 177777      * 044000      * 000000      ! 80 KT2 !! H !
    
```

Example 10-9 CDA - POOL Dump  
 (Sheet 2 of 2)



```

1          .TITLE  DUMP
2          ;+
3          ;
4          ;
5          THIS TASK ASKS THE USER FOR A TERMINAL NUMBER AND A
6          COMMAND LINE.  IT THEN PASSES THE COMMAND TO MCR
7          AS IF HAD ORIGINATED AT THE SPECIFIED TERMINAL.  IT
8          PERFORMS THIS TASK BY USING SYSTEM SUBROUTINES, $ALOCB
9          AND $QMCR, TO ALLOCATE A BLOCK FROM POOL AND PASS IT
10         TO MCR.
11         ;
12         ;
13         THE TASK MUST BE BUILT PRIVILEGED AND MAP TO THE EXECUTIVE.
14         ;
15         TO ASSEMBLE:
16         ;
17         >MAC TERM=[1,1]EXEMC/ML,[11,10]RSXMC/PA:1,[YOUR UIC]TERM
18         ;
19         TO BUILD:
20         ;
21         >TKB TERM/PR:5=TERM,[1,54]RSX11M.STB/SS
22         ;+
23         .MCALL  EXIT$S,QIOW$S,DCBDF$
24         DCBDF$
25         ;
26         ;
27         TERMINAL MESSAGES
28         ;
29         PRMT:  .ASCII  <12><15>/ENTER A TERMINAL NUMBER: /      ;PROMPT
30         000000    012    015    105
31         000003    116    124    105
32         000006    122    040    101
33         000011    040    124    105
34         000014    122    115    111
35         000017    116    101    114
36         000022    040    116    125
37         000025    115    102    105
38         000030    122    072    040
39         28      000033    PLEN  =      .--PRMT          ;LENGTH OF PROMPT
40         29      000033    105    116    124    MES1:  .ASCII  /ENTER A COMMAND FOR MCR/
41         000036    105    122    040
42         000041    101    040    103
43         000044    117    115    115
44         000047    101    116    104
45         000052    040    106    117
46         000055    122    040    115
47         000060    103    122
48         30      000027    LENT1 =      .--MES1
49         31      000062    116    125    115    MES1:  .ASCII  /NUMBER IS NOT OCTAL, TRY AGAIN!/
50         000065    102    105    122
51         000070    040    111    123
52         000073    040    116    117
53         000076    124    040    117
54         000101    103    124    101
55         000104    114    054    040
56         000107    124    122    131
57         000112    040    101    107
58         000115    101    111    116
59         000120    041
60         32      000037    LEN1  =      .--MESS1

```

Example 10-10 Listing of Task TT2 (DUMP)  
(Sheet 1 of 5)

```

33 000121    124    105    122  ERMES: .ASCII /TERMINAL NOT FOUND!/
    000124    115    111    116
    000127    101    114    040
    000132    116    117    124
    000135    040    106    117
    000140    125    116    104
    000143    041
34      000023
35 000144    116    117    040  ERL      =      .-ERMES
    000147    120    117    117  POOL:   .ASCII /NO POOL AVAILABLE!/
    000152    114    040    101
    000155    126    101    111
    000160    114    101    102
    000163    114    105    041
36      000022
37 000166    111    057    117  PL      =      .-POOL
    000171    040    105    122  IOERR: .ASCII !I/O ERROR ON COMMAND INPUT!
    000174    122    117    122
    000177    040    117    116
    000202    040    103    117
    000205    115    115    101
    000210    116    104    040
    000213    111    116    120
    000216    125    124
38      000032
39      IOL      =      .-IOERR
40      .EVEN
41      ;
42      ;      PROGRAM DATA
43      ;
44      BUF:    .BLKB  4      ;BUFFER FOR TERMINAL NUMBER
45      IOSB:   .BLKW  2      ;I/O STATUS BLOCK
46      NAM:    .ASCII  /TT/  ;TERMINAL NAME
47      ERRCNT: .WORD   -1    ;ERROR INDICATOR
48      COMM:   .WORD   0      ;ADDRESS OF COMMAND LINE IN POOL
49      FLACE:  .WORD   0      ;ADDRESS OF POOL BLOCK
50      UCB:    .WORD   0      ;SAVED UCB ADDRESS
51      DCB:    .WORD   0      ;SAVED DCB ADDRESS
52      LOW:    .WORD   0      ;SAVED LOW UNIT NUMBER
53      HIGH:   .WORD   0      ;SAVED HIGH UNIT NUMBER
54      ;
55      ;      BEGINNING OF CODE
56      ;
57      TERM:   QIOW$S  #IO.WVB,#S,#1,,,<#PRMT,#PLEN,#40>  #PROMPT
58      QIOW$S  #IO.RVB,#S,#1,#IOSB,,<#BUF,#4> #GET 'TT' NUMBER
59      MOV     IOSB+2,R3    ;SAVE CHARACTER COUNT
60      MOV     #BUF,R0     ;SET UP FOR CALL TO CONVERSION
61      CLR     R2          ;ROUTINE - FROM ASCII TO
62      CALL    %COTB      ; BINARY(OCTAL)
63      ; R1 WILL CONTAIN CONVERTED NUMBER
64      ; R2 WILL CONTAIN TERMINATOR
65      TST     R2         ;TEST FOR ERROR
66      BEQ     CONT      ;IF NOT CONTINUE
67      JMP     ERR1      ;GO TO ERROR ROUTINE
68      MOV     #SWSTK,BACK ;SWITCH TO SYSTEM STATE
69      MOV     ##DEVHD,R0 ;PICK UP LISTHEAD FOR DCB LIST
70      MOV     (R0),R0    ;GO TO NEXT DCB
    BEQ     GO          ;IF NONE FINISH UP

```

Example 10-10 Listing of Task TT2 (DUMP)  
(Sheet 2 of 5)



```

128          ;          ROUTINE TO HANDLE BAD TERMINAL NUMBER
129          ;
130 001060    ERR1:  QIOW$S  #IO.WVB,#5,#1,,,,<#MESS1,#LEN1,#40>  ;PRINT MESSAGE
131 001132    MOV      #BUF,R0          ;GET INPUT BUFFER ADDRESS
132 001136    012700 000220' CLEAR: CLR      (R0)+          ;CLEAR BUFFER
133 001140    077302    SOB      R3,CLEAR          ;R3 CONTAINS CHARACTER COUNT
134 001142    000167 177102    JMP      TERM          ;TRY AGAIN
135          ;
136          ;          ROUTINE TO HANDLE NON-EXISTENT TERMINAL
137          ;
138 001146    ERR2:  QIOW$S  #IO.WVB,#5,#1,,,,<#ERMES,#ERL,#40>  ;PRINT MESSAGE
139 001220    EXIT$S          ;EXIT
140          ;
141          ;          ROUTINE TO HANDLE POOL ALLOCATION FAILURE
142          ;
143 001226    ERR3:  QIOW$S  #IO.WVB,#5,#1,,,,<#POOL,#FL,#40>  ;PRINT MESSAGE
144 001300    EXIT$S          ;EXIT
145          ;
146          ;          ROUTINE TO HANDLE I/O ERRORS ON COMMAND INPUT
147          ;          THE POOL BLOCK MUST BE DEALLOCATED!
148          ;
149 001306    ERR4:  QIOW$S  #IO.WVB,#5,#1,,,,<#IOERR,#IOL,#40>  ;PRINT MESSAGE
150 001360    CALL    $SWSTK,FIN          ;;SWITCH TO SYSTEM STATE
151 001364    016700 176646    MOV      PLACE,R0          ;;GET ADDRESS OF BLOCK
152 001370    012701 000124    MOV      #B4,,R1          ;;SET BLOCK LENGTH
153 001374    CALL    $DEACB          ;;DEALLOCATE BLOCK
154 001400    RETURN          ;;LEAVE SYSTEM STATE
155 001402    FIN:          ;BACK IN USER STATE
156 001402    EXIT$S          ;EXIT
157          000250' .END      TERM

```

Example 10-10 Listing of Task TT2 (DUMP)  
(Sheet 4 of 5)

DUMP MACRO M1200 01-NOV-81 11:09 PAGE 3-4  
SYMBOL TABLE

A\$\$BIO= 000000	D.MSK 000014	K\$\$IEN= 000113	FRMT 000000R	T\$\$BTW= 000000
A\$\$BRT= 000000	D.NAM 000004	K\$\$LDC= 000144	F\$\$BFR= 000063	T\$\$BUF= 000000
A\$\$CHK= 000000	D.FCB 000034	K\$\$TFS= 000144	F\$\$CTL= 000000	T\$\$CCA= 000000
A\$\$CLI= 000004	D.UCB 000002	LD\$CD = 000000	F\$\$FRS= 000310	T\$\$CCO= 000000
A\$\$CPS= 000000	D.UCBL 000010	LD\$DD = 000000	F\$\$GMX= 000000	T\$\$CFW= 000000
A\$\$NSI= 000000	D.UNIT 000006	LD\$DK = 000000	F\$\$HIL= 003100	T\$\$CTR= 000000
A\$\$PRI= 000000	D.VCAN= 000002	LD\$DL = 000000	F\$\$LAS= 000000	T\$\$CUP= 000000
A\$\$TRP= 000000	D.VDEB= 177776	LD\$DM = 000000	F\$\$LQL= 001130	T\$\$C11= 000001
BACK 000504R	D.VINI= 000000	LD\$DR = 000000	F\$\$OFF= 000000	T\$\$ESC= 000000
BACK2 000606R	D.VOUT= 000004	LD\$DS = 000000	F\$\$P45= 000000	T\$\$GMC= 000000
BACK3 001052R	D.VWVF= 000006	LD\$DT = 000000	F\$\$RFL= 000000	T\$\$GTS= 000000
BUF 000220R	ERL = 000023	LD\$LP = 000000	F\$\$RTY= 000000	T\$\$HFF= 000000
B\$\$LV1= 030463	ERMES 000121R	LD\$MM = 000000	F\$\$SRF= 000000	T\$\$HLD= 000000
B\$\$LV2= 020040	ERRCNT 000232R	LD\$TT = 000000	Q\$\$OPT= 000005	T\$\$J16= 000001
CLEAR 001136R	ERR1 001060R	LENT1 = 000027	R\$\$DER= 000000	T\$\$KMG= 000000
COMM 000234R	ERR2 001146R	LEN1 = 000037	R\$\$EXV= 000000	T\$\$LWC= 000000
CONT 000422R	ERR3 001226R	LOW 000244R	R\$\$JS1= 000001	T\$\$REDI= 000000
C\$\$CDA= 000002	ERR4 001306R	L\$\$ASG= 000000	R\$\$K11= 000001	T\$\$RNE= 000000
C\$\$CHE= 000000	E\$\$ACT= 000000	L\$\$DRV= 000000	R\$\$LKL= 000001	T\$\$RPR= 000000
C\$\$CKP= 000004	E\$\$DVC= 000000	L\$\$LDR= 000000	R\$\$L11= 000001	T\$\$RST= 000000
C\$\$CSR= 177404	E\$\$LOG= 000000	L\$\$PTD= 000036	R\$\$MOF= 000000	T\$\$RUB= 000000
C\$\$INT= 000000	E\$\$XPR= 000000	L\$\$P11= 000001	R\$\$M11= 000001	T\$\$SMC= 000000
C\$\$ONS= 000001	FIN 001402R	L1 000432R	R\$\$NDC= 000005	T\$\$SYN= 000000
C\$\$ORE= 002022	F\$\$LFP= 000000	MESS1 000062R	R\$\$NDH= 000226	T\$\$TRW= 000000
C\$\$OTM= 000000	F\$\$LVL= 000001	MES1 000033R	R\$\$NDL= 000001	T\$\$UTB= 000000
C\$\$RSH= 177564	GO 000502R	M\$\$CRB= 000124	R\$\$PDI= 000000	T\$\$UTO= 000170
C\$\$RUN= 000000	G\$\$EFN= 000000	M\$\$CRX= 000000	R\$\$SND= 000000	T\$\$U5B= 000001
C\$\$SMT= 000000	G\$\$TFP= 000000	M\$\$EIS= 000000	R\$\$11M= 000000	T\$\$VBF= 000000
C\$\$TTY= 177564	G\$\$TSS= 000000	M\$\$EXT= 000000	R\$\$60F= 000000	T\$\$30P= 000000
DCB 000242R	G\$\$TTK= 000000	M\$\$FCS= 000000	R\$\$611= 000001	UCB 000240R
D\$\$H11= 000001	HIGH 000246R	M\$\$MGE= 000000	S\$\$ECC= 000000	U\$\$MHI= 000000
D\$\$IAG= 000000	H\$\$RTZ= 000074	M\$\$MUF= 000000	S\$\$NM1= 051522	U\$\$MLO= 160000
D\$\$ISK= 000000	IQERR 000166R	M\$\$OVR= 000000	S\$\$NM2= 030530	U\$\$MRN= 170234
D\$\$L11= 000002	IOL = 000032	NAM 000230R	S\$\$NM3= 046461	V\$\$CTR= 000400
D\$\$M11= 000001	IOSE 000224R	NONE 000604R	S\$\$TIM= 000000	V\$\$RSN= 000040
D\$\$PAR= 000000	IO.RVB= ***** GX	N\$\$LIV= 000001	S\$\$TOP= 000000	X\$\$DBT= 000000
D\$\$SHF= 000000	IO.WVB= ***** GX	N\$\$MOV= 000041	S\$\$WLK= 000000	\$ALOCB= ***** GX
D\$\$WCK= 000000	I\$\$RAR= 000000	N\$\$UMR= 000034	S\$\$WPC= 000036	\$COTB = ***** GX
D\$\$YNC= 000000	I\$\$RDN= 000000	PL = 000022	S\$\$WFR= 000005	\$DEACB= ***** GX
D\$\$YNM= 000000	K\$\$AST= 000000	PLACE 000236R	S\$\$YSZ= 022000	\$DEVHD= ***** GX
D.DSP 000012	K\$\$CNT= 172542	PLEN = 000033	TERM 000250R	\$QMCR= ***** GX
D.LNK 000000	K\$\$CSR= 172540	POOL 000144R	T\$\$ACR= 000000	\$\$\$ARG= 000002

. ABS. 000036 000  
001410 001  
ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 10113 WORDS ( 40 PAGES)  
DYNAMIC MEMORY: 16120 WORDS ( 62 PAGES)  
ELAPSED TIME: 00:00:13  
DUMP, DUMP/-SP=[1,1]EXEMC/ML,[11,10]RSXMC/PA:1,[7,377]DUMP

Example 10-10 Listing of Task TT2 (DUMP)  
(Sheet 5 of 5)

Partition name : GEN  
 Identification : M4.0  
 Task UIC : [7,377]  
 Stack limits: 120172 121171 001000 00512.  
 PRG xfr address: 121442  
 Task attributes: FR  
 Total address windows: 1.  
 Task image size : 800. words  
 Task address limits: 120000 123007  
 R-W disk blk limits: 000002 000005 000004 00004.

\*\*\* Root segment: DUMP

R/W mem limits: 120000 123007 003010 01544.  
 Disk blk limits: 000002 000005 000004 00004.

Memory allocation synopsis:

Section	Title	Ident	File
. BLK.:(RW,I,LCL,REL,CON)	121172 001504 00836.		
	121172 001410 00776.	DUMP	M4.0 DUMP.OBJ#2
\$\$RESL:(RO,I,LCL,REL,CON)	122676 000112 00074.		

Global symbols:

ID.RVB 010400 ID.WVB 011000 \$ALOCB 011346 \$DEACB 011614 \$DEVHD 010046 \$QMCRL 021432

\*\*\* Task builder statistics:

Total work file references: 850.  
 Work file reads: 0.  
 Work file writes: 0.  
 Size of core pool: 20506. words (80. pages)  
 Size of work file: 768. words (3. pages)

Elapsed time:00:00:04

Example 10-11 Map of Task TT2

# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81    11:39      PAGE 9  
 TASK DUMP

## TASK DUMP OF TT2

---

TCB ADDRESS = 054440      HEADER ADDRESS = 054554

WINDOW BLOCKS:

PAR	VIRT LIMITS	ATT DESC	WND SIZE	OFFSET	1ST PDR	NO.	LAST PDR
GEN	120000 123077	047074	000031	000000	177612	1	014006

WINDOW #1 -- TASK VIRTUAL LIMITS 120000-123077

---

PHYSICAL STARTING ADDRESS = 00440400

---

120000	000000	000172	053254	135600	!	CB M4. 0	!!	z ,V	!
120010	003777	003777	170017	121442	!	AKG AKG BPO ZDB!!		P*#!	!
120020	121172	000000	000000	000000	!	Y94		!!z*	!
120030	000000	000000	000000	000000	!			!!	!
120040	000000	000000	054702	000000	!		NNR	!!	BY
120050	000000	000000	000000	000000	!			!!	!
120060	000000	000000	000000	000000	!			!!	!
120070	000000	054744	000006	046166	!	NOL	F	LIN!!	dY vL!
120100	000000	046166	000000	046166	!	LIN		LIN!!	vL vL!
120110	000000	046166	000000	046072	!	LIN		LG4!!	vL !L!
120120	000000	046116	000000	000001	!	LHN		A!!	NL
120130	115274	120000	123077	000000	!	XOL YX	ZW9	!!<	?&
120140	000031	000000	000612	014006	!	Y		I4 C30!!	!
120150	004070	000001	000000	135600	!	ALX	A	0	!!B
120160	053254	000000	100100	000000	!	M4.		TT2	!! ,V @
120170	000000	000000	000000	000000	!			!!	!

[ABOVE LINE REPEATED 60. TIMES]

121140	000000	006003	010400	000005	!	A65 B.2		E!!	!
121150	000001	000000	000000	054104	!	A		ND6!!	DX!
121160	000120	000000	000000	000000	!	B		!!P	!
121170	000000	006412	047105	042524	!	BCR	LT7	KC.!!	ENTE!
121200	020122	020101	042524	046522	!	EF4	EFQ	KC. LN4!!	R A TERM!
121210	047111	046101	047040	046525	!	LUA	LHA	LT LN7!!	INAL NUM!
121220	042502	035122	042440	052116	!	KCJ	IMJ	KBP MSV!!	BER: ENT!
121230	051105	040440	041440	046517	!	MFU	JP2	J/X LN1!!	ER A COM!
121240	040515	042116	043040	051117	!	JQ7	J7F	KH2 MF1!!	MAND FOR!
121250	046440	051103	052516	041115	!	LMX	MFS	MY8 JXM!!	MCRNUMB!

Example 10-12 CDA of Task TT2  
 (Sheet 1 of 4)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER V4.0 1-NOV-81 11:39 PAGE 10  
 TASK DUMP

121260	051105	044440	020123	047516	!MFU K. EF5 L\$V!!ER IS NO!
121270	020124	041517	040524	026114	!EF6 J01 JRD GCT!!T OCTAL,!
121300	052040	054522	040440	040507	!MRP NKZ JF2 JQ1!! TRY AGA!
121310	047111	052041	051105	044515	!LUA MRQ MFU K/E!!IN!TERMI!
121320	040516	020114	047516	020124	!JQ8 EF. L\$V EF6!!NAL NOT!
121330	047506	047125	020504	047516	!L\$N LUM EL6 L\$V!!FOUND!NO!
121340	050040	047517	020114	053101	!L22 L\$W EF. M2A!! POOL AV!
121350	044501	040514	046102	020505	!K.3 JQ6 LHB EL7!!AILABLE!!
121360	027511	020117	051105	047522	!GVY EF1 MFU L\$Z!!I/O ERRO!
121370	020122	047117	041440	046517	!EF4 LUG J/X LN1!!R ON COM!
121400	040515	042116	044440	050116	!JQ7 J7F K. L38!!MAND INF!
121410	052125	000063	000000	000000	!MS/ AK !!UT3 !
121420	000000	052124	000000	054104	! MS. ND6!! TT DX!
121430	054100	044336	044212	000002	!ND2 KZN KXJ B!!QX^H H !
121440	000021	005046	005046	005046	! Q AX8 AX8 AX8!! & & & !
121450	012746	000040	012746	000033	!CTF 2 CTF \$!!f & f !
121460	012746	121172	005046	005046	!CTF Y94 AX8 AX8!!f z"& & !
121470	005046	112716	000001	012746	!AX8 W80 A CTF!!& N f !
121500	000005	012746	011000	012746	! E CTF B5H CTF!! f f !
121510	006003	104377	005046	005046	!A65 U61 AX8 AX8!! & & !
121520	005046	005046	012746	000004	!AX8 AX8 CTF D!!& & f !
121530	012746	121412	005046	012746	!CTF ZCR AX8 CTF!!f #& f !
121540	121416	005046	112716	000001	!ZCV AX8 W80 A!! #& N !
121550	012746	000005	012746	010400	!CTF E CTF B.2!!f f !
121560	012746	006003	104377	016703	!CTF A65 U61 D0S!!f C !
121570	177626	012700	121412	005002	! 50 CSH ZCR AXB!! @ # !
121600	004767	001004	005702	001402	!AW1 L6 A5J SJ!!w B !
121610	000167	000436	104376	121676	! B9 GF U60 ZG8!!w ~ >#!
121620	012700	010046	011000	001422	!CSH BWN B5H SZ!!@ & !
121630	026760	177566	000004	001372	!GN 48 D SB!!P-v z !
121640	116067	000006	177570	116067	!X91 F 5 X91!!7 x 7 !
121650	000007	177564	020167	177560	! G 46 EG1 42!! t w P !
121660	003361	010067	177546	062767	!ADQ BW1 4V PLW!!a 7 f we!
121670	000001	177530	000207	005767	! A 4H CO A6W!! X w !
121700	177522	001402	000167	000430	! 4B SJ B9 G!!R w !
121710	016700	177520	016002	000002	!DOP 4 DSJ B!!R P !
121720	010104	166704	177510	016005	!BXD BA. 32 DSM!!D DmH !
121730	000010	070504	060502	010267	! H RD6 OVR BZ9!! DgBa7 !
121740	177470	012767	177777	177454	! 3F CTW 80 3D!!8 w , !
121750	104376	122000	012701	000124	!U60 ZIX CSI BD!!~ \$A T !
121760	004767	067362	103404	005267	!AW1 Q0B UXD A.W!!w rn 7 !
121770	177432	010067	177432	000207	! 2Z BW1 2Z CO!! 7 !
122000	005767	177420	001402	000167	!A6W 2F SJ B9!!w w !
122010	000406	012700	000124	016701	! FV CSH BD D0Q!! @ T A !
122020	177406	012721	000040	077003	! 2F CSY 2 TFS!! Q ~!
122030	016767	177374	177370	062767	!D11 16 12 PLW!!w !~x~we!
122040	000004	177362	005046	005046	! D 1Z AX8 AX8!! r~& & !
122050	005046	012746	000040	012746	!AX8 CTF 2 CTF!!& f f !
122060	000027	012746	121225	005046	! W CTF Z U AX8!! f "& !
122070	005046	005046	112716	000001	!AX8 AX8 W80 A!!& & N !
122100	012746	000005	012746	011000	!CTF E CTF B5H!!f f !
122110	012746	006003	104377	005067	!CTF A65 U61 AY0!!f 7 !
122120	177274	005067	177272	005046	! OL AY0 OJ AX8!!<~7 :~& !
122130	005046	005046	005046	012746	!AX8 AX8 AX8 CTF!!& & & f !
122140	000120	016746	177260	005046	! B D1N 0 AX8!!F f 0~& !
122150	016746	177242	005046	112716	!D1N /Z AX8 W80!!f ~& N !

Example 10-12 CDA of Task TT2  
 (Sheet 2 of 4)



# SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81      11:39      PAGE 11  
 TASK DUMP

```

122160 000001 012746 000005 012746 ! A CTF E CTF!! f f !
122170 010400 012746 006003 104377 !B.2 CTF A65 U61!! f !
122200 103002 000167 000272 105767 !UQZ B9 DZ V01!! w ; w !
122210 177204 002002 000167 000260 ! .6 YZ B9 DP!! ~ w 0 !
122220 104376 122244 016701 177200 !U60 ZM. D0Q .2!!~ $$A ~ !
122230 016761 177176 000002 004767 !D1Y .0 B AW1!!g ~ w !
122240 077170 000207 012746 000463 !TIP CO CTF G$!!x~ f 3 !
122250 104377 005046 005046 005046 !U61 AX8 AX8 AX8!! & & & !
122260 012746 000040 012746 000037 !CTF 2 CTF 1!!f f !
122270 012746 121254 005046 005046 !CTF ZAD AX8 AX8!!f ,"& & !
122300 005046 112716 000001 012746 !AX8 W80 A CTF!!& N f !
122310 000005 012746 011000 012746 ! E CTF B5H CTF!! f f !
122320 006003 104377 012700 121412 !A65 U61 CSH ZCR!! @ # !
122330 005020 077302 000167 177102 !AXP TKJ B9 $J!! B~w B~ !
122340 005046 005046 005046 012746 !AX8 AX8 AX8 CTF!!& & & f !
122350 000040 012746 000023 012746 ! 2 CTF S CTF!! f f !
122360 121313 005046 005046 005046 !ZA5 AX8 AX8 AX8!!K"& & & !
122370 112716 000001 012746 000005 !W80 A CTF E!!N f !
122400 012746 011000 012746 006003 !CTF B5H CTF A65!!f f !
122410 104377 012746 000463 104377 !U61 CTF G$ U61!! f 3 !
122420 005046 005046 005046 012746 !AX8 AX8 AX8 CTF!!& & & f !
122430 000040 012746 000022 012746 ! 2 CTF R CTF!! f f !
122440 121336 005046 005046 005046 !ZBN AX8 AX8 AX8!!^"& & & !
122450 112716 000001 012746 000005 !W80 A CTF E!!N f !
122460 012746 011000 012746 006003 !CTF B5H CTF A65!!f f !
122470 104377 012746 000463 104377 !U61 CTF G$ U61!! f 3 !
122500 005046 005046 005046 012746 !AX8 AX8 AX8 CTF!!& & & f !
122510 000040 012746 000032 012746 ! 2 CTF Z CTF!! f f !
122520 121360 005046 005046 005046 !ZB2 AX8 AX8 AX8!!P"& & & !
122530 112716 000001 012746 000005 !W80 A CTF E!!N f !
122540 012746 011000 012746 006003 !CTF B5H CTF A65!!f f !
122550 104377 104376 122574 016700 !U61 U60 ZSD D0P!! ~ !Z@ !
122560 176646 012701 000124 004767 ! WN CSI BD AW1!!&A T w !
122570 067022 000207 012746 000463 !QXR CO CTF G$!! n f 3 !
122600 104377 012702 000012 000402 !U61 CSJ J FR!! B !
122610 012702 000010 004567 000144 !CSJ H ATW BT!!B w d !
122620 005001 112005 122705 000040 !AXA W$M ZT7 2!! EZ !
122630 001774 122705 000011 001771 ! YT ZT7 I YQ!!! EZ y !
122640 162705 000060 120502 103010 !60U AH Y2B UQ2!!Ee0 B! !
122650 010004 010200 004767 000016 !BVT BYX AW1 N!! w !
122660 010400 060501 112005 000764 !B.2 OVR W$M LT!! Aa t !
122670 116002 177777 000207 010046 !X8R 80 CO BWN!! & !
122700 012746 000021 005000 006000 !CTF Q AX A62!!f !
122710 006001 103002 066600 000002 !A63 UQZ QT2 B!! m !
122720 005316 003371 000415 012746 !A/F ADY F/ CTF!!N y f !
122730 000020 010146 005001 006300 ! P BX8 AXA BAX!! f @ !
122740 006101 020116 103402 161601 !ASR EFO UXB 6PA!!A N c !
122750 005200 005366 000002 003367 !A$H AOF B ADW!! v w !
122760 022626 000207 010446 010346 !F V CO B/O B.F!! z & f !
122770 010546 016605 000006 004736 !B1N D.7 F AWF!!f ~ !
123000 012603 012604 012605 000207 !CQ$ CQ. CQ/ CO!! !
123010 000000 000000 000000 000000 ! !! !
123020 000000 000000 000000 000000 ! !! !
123030 000000 000000 000000 000000 ! !! !
123040 000000 000000 000000 000000 ! !! !
123050 000000 000000 000000 000000 ! !! !
    
```

Example 10-12 CDA of Task TT2  
 (Sheet 3 of 4)

SYSTEM CRASHES

RSX-11M CRASH DUMP ANALYZER      V4.0      1-NOV-81    11:39      PAGE 12  
TASK DUMP

123060	000000	000000	000000	000000	!	!!	!
123070	000000	000000	000000	000000	!	!!	!

[END OF ANALYSIS OUTPUT]

Example 10-12 CDA of Task TT2  
(Sheet 4 of 4)

# **DIRECTIVE PROCESSING**



## DIRECTIVE PROCESSING

### INTRODUCTION

Many tasks require activities, such as I/O, which cannot be easily performed within a user task. To provide the facilities for these activities without requiring privileged tasks and extensive knowledge of the inner workings of the operating system, RSX-11M provides a set of system services called Executive directives.

Executive directives provide a simple interface to these services. This interface is through system macros for the MACRO-11 programmer and system subroutines for the FORTRAN programmer. The interface also provides a completion code for error checking.

### OBJECTIVES

1. List the steps in processing an Executive directive.
2. Perform the steps necessary to add a user written directive to the system.

### RESOURCES

1. RSX-11M System Lists and Data Structures
2. RSX-11M/M-PLUS Executive Reference Manual



## THE USER TASK INTERFACE

- MACRO-11 task uses macros to invoke directives
- Three types of macros
  - \$-form
  - \$C-form
  - \$S-form
- FORTRAN tasks call subroutines
- Directive Parameter Block (DPB) used to pass data to system
- Result of directive execution indicated by
  - Directive Status Word (DSW)
  - Processor Status Word
    - Set to indicate failure
    - Clear to indicate success

### Directive Parameter Block

- Data structure contained within the user task
- Contains parameters needed to execute the directive
  - Directive identification code (DIC)
  - Other parameters as needed
  - Length depends on DIC, can be variable
- Location of DPB
  - In task data area
    - In user selected PSECT
    - In PSECT \$DPB\$\$
  - On task stack
- Directive identification code always odd whole number

DIRECTIVE PROCESSING

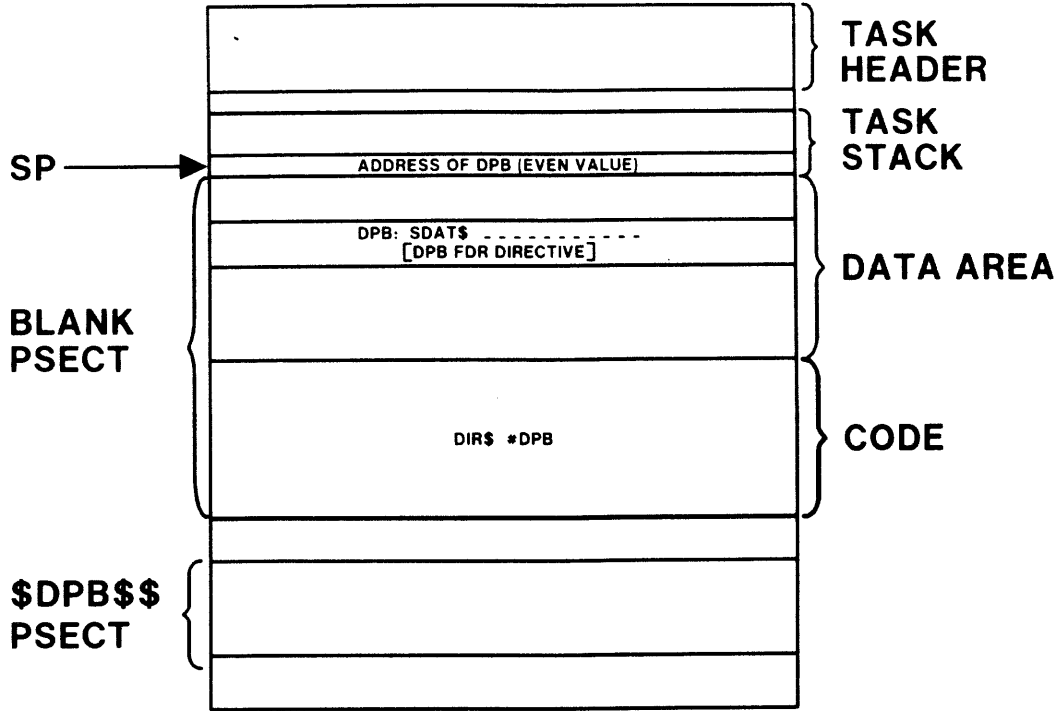


Figure 11-1 Directive Macros: '\$' Form

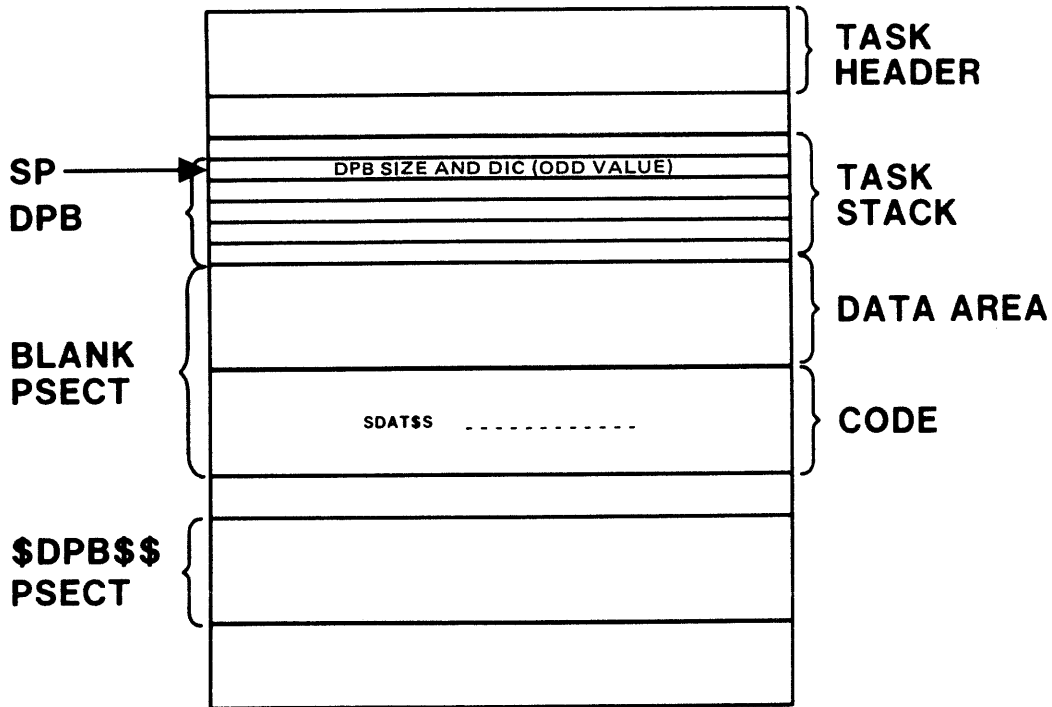


Figure 11-1 Directive Macros: '\$S' Form



DIRECTIVE PROCESSING

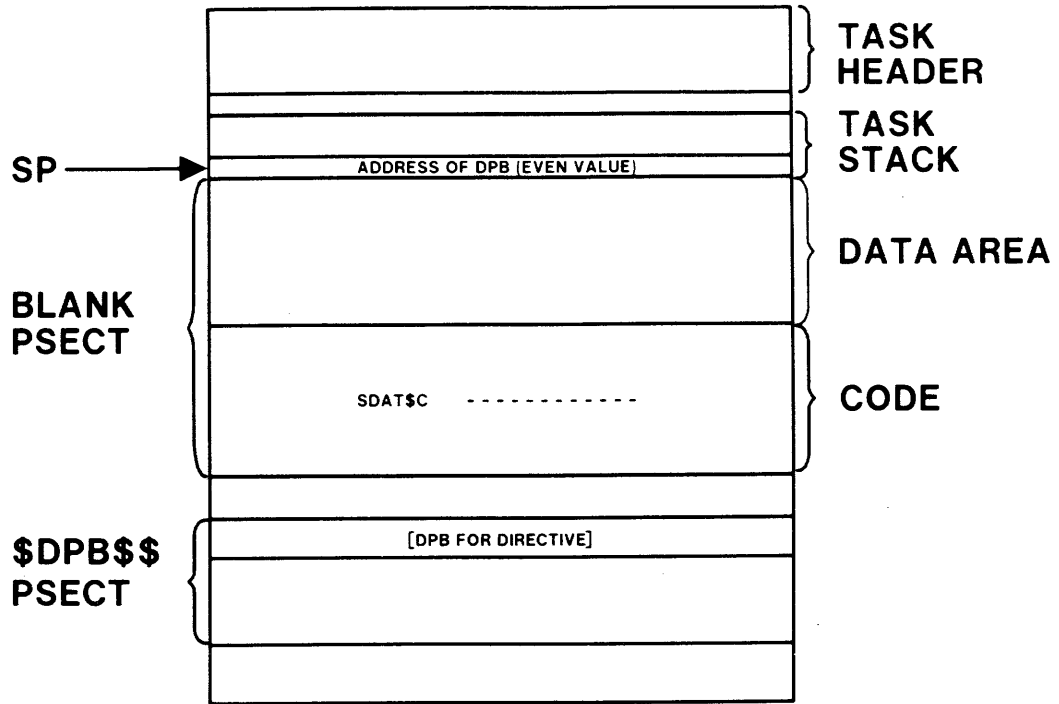


Figure 11-1 Directive Macros: '\$C' Form

DIRECTIVE PROCESSING

---

'\$' FORM

---

SEND:	SDAT\$	TASKB,BUF,5	SEND:	.BYTE	71.,5
				.RAD50	/TASKB/
				.WORD	BUF
	DIR\$	#SEND,ERR		.WORD	5
				MOV	#SEND,-(SP)
				EMT	377
				BCC	+.6
				JSR	PC,ERR

---

'\$C' FORM

---

				.PSECT	\$DPB\$\$
			\$\$\$	=	.
				.BYTE	71.,5
				.RAD50	/TASKB/
	SDAT\$C	TASKB,BUF,5,PROG1,ERR		.WORD	BUF
				.WORD	5
				.PSECT	PROG1
				MOV	\$\$\$\$,-(SP)
				EMT	377
				BCC	+.6
				JSR	PC,ERR

---

'\$\$' FORM

---

TASKB:	.RAD50	/TASKB/	TASKB:	.RAD50	/TASKB/
				MOV	#5,-(SP)
				MOV	#BUF,-(SP)
				MOV	TASKB+2,-(SP)
	SDAT\$\$	#TASKB,#BUF,#5,ERR		MOV	TASKB,-(SP)
				MOV	(PC)+,-(SP)
				.BYTE	71.,5
				EMT	377
				BCC	+.6
				JSR	PC,ERR

---

Example 11-1 Macro Expansions for SEND DATA

DIRECTIVE PROCESSING

<b>DPB SIZE IN WORDS</b>	<b>DIC</b>
<b>PARAMETER 1</b>	
<b>PARAMETER 2</b>	
<b>PARAMETER N</b>	

Figure 11-2 The Directive Parameter Block

### Directive Status Word

- Executive returns a status code in the DSW
- In general, success is denoted by a status of +1
- The Set/Clear Event Flag directives use
  - 0 to indicate success and flag clear
  - 2 to indicate success and flag set
- An error is indicated by a negative status
- Value stored at location \$DSW in the task header (in task region)
- In FORTRAN, value returned in calling argument

## DIRECTIVE PROCESSING

### THE DIRECTIVE DISPATCHER

- EMT trap causes entry to module DRSUB at \$EMTRP
- Module DRDSP is mapped using KERNEL APR5 and control passes to module DRDSP at \$DRDSP
- Routine \$DRDSP distinguishes between directive calls, calls to \$SWSTK and non-RSX EMT traps
- For directive calls
  - KERNEL APR6 is used to map
    - WDB or RDB if PLAS directive
    - DPB otherwise
  - Directive processing routine is called
- To process a request to switch to kernel mode, a jump to the Executive routine \$SWSTK is executed
- For non-RSX EMT traps, a jump to \$EMSST in SSTSR is executed

### The Directive Dispatch Table

- Contains entry for each directive
  - Address of service routine
  - 'Flags byte'
  - Length in words (For variable length = 0)
- Assembled in one of two possible forms
  - Single table form
    - Two words per possible directive
  - Double table form
    - One byte per possible directive
    - Two words per existing directive
- The form which uses the least space is automatically chosen
  - If less than 75 percent of directives exist, use the two table structure
  - If 75 percent or more of the possible directives exist, use the one table structure

DIRECTIVE PROCESSING

QIO\$	1.	ADDRESS OF \$DRQIO	2.
		FLAGS BYTE   DPB LENGTH	4.
QIOW\$	3.	ADDRESS OF \$DRQIO	6.
		FLAGS BYTE   DPB LENGTH	8.
GLUN\$	5.	ADDRESS OF \$DRGLI	10.
		FLAGS BYTE   DPB LENGTH	12.
ALUN\$	7.	ADDRESS OF \$DRASG	14.
		FLAGS BYTE   DPB LENGTH	16.
ALTP\$	9.	0	18.
		0   0	20.
RQST\$	11.	ADDRESS OF \$DRREQ	22.
		FLAGS BYTE   DPB LENGTH	24.
UNUSED	13.	0	26.
		0   0	28.
UNUSED	15.	0	30.
		0   0	32.
RUN\$	17.	ADDRESS OF \$DRRUN	34.
		FLAGS BYTE   DPB LENGTH	36.
UNUSED	19.	0	40.
		0   0	42.
SRRAS\$	21.	ADDRESS OF \$DRRRA	44.
		FLAGS BYTE   DPB LENGTH	46.
MRKT\$	23.	ADDRESS OF \$DRMKT	50.
		FLAGS BYTE   DPB LENGTH	52.

Single Table Form

TABLE 1

TABLE 2

QIO\$	1.	2.	ADDRESS OF \$DRQIO	2.
QIOW\$	3.	6.	FLAGS BYTE   DPB LENGTH=12.	4.
GLUN\$	5.	10.	ADDRESS OF \$DRQIO	6.
ALUN\$	7.	14.	FLAGS BYTE   DPB LENGTH=12.	8.
ALTP\$	9.	0	ADDRESS OF \$DRGLI	10.
RQST\$	11.	18.	FLAGS BYTE   DPB LENGTH=3.	12.
UNUSED	13.	0	ADDRESS OF \$DRASG	14.
UNUSED	15.	0	FLAGS BYTE   DPB LENGTH=4.	16.
RUN\$	17.	22.	ADDRESS OF \$DRREQ	18.
UNUSED	19.	0	FLAGS BYTE   DPB LENGTH=7.	20.
SRRAS\$	21.	26.	ADDRESS OF \$DRRUN	22.
MRKT\$	23.	30.	FLAGS BYTE   DPB LENGTH=11.	24.
CSRQ\$	25.	34.	ADDRESS OF \$DRRRA	26.
CMKT\$	27.	38.	FLAGS BYTE   DPB LENGTH=2.	28.
EXST\$	29.	42.	ADDRESS OF \$DRMKT	30.
CLEF\$	31.	46.	FLAGS BYTE   DPB LENGTH=5.	32.
SETF\$	33.	50.		

Double Table Form

Figure 11-3 The Directive Dispatch Table

# DIRECTIVE PROCESSING

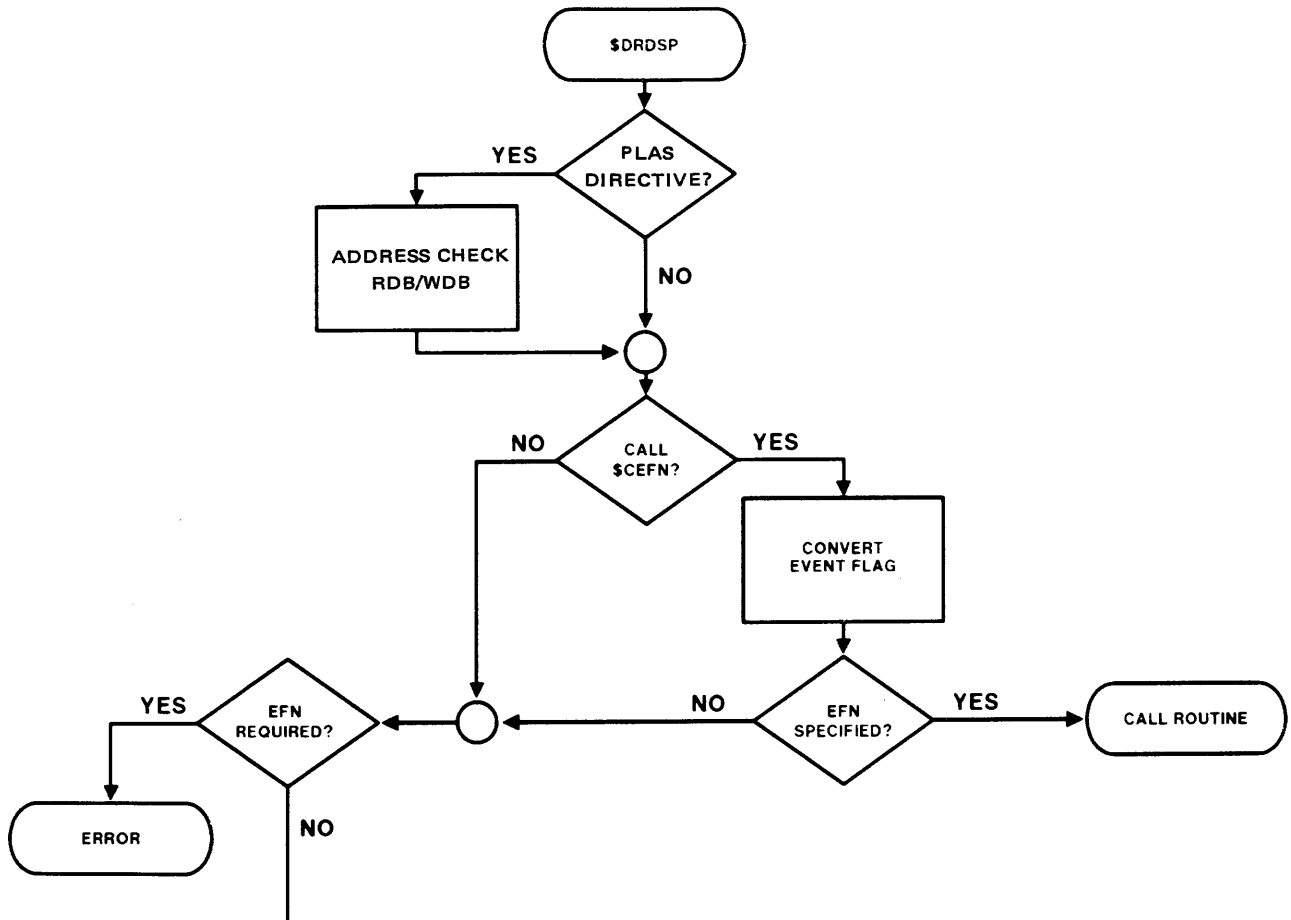


Figure 11-4 Processing in DRDSP  
(Sheet 1 of 2)

DIRECTIVE PROCESSING

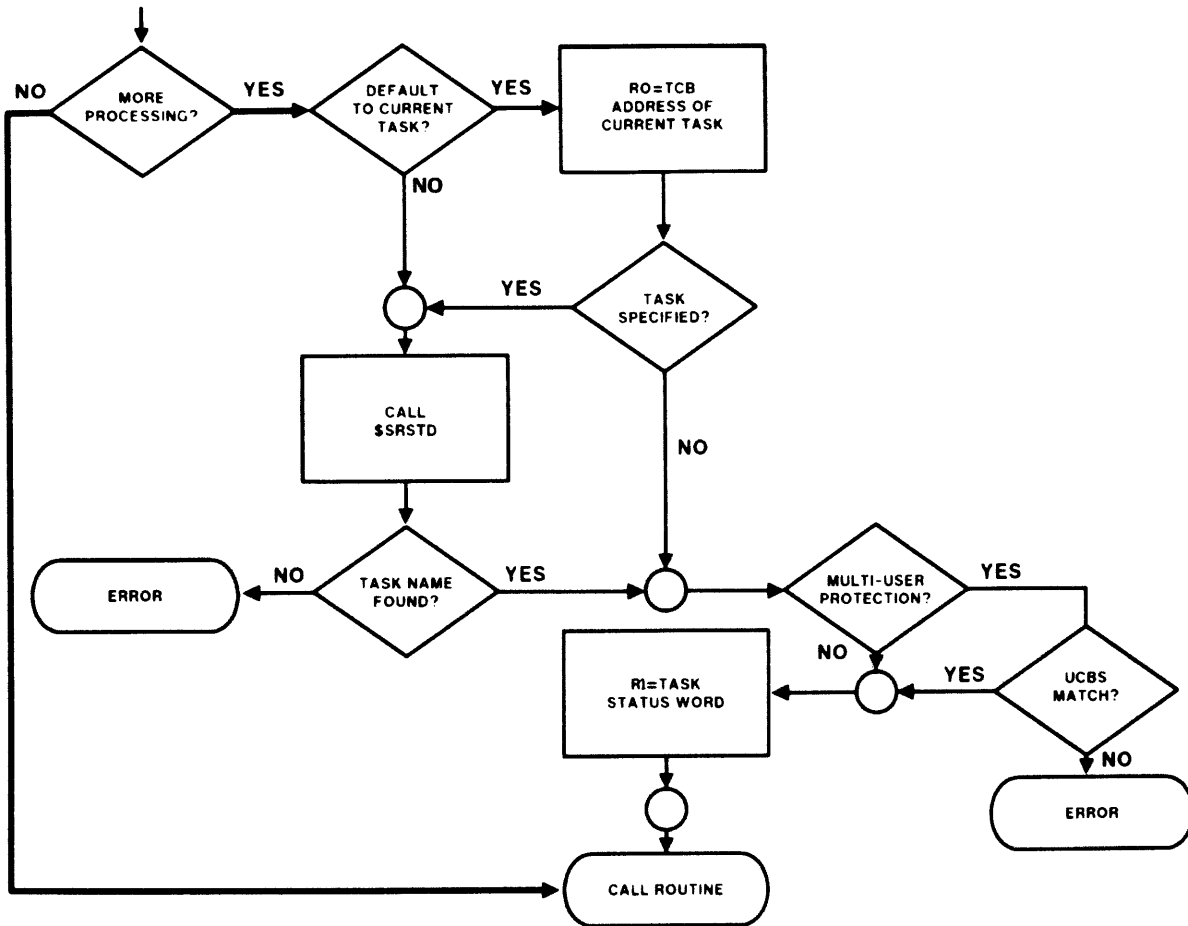


Figure 11-4 Processing in DRDSP  
(Sheet 2 of 2)



## DIRECTIVE PROCESSING ROUTINES

### The Interface

- Directive processing routine is called with registers loaded as in Table 11-1
- Flag byte in directive dispatch table determines processing
  - ACHKDB - Address PLAS definition block
  - CEFNCNCL - Convert the event flag
  - GEFUSE - Do not increment group global use count
  - CEFNMNT - Event flag must be specified
  - DFCTSK - Task name defaults to current task
  - MUPCHK - Perform multi-user protection check
  - SRSTCL - Call \$SRSTD to find TCB in STD
- Bits set in flag byte determine contents of R0 and R1
  - If CEFNCNCL specified
    - R0 - Event flag mask word
    - R1 - Address of event flag
  - If SRSTCL specified
    - R0 - TCB address of specified task
    - R1 - Address of status word in TCB

# DIRECTIVE PROCESSING

Table 11-1 Register Usage

Register	Contents
R5	Address of the TCB of the current task
R4	Address of the header of the current task
R3	Address of the next word in the DPB
R2	Address of the second task status word of the current task
R1	Depends on directive
R0	Depends on directive

## DIRECTIVE PROCESSING

### The Directive Commons

- Most directive processing code removed from Executive
  - Increases available DSR
- Two directive commons, EXCOM1 and EXCOM2
  - Existence of commons determined at SYSGEN
  - Kernel I-space APR 5 used to map directive commons
  - Location of processing routine indicated by low order bit of address of routine in DDT
- Module DRSUB
  - Is in the Executive
  - Always mapped
  - Contains the location \$EMTRP
    - Calls \$DIRSV
    - Maps to DRDSP which is in EXCOM1
    - Contains coroutines \$MPXC1 and \$MPXC2 which are used to map EXCOM1 and EXCOM2

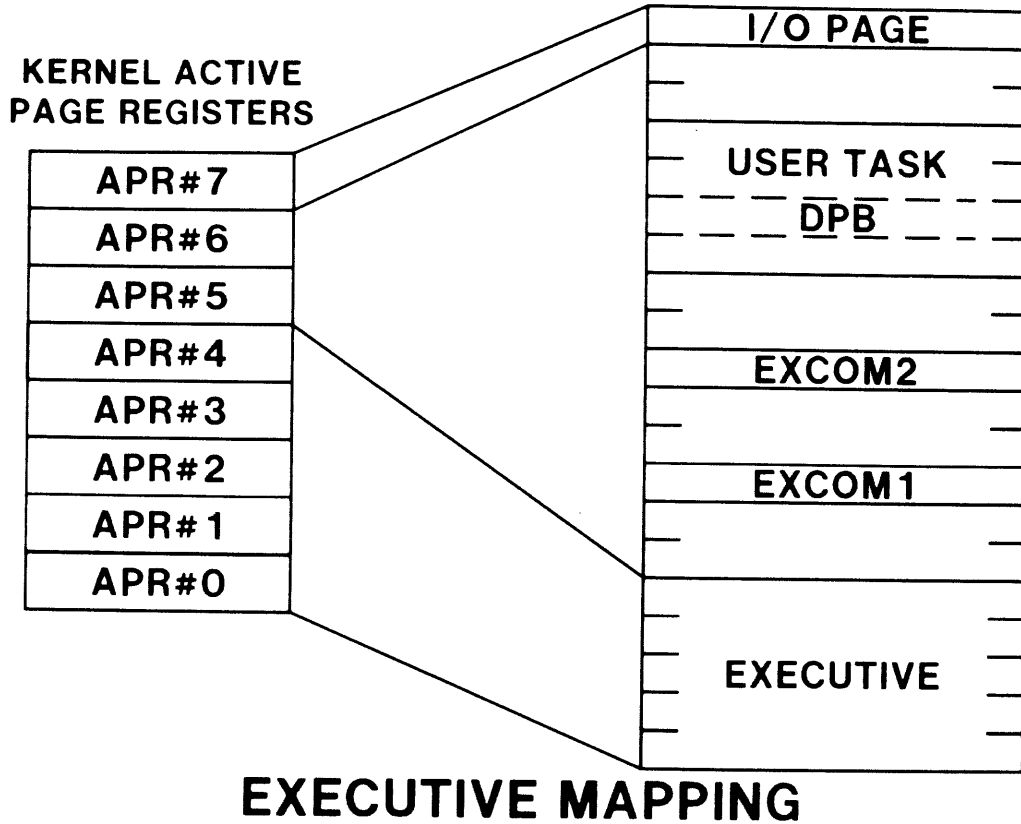


Figure 11-5 The Directive Commons: Standard Executive Mapping

DIRECTIVE PROCESSING

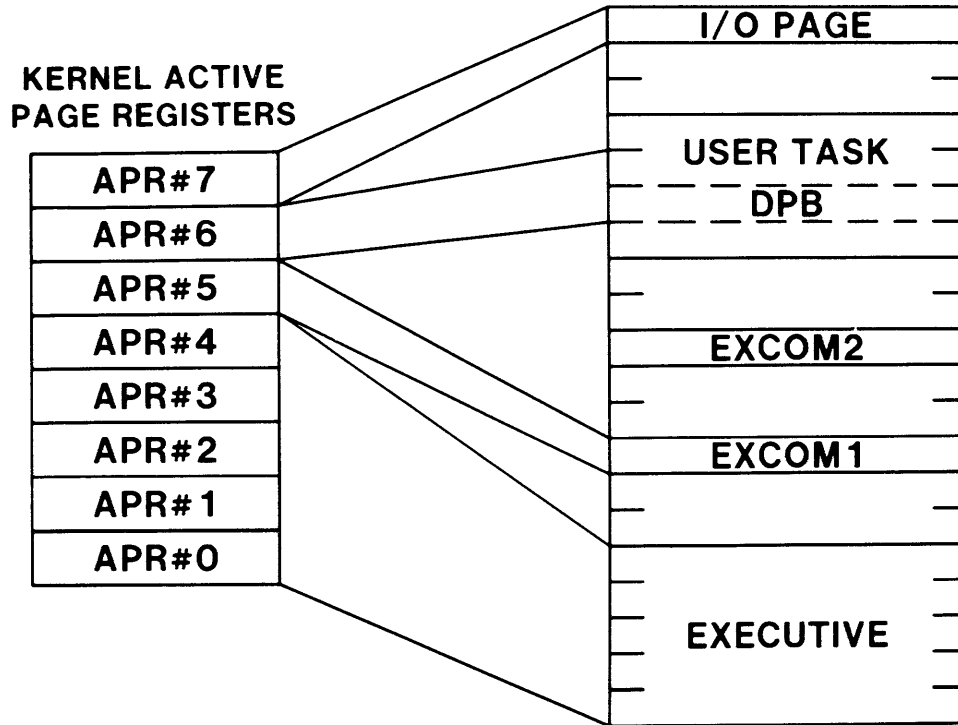


Figure 11-5 The Directive Commons: Mapping to Reference EXCOM1

DIRECTIVE PROCESSING

Table 11-2 Directive Processing Modules

Module	Location	Routines
DRABO	EXCOM1	\$DRABO
DRASG	EXCOM2	\$DRATX
DRATP	EXCOM2	
DRATX	EXCOM1	
DRCIN	EXCOM2	\$DRCIN, \$DISIN
DRCLI	EXCOM1	\$DRCLI, \$STCLI, \$STCLI
DRCMT	EXCOM1	
DRDAR	EXCOM1	\$DRDAR, \$DREAR
DRDCP	EXEC	\$DRDCP, \$DRECP
DRDSP	EXCOM1	\$TRTRP, \$DRTRP, \$EMTRP, \$DRDSP, \$DRATP
DREIF	EXEC	\$DREIF, \$DREXT, \$DREX1
DREXP	EXCOM2	\$DREXP
DRGCL	EXCOM1	\$GRGCL, \$RLMCB, \$RLCIB
DRGEF	EXCOM2	\$DRCRE, \$DRELE, \$UNLCK, \$GTGEF
DRGLI	EXCOM1	\$DRGLI
DRGPP	EXCOM1	\$DRGPP
DRGSS	EXCOM1	\$DRGSS
DRGTK	EXCOM1	\$DRGTK
DRGTP	EXCOM2	\$DRGTP
DRMAP	EXCOM2	\$DRCRW, \$DRELW, \$DRMAP, \$DRUNM, \$DRSRF, \$DRRRF \$DRGMX
DRMKT	EXCOM1	\$DRMKT, \$DRRUN
DRPUT	EXCOM1	\$DRREX, \$CAAST, \$DRFEX, \$DRPUT, \$DRRRA, \$DRRCV
DRQIO	EXCOM1	\$DRQIO
DRRAS	EXCOM1	\$DRRCS, \$DRREC, \$DRSND
DRREG	EXCOM2	
DRRES	EXCOM1	\$DRUNS, \$DRRES, \$DRSTP, \$DRSPN
DRSED	EXCOM1	\$DRCEF, \$DRRAF, \$DRSEF, \$DRSTS, \$DRSTL, \$DRWFL \$DRWFS
DRSMG	EXCOM2	
DRSPW	EXCOM1	
DRSST	EXCOM1	\$DRSDV, \$DRSTV
DRSUB	EXEC	\$ELGEF, \$DEAGF, \$SRGEF, \$DRDSE, \$TKWSE, \$DRWSE \$MPXC1, \$MPXC2, \$DETRG, \$CITFR, \$DRQRQ, \$SRCCQ \$GTUCB, \$STCLI, \$FNCLI, \$TRTRP, \$EMTRP, \$OTHRI \$DRATP

**Send/Receive Processing**

- Used to transfer a 13-word data packet to a specified task
- Routine \$DRSND in module DRRAS used to send data
- Routine \$DRREC in module DRRAS used to receive data
- Steps in sending/receiving

An 18-word send/receive data block is allocated in DSR

Link word for receive queue  
 Sender name in RAD50  
 13-word data area  
 UCB of TI: of sender  
 Current UIC of sender

A 13-word buffer in sender task is copied into DSR block

A 15-word buffer in user task receives sender name and data

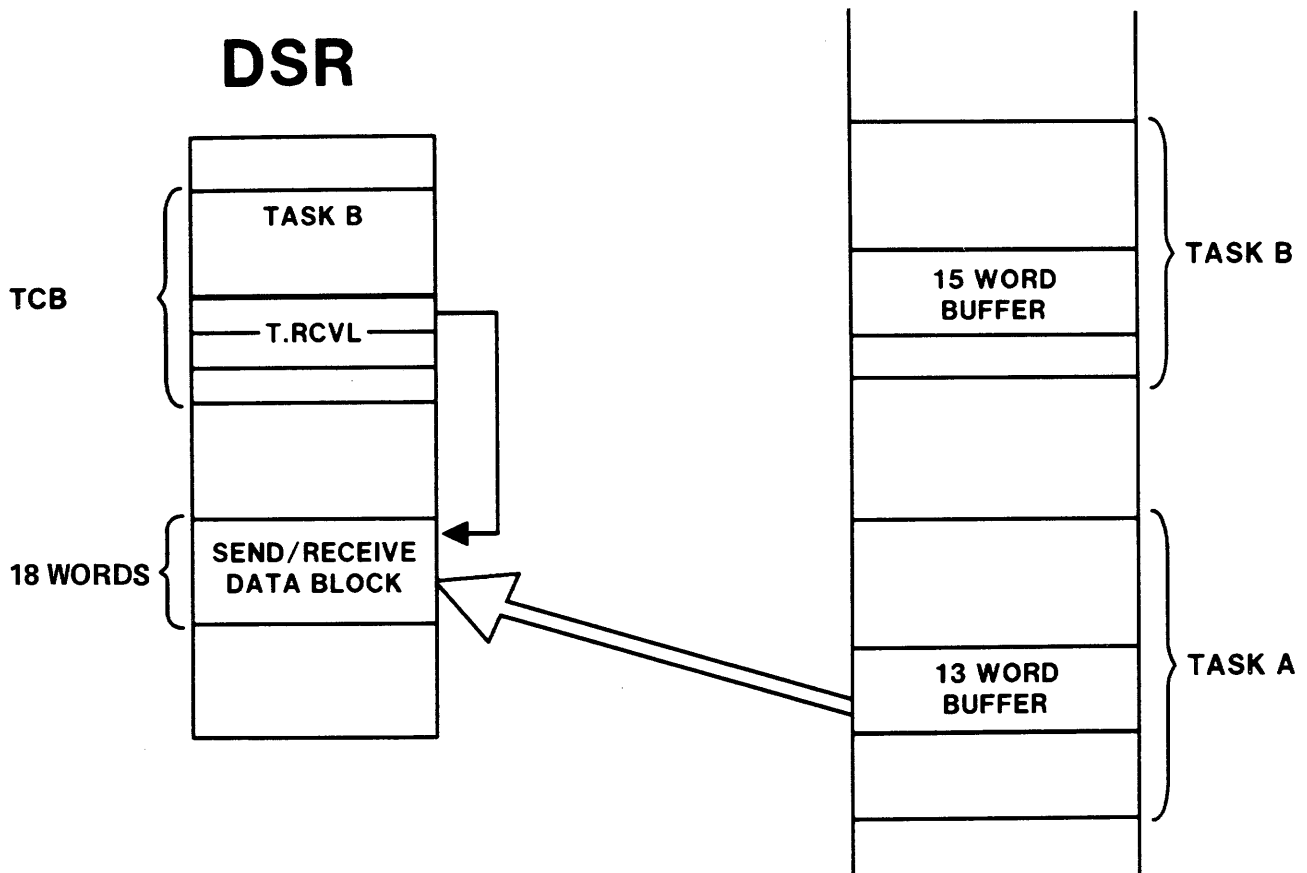


Figure 11-6 Send/Receive Processing: Send from TASK A

DIRECTIVE PROCESSING

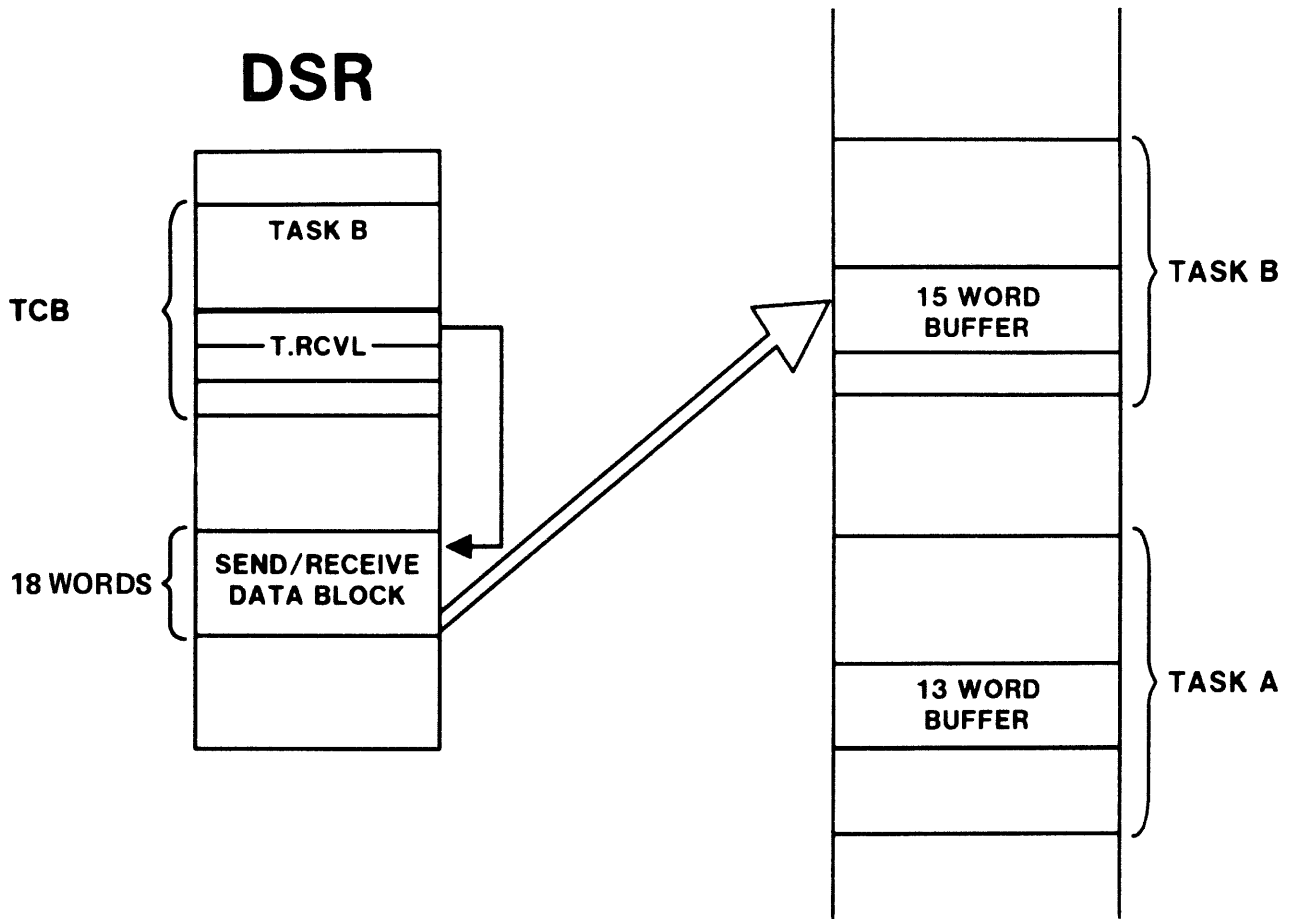


Figure 11-6 Send/Receive Processing: Receive by TASK B



## DIRECTIVE PROCESSING

### Parent/Offspring Tasking

- Connecting TASKA to TASKB

TASKB passes a one-word status back to TASKA when

TASKB exits  
TASKB emits status

TASKA is the parent task, TASKB is the offspring task

- TASKA spawns TASKB

TASKA requests TASKB

TASKA connects to TASKB

- Steps in connecting

A 14-word offspring control block is allocated in DSR

OCB is linked to the TCB of the offspring task at T.OCBH

When offspring exits or emits status, status moved to OCB  
placed into first word in 8-word status area

Status automatically moved into parent status buffer

Parent task specifies event flag and/or AST for  
notification of the offspring's return of status

DIRECTIVE PROCESSING

<b>OCB LINK WORD</b>	<b>0</b>	<b>O.LINK</b>
<b>ADDRESS OF MCR COMMAND LINE</b>	<b>2</b>	<b>O.MCRL</b>
<b>PARENT TCB ADDRESS</b>	<b>4</b>	<b>O.PTCB</b>
<b>EXIT AST ADDRESS</b>	<b>6</b>	<b>O.AST</b>
<b>EXIT EVENT FLAG</b>	<b>10</b>	<b>O.EFN</b>
<b>EXIT STATUS BLOCK VIRTUAL ADDRESS</b>	<b>12</b>	<b>O.ESB</b>
	<b>14</b>	<b>O.STAT</b>
	<b>16</b>	
	<b>20</b>	
<b>EXIT STATUS BUFFER (8 WORDS)</b>	<b>22</b>	
	<b>24</b>	
	<b>26</b>	
	<b>30</b>	
	<b>32</b>	

Figure 11-7 Parent/Offspring Tasking: Offspring Control Block

DIRECTIVE PROCESSING

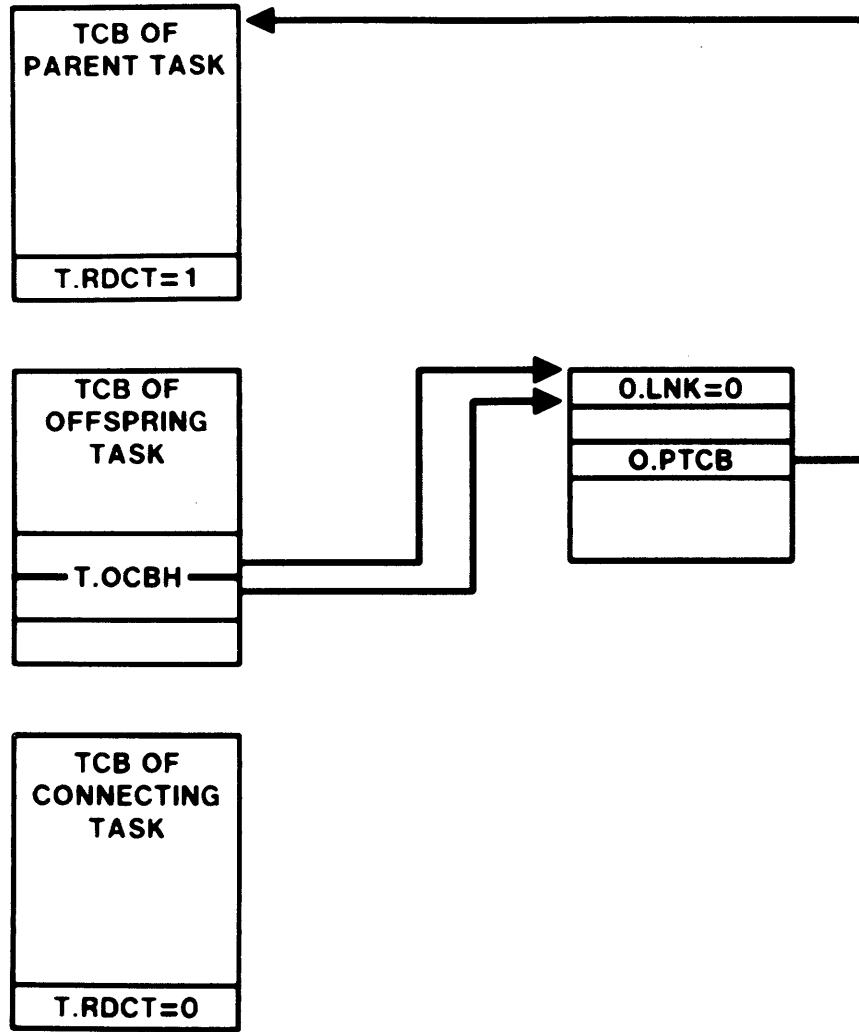


Figure 11-7 Parent/Offspring Tasking: Spawning a Task

DIRECTIVE PROCESSING

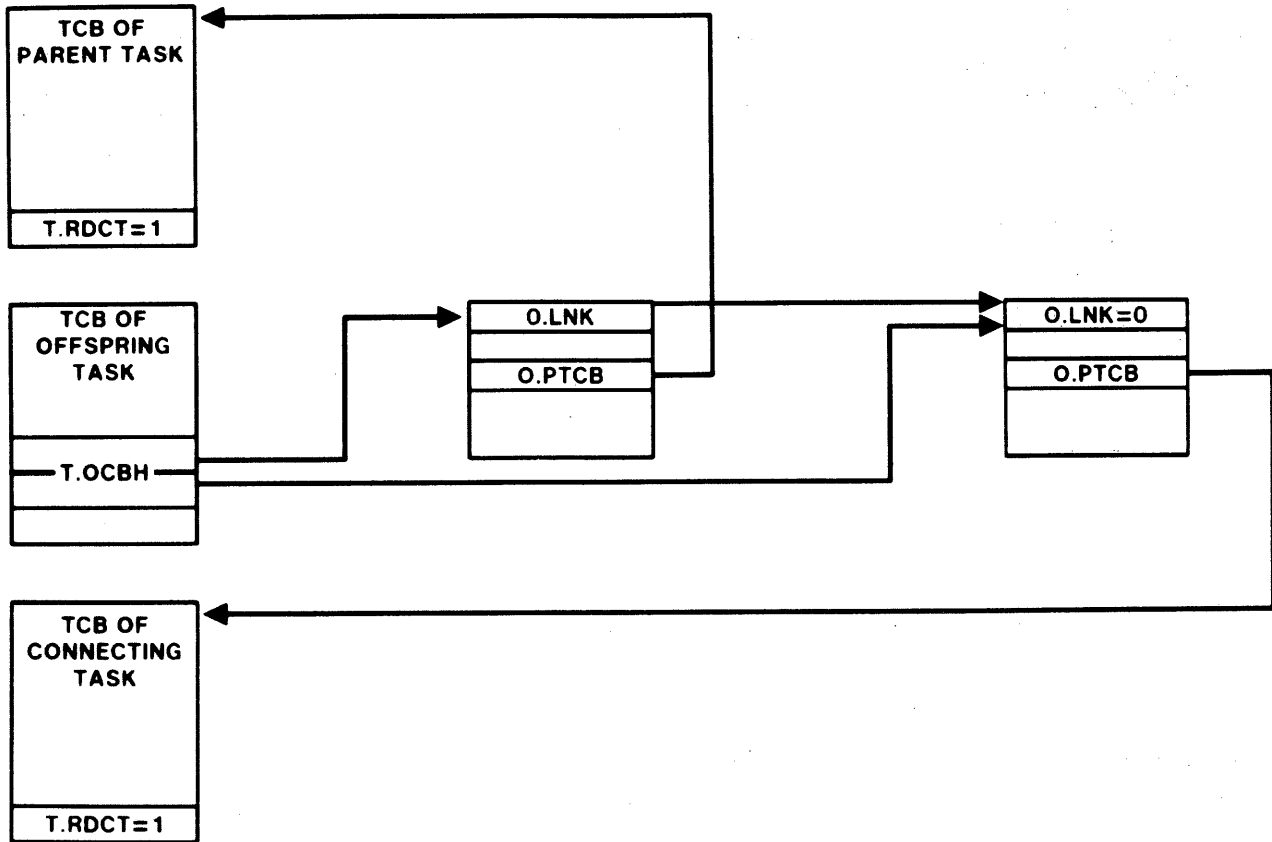


Figure 11-7 Parent/Offspring Tasking: Connecting to a Task

## DIRECTIVE PROCESSING

### **Memory Management Processing**

- User task specifies information for creating/attaching to a region in a Region Definition Block (RDB)
- Information in RDB used to initialize PCB for subpartition in dynamic partition
- User task specifies information for creating/mapping an addressing window in a Window Definition Block (WDB)
- Information in WDB used to initialize window block in task header

DIRECTIVE PROCESSING

**REGION DEFINITION BLOCK**

REGION ID
SIZE OF REGION (32W BLOCKS)
NAME OF REGION (RAD50)
REGION'S MAIN PARTITION NAME (RAD50)
REGION STATUS WORD
REGION PROTECTION WORD

**PARTITION CONTROL BLOCK (PCB)**

LINK TO NEXT PARTITION PCB	
I/O COUNT=0	PRIORITY OF PARTITION
PARTITION NAME (IN RADIX-50)	
POINTER TO NEXT SUB-PARTITION	
POINTER TO MAIN	
PHYSICAL START ADDRESS OF PARTITION	
SIZE OF PARTITION	
PARTITION WAIT QUEUE	LIST HEAD
PARTITION SWAP SIZE (SYSTEM ONLY)	
PARTITION BUSY FLAGS	
TCS ADDR. OF OWNER/CURRENT UIC OF OWNER TASK	
PARTITION STATUS FLAGS	
POINTER TO TASK HEADER	
PROTECTION WORD FOR REGION	
ATTACHMENT DESCRIPTOR	
LIST HEAD	

**CREATING A REGION**

**WINDOW DEFINITION BLOCK**

BASE APR	WINDOW ID
VIRTUAL BASE ADDRESS (BYTES)	
WINDOW SIZE (32W BLOCKS)	
REGION ID	
OFFSET IN REGION (32W BLOCKS)	
LENGTH TO MAP (32W BLOCKS)	
WINDOW STATUS WORD	
SEND/RECEIVE BUFFER ADDRESS (BYTES)	

**TASK ADDRESSING WINDOW BLOCK**

PCB ADDRESS	
LOW VIRTUAL ADDRESS LIMIT	
HIGH VIRTUAL ADDRESS LIMIT	
ADDRESS OF ATTACHMENT DESCRIPTOR	
SIZE OF WINDOW IN 32. WORD BLOCKS	
PHYSICAL MEMORY OFFSET IN 32. WORD BLOCKS	
NUMBER OF APRS TO MAP	FIRST PDR ADDRESS (LOW BYTE)
CONTENTS OF LAST PDR	

**CREATING AND MAPPING A WINDOW**

Figure 11-8 Memory Management Processing

## DIRECTIVE PROCESSING

### ADDING A USER-WRITTEN DIRECTIVE

- Interface to the directive processing

Structure of Directive Parameter Block must be determined

Entry for new directive must be added to the DDT

Directive processing routine must be written

Macros to invoke directive must be written

Directive processing routine must be built into the system

Macros must be added to the system macro library

### Structuring the Directive Parameter Block

- Information needed to execute directive
- Choose an unused DIC
- Choose order for necessary parameters

If event flag is first parameter, specify CEFNCL and/or CEFNMT

If task name is first parameter, specify DFCTSK and/or SRSTCL

<b>SIZE=4</b>	<b>DIC=161</b>
<b>TASK NAME</b>	
<b>IN RAD50</b>	
<b>EVENT FLAG NUMBER</b>	

Figure 11-9 Directive Parameter Block for New Directive

## Changes to the Directive Dispatcher

- DDT determines
  - Which directive processing routine to call
  - What processing to perform in DRDSP
  - Size of DPB
  - Where the module is to be located (directive commons)
- Each directive is represented by a line in the DIREC macro defined in the module DRDSP
- Format of line in DIREC macro is

```
MAC    DIC,DPBSIZ,DIRADR,MASK,COND,SECOND
```

Where

```
DIC      - Directive Identification Code
DPBSIZ   - Size of the DPB
DIRADR   - Address of the Directive Processing Routine
MASK     - Directive Processing Control Mask
COND     - Conditional Assembly Parameters which must
           be defined if the directive is supported
SECOND   - Conditional assembly parameters which if
           defined require that the directive have a
           variable length DPB
```

Example:

```
MAC    55.,2.,$DRCRR!PAG,<ACHKDB>,P$$LAS
```

This is the 'create region' directive.

PAG is set to 1 if directive common support is desired, 0 otherwise. The service routine will be placed in EXCOM2.



## DIRECTIVE PROCESSING

---

Place the following in the Directive Dispatch Table

MAC 161.,4.,\$DRFLG!PAG,<DFCTSK!SRSTCL>

DIC

Size of DPB

Processing Routine

Force to EXCOM2

Default to current task

Call \$SRSTD to find TCB

---

Example 11-2 New Entry in the Directive Dispatch Table

## The Directive Processing Routine and Macros

- Routine should be written to make use of the standard register usage in DRDSP
- Assembly with EXEMC and RSXMC
- Provide only macros needed by applications

```

        .TITLE  DRFLG
        .IDENT  /1.0/
$+
$  ** - $DRFLG - SET TASK'S LOCAL EVENT FLAG
$
$  THIS DIRECTIVE INSTRUCTS THE SYSTEM TO SET A SPECIFIED TASK'S LOCAL
$  EVENT FLAG.
$
$  DPB FORMAT:
$
$      WD. 00 -- DIC (161.), DPB SIZE (4.)
$      WD. 01 -- FIRST HALF OF TASK NAME (RAD50)
$      WD. 02 -- SECOND HALF OF TASK NAME (RAD50)
$      WD. 03 -- EVENT FLAG NUMBER (1-32.)
$
$  INPUTS:
$      R0 = TCB ADDR. OF TARGET TASK
$      R1 = ADDR. OF FIRST TASK STATUS WORD
$      R2 = ADDR. OF SECOND TASK STATUS WORD
$      R3 = ADDR. OF NEXT WORD IN DPB
$      R4 = ADDR. OF HEADER OF CURRENT TASK
$      R5 = ADDR. OF TCB OF CURRENT TASK
$
$  OUTPUTS:
$      C = 0 IF DIRECTIVE IS SUCCESSFULLY COMPLETED
$          DIRECTIVE STATUS D.RS22 IS RETURNED IF EVENT FLAG IS
$          ALREADY SET
$          DIRECTIVE STATUS D.RS00 IS RETURNED IF EVENT FLAG WAS
$          CLEARED
$      C = 1 IF DIRECTIVE IS REJECTED
$          DIRECTIVE STATUS D.RS97 IS RETURNED IF ILLEGAL EVENT
$          FLAG
$-
        .ENABL  LSB
$DRFLG::
        MOV     R0,R5    $ADDR OF TARGET TASK TCB
        CALL   $CEFN    $CONVERT TO EVENT FLAG MASK
        BCS    20$      $ILLEGAL EVENT FLAG
        BIT    R0,(R1)  $EVENT FLAG ALREADY SET?
        BEQ    10$      $NO, IF EQUAL
        DRSTS  D.RS22   $RETURN STATUS
10$:     BIS    R0,(R1)  $SET THE EVENT FLAG
        DRSTS  D.RS00   $RETURN STATUS
20$:     DRSTS  D.RS97   $ILLEGAL EVENT FLAG STATUS
        .END

```

Example 11-3 Processing Routine for New Directive

## DIRECTIVE PROCESSING

```

$+
$
$
$ FORM OF MACRO FOR $DRFLG

.MACRO SLEF$ TN,EFN
.BYTE 161.,4
R50$ TN
.WORD EFN
.ENDM SLEF$

$+
$
$-
$C FORM OF MACRO FOR $DRFLG

.MACRO SLEF$C TN,EFN,ERR,PST
.PSECT $DPB$$
$$$
=
.BYTE 161.,4
R50$ TN
.WORD EFN
.PSECT PST
MOV $$$,-(SP)
EMT ^O<377>
.IF NB ERR
BCC .+6
JSR PC,ERR
.ENDC
.ENDM SLEF$C

$+
$
$-
$S FORM OF MACRO FOR $DRFLG

.MACRO SLEF$S TN,EFN,ERR
MOV$ EFN
RFA$ TN
MOV (PC)+,-(SP)
.BYTE 161.,4
DIR$ ,ERR
.ENDM SLEF$S

```

Example 11-4 Macros for New Directive

## DIRECTIVE PROCESSING

### Adding a Directive to the System

- Directive can be included in the Executive or in EXCOM2

In the Executive if

Directive commons not chosen at SYSGEN

Not enough room in EXCOM2

Otherwise in EXCOM2

- To include in the Executive  
Build with the Executive during SYSGEN
- To include in EXCOM2  
Build with EXCOM2 during SYSGEN
- Macros included in system macro library RSXMAC.SML

DIRECTIVE PROCESSING

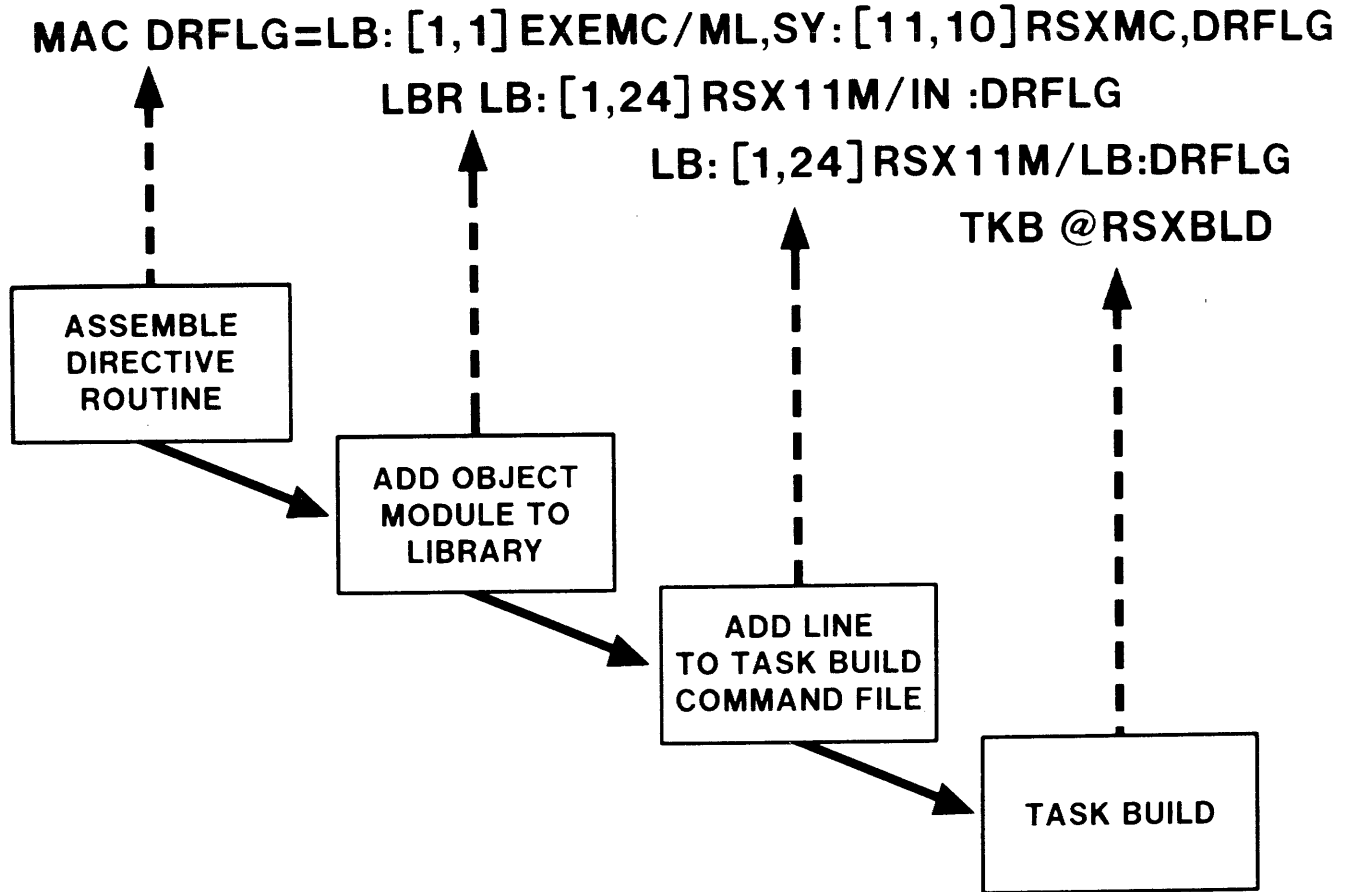


Figure 11-10 Assembling and Taskbuilding the Processing Routine



## **I/O PROCESSING**





## INTRODUCTION

Any modern operating system must provide a complete I/O system. Besides providing basic I/O device handling software, it must also provide a convenient file system.

Device drivers handle primitive I/O functions under RSX-11M. These drivers are tailored to individual devices and optimized to provide maximum performance. They are invoked by means of the QIO mechanism.

RSX-11M uses the FILES-11 file system. There are two levels of software support in the operating system for FILES-11. The more visible level includes the file access systems, FCS, and RMS. These systems provide all features needed in any application under RSX-11M. A more primitive level, in the form of ACPS (F11ACP), forms the interface between FCS/RMS and device drivers.

## OBJECTIVES

1. Diagram the flow in the I/O system.
2. List the types of ACPS and their differences.
3. List the steps in processing an I/O request within DRQIO.

## RESOURCES

1. RSX-11M System Lists and Data Structures
2. RSX-11M Guide to Writing an I/O Driver
3. RSX-11M/M-PLUS I/O Operations References Manual



## OVERVIEW

### Components of the I/O System

- The File System

Used to structure data for convenient use in applications

Provides software for easy manipulation of data

Consists of:

FILES-11 structures

File Control Services (FCS)

Record Management Services (RMS)

- QIO directive

Used to request I/O service from the Executive

Can be used directly in user task

All file-system I/O requests converted into QIOs

- Device Drivers

Used to control physical devices and perform actual I/O

One required for each device type

Carry I/O requests to transfer data

## I/O PROCESSING

- Ancillary Control Processor (ACP)

- Performs functions subordinate to those of the driver

- Provides a file system for user tasks

- Handles protocols needed by a communications network

- Converts I/O requests into one or more request to a device driver

- Manipulates I/O parts of the system data base

- Three ACPs provided with RSX-11M

- F11ACP: Files-11

- MTAACP: Magtape I/O ACP

- NETACP: DECNET ACP

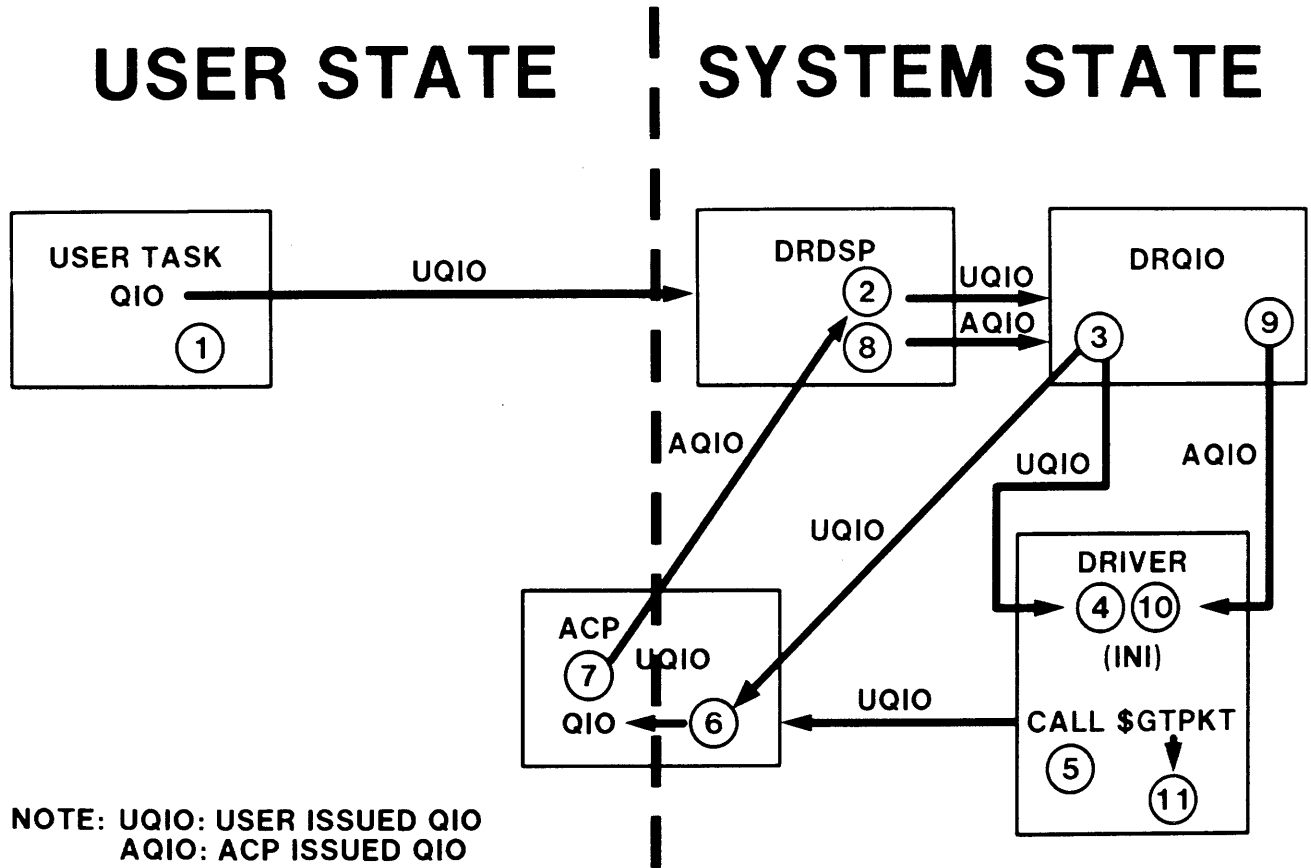


Figure 12-1 The I/O Process

## Initiating I/O From a User Task

- Use QIO directives

Harder to use than other methods

Can be the most efficient method of I/O

For file I/O, use virtual block transfers

For non-file I/O, use logical block transfers

- Use high-level language I/O commands

Easier to use than QIOs, but less efficient

Language processor may convert to QIOs or convert to FCS/RMS commands

- Use FCS/RMS to perform file system I/O

Allows data to be accessed in a form natural to the application

File processor converts to QIOs

## I/O PROCESSING

### Processing I/O Request in DRQIO

- All I/O performed as a result of QIO directives
- QIO directive parameters are checked; directive status is returned
- Parameters used to create I/O packet
- I/O packet is queued to a device driver or to an ACP
- If ACP function, a number of checks are performed before queuing I/O packet

## QIO PROCESSING

### Logical Units

- Logical Unit Numbers (LUNs) identify the device to which I/O is to be performed
- LUN determines a unique entry in the task's Logical Unit Table (LUT) in the task header
- Each entry in the LUT is two words long
- When a task is installed, the first word of each LUT entry is initialized with the UCB address of the device
- When a file is opened on a volume, the second word of the corresponding LUN points to a FILES-11 window block

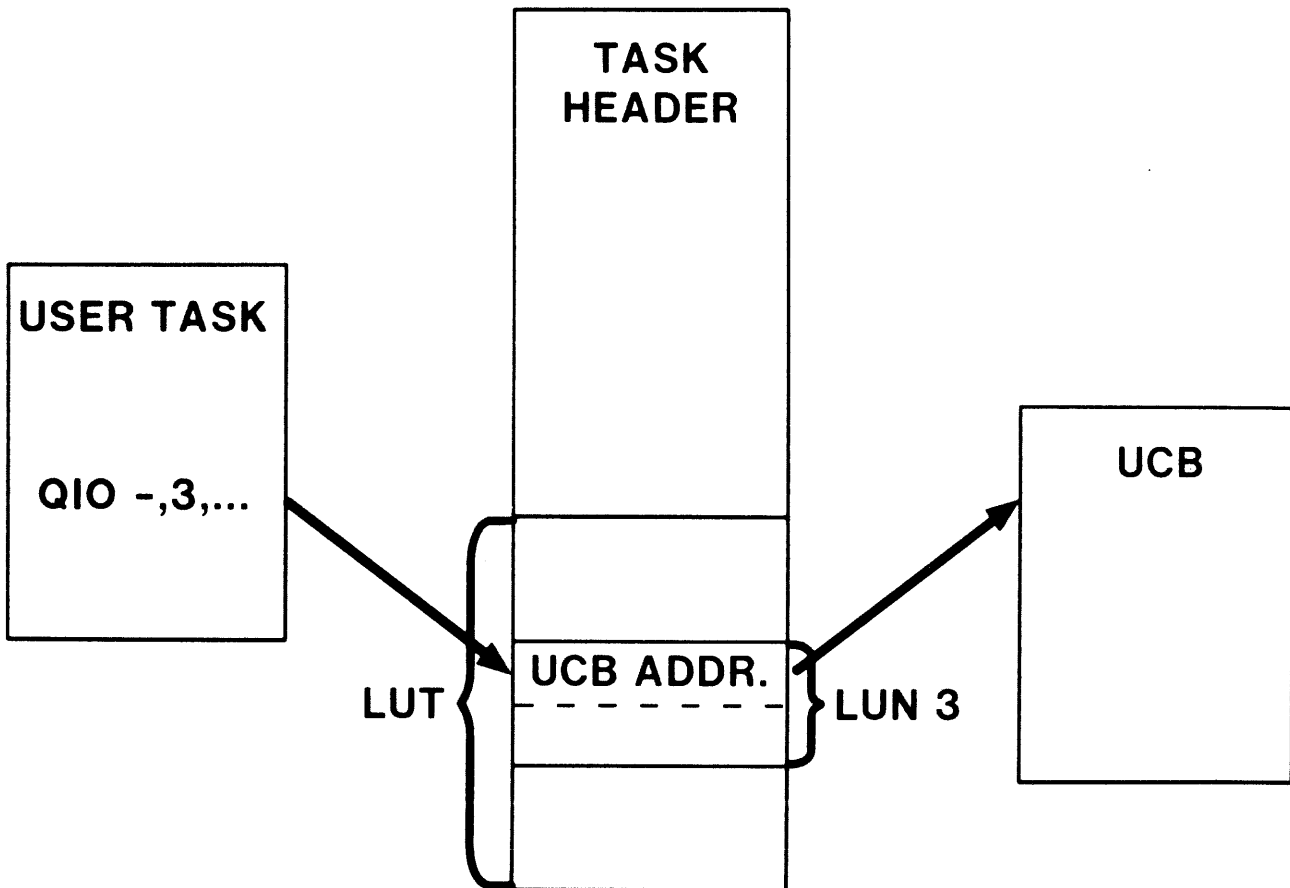


Figure 12-2 Logical Units



## I/O PROCESSING

### Processing Within DRQIO

- Locates the UCB for LUN
  - Calls \$MPLUN in module EXESB
- Checks to see if driver resident
  - Location D.DSP in the DCB
- Clears specified event flag
- Clears I/O status block if specified
- QIO directive is now successful
  - DSW shows success
  - Any errors are reported as I/O errors in the IOSB
- Allocates space for I/O packet in POOL
  - Calls \$ALPKT in module CORAL
- Increments I/O request count in the TCB
- Copy data from DPB to I/O packet
- If function is IO.KIL, go the routine \$IOKIL in module IOSUB
- Check if task has privileges to perform I/O
- Check function code against function masks in DCB
- If not legal function, return I/O error
- If control function, queue I/O packet to driver
- If 'no-op' function, return successful status
- If ACP function to mounted device, perform ACP function checks

### The ACP Function Checks

- Implemented by a collection of primitive routines
- Each ACP requires a different group of these routines
- A two-level dispatch table, the Polish Interpreter Database, is used
- First level table, the Function Code Dispatch Vector, resides at FCDSV in DRQIO

Each entry corresponds to a unique function code

Each entry is a vector which points to a second level dispatch table

- Second level dispatch table contains primitive routines to be called

I/O PROCESSING

Table 12-1 Function Code Dispatch Vector

Function Code	Dispatch Table	Function
10	FCIFC	Illegal function
11	FCPKT	Find file name in directory
12	UNLCK	Unlock Block
13	FCPKT	Remove file name from directory
14	FCPKT	Enter file name in directory
15	FCACC	Access file for READ
16	FCACC	Access file for READ and WRITE
17	FCACC	Access file for READ, WRITE, and EXTEND
20	FCDAC	Deaccess file
21	FCRVB	Read Virtual Block
22	FCWVB	Write Virtual Block
23	FCEXT	Extend file
24	FCCRE	Create file
25	FCDEL	Mark file for DELETE/TRUNCATE file
26	FCPKT	Read file attributes
27	FCPKT	Write file attributes
30	FCPKT	User magtape control function
31	FCWVB	Transmit process message
32	FCRVB	Receive process message
33	FCCON	Connect to process
34	FCDIS	Disconnect from process
35	FCNCT	Network control process
36	FCIFC	Illegal function
37	FCIFC	Illegal function

I/O PROCESSING

Table 12-2 Polish Routines

Table	Routine	Function
FCIFC	IEIFC	Set illegal function status
FCACC	CKDMO	Check if volume marked for dismount
	CKALN	Check if file already accessed on LUN
	CKMOU	Check volume mounted this user
	CKACP	Set flag to queue to ACP
	BDPKT	Build an I/O packet
	CKRLK	Synchronize access and exit
FCDAC	CKNLN	Check if file accessed on LUN
	CKQMT	Queue to MTAACP if ANSI
	BDPKT	Build an I/O packet
	CKRLK	Synchronize and exit
FCRVB	CKNLN	Check if file accessed on LUN
	CKRAC	Check read access and exit
FCWVB	CKNLN	Check if file accessed on LUN
	CKWAC	Check write access and exit
FCCRE	CKDMO	Check if volume marked for dismount
	CKALN	Check if file accessed on LUN
	CKPKT	Join common ACP and check mount
FCDEL	CKTRN	Check if really truncate
	CKACP	Set flag to queue to ACP
	CKMOU	Check volume mounted by this user
	BDPKT	Build an I/O packet
	CKXIT	Exit
FCPKT	CKACP	Set flag to queue to ACP
	CKMOU	Check volume mounted by this user
	BDPKT	Build an I/O packet
	CKXIT	Exit
FCEXT	CKPND	Increment window pending count for extend
UNLCK	CKNLN	Check if file accessed on LUN
	UNLXT	Set registers and exit
FCCON	CKDMO	Check if volume marked for dismount
	CKALN	Check if process already connected on LUN
	CKCON	Address check connect buffer
	CKRLK	Interlock LUN usage and exit

# I/O PROCESSING

Table 12-2 Polish Routines (Cont)

Table	Routine	Function
FCDIS	CKNLN	Check if process connected on LUN
	CKDIS	Check buffer and copy parameters
	CKRLK	Interlock LUN usage and exit
FCNCT	CKDMO	Check if volume marked for dismount
	CKCON	Address check buffer
	CKXIT	Exit

### Queuing I/O Requests

- I/O request packets are queued by routine \$DRQRQ in module DRSUB

- Processing in \$DRQRQ

Bit UC.QUE in U.CTL in the UCB is checked

If set, packet queued to driver

Contents of KERNEL APR 5 is saved on stack

If driver loadable, base address of driver loaded into KERNEL APR 5

The driver is called to initiate I/O

When driver exits

Control returns to \$DRQRQ

Original contents of KERNEL APR 5 are restored

## ANCILLARY CONTROL PROCESSORS

### Types of ACPs

- Standard ACPs

Known to the Executive

Executive includes special code for support

Follow rules used by DEC in writing F11ACP and MTAACP

- User ACPs

Not known to the Executive

Known only to the driver which uses their services

UC.QUE set in U.CTL to prevent ACP function checks in DRQIO

Driver does preprocessing and queues requests to ACPs

No change to the Executive code is necessary

- Foreign ACPs

Between standard and user ACPs

Known to the Executive

No special services provided to support ACP

Identified by foreign bit US.FOR in the UCB

I/O PROCESSING

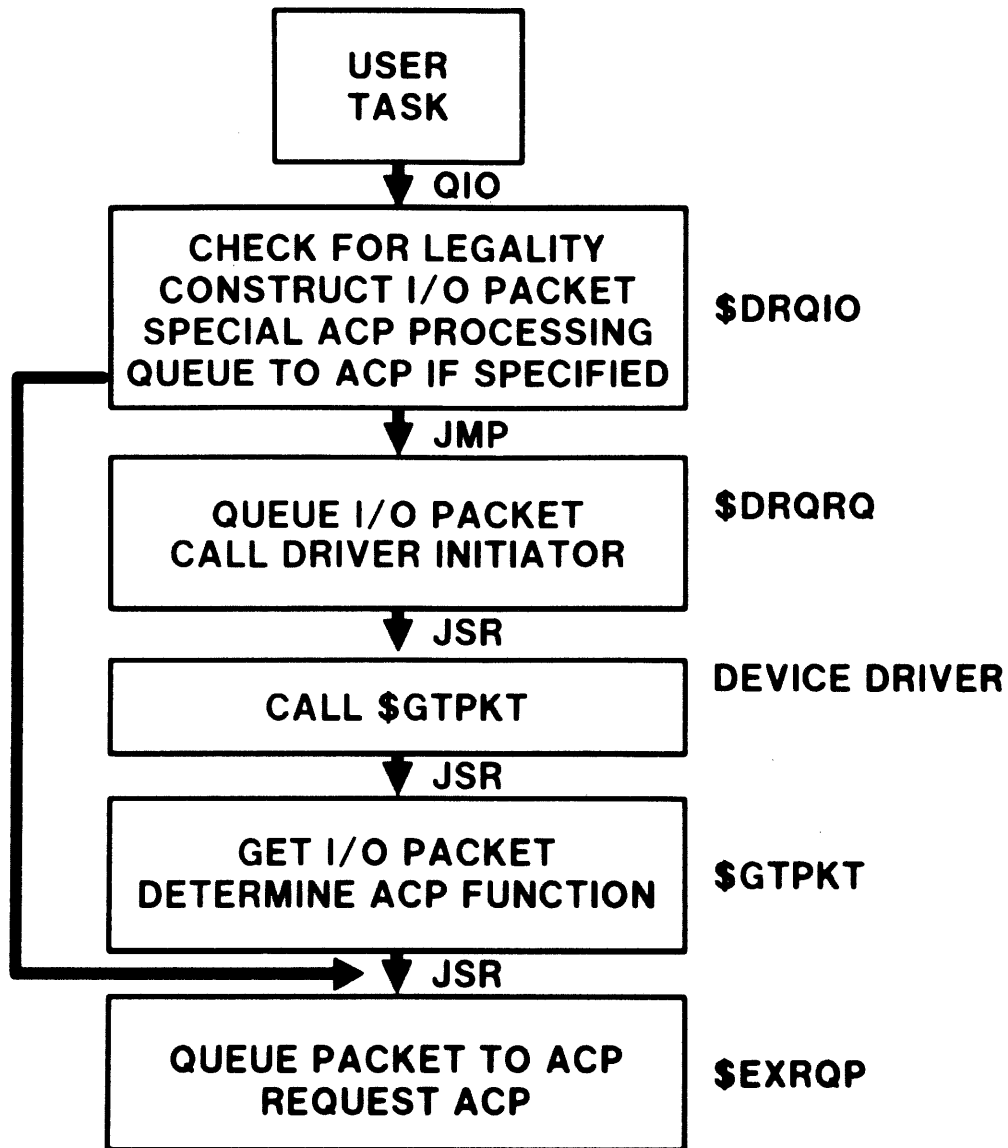


Figure 12-3 Standard ACP



I/O PROCESSING

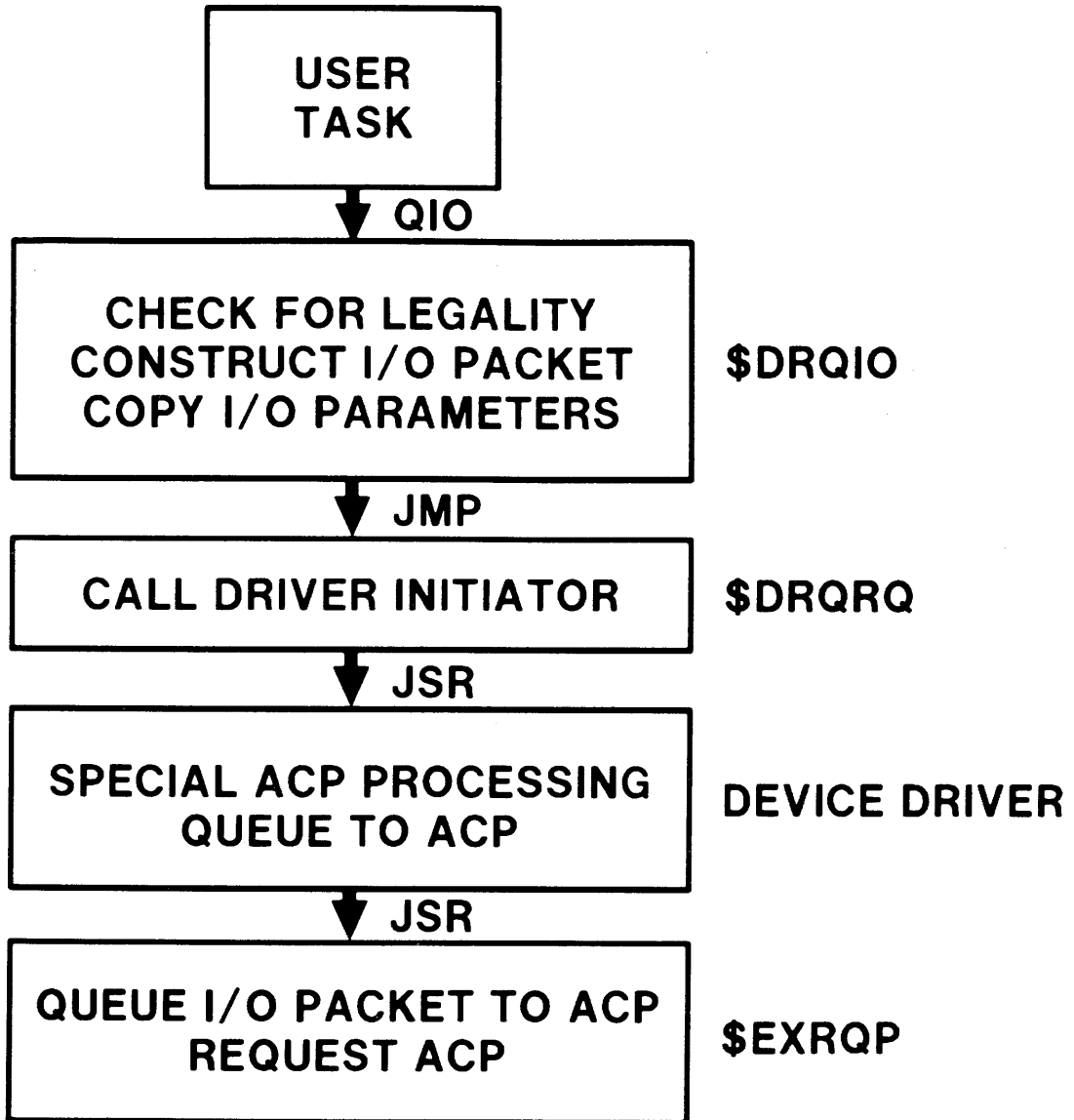


Figure 12-4 User ACP

I/O PROCESSING

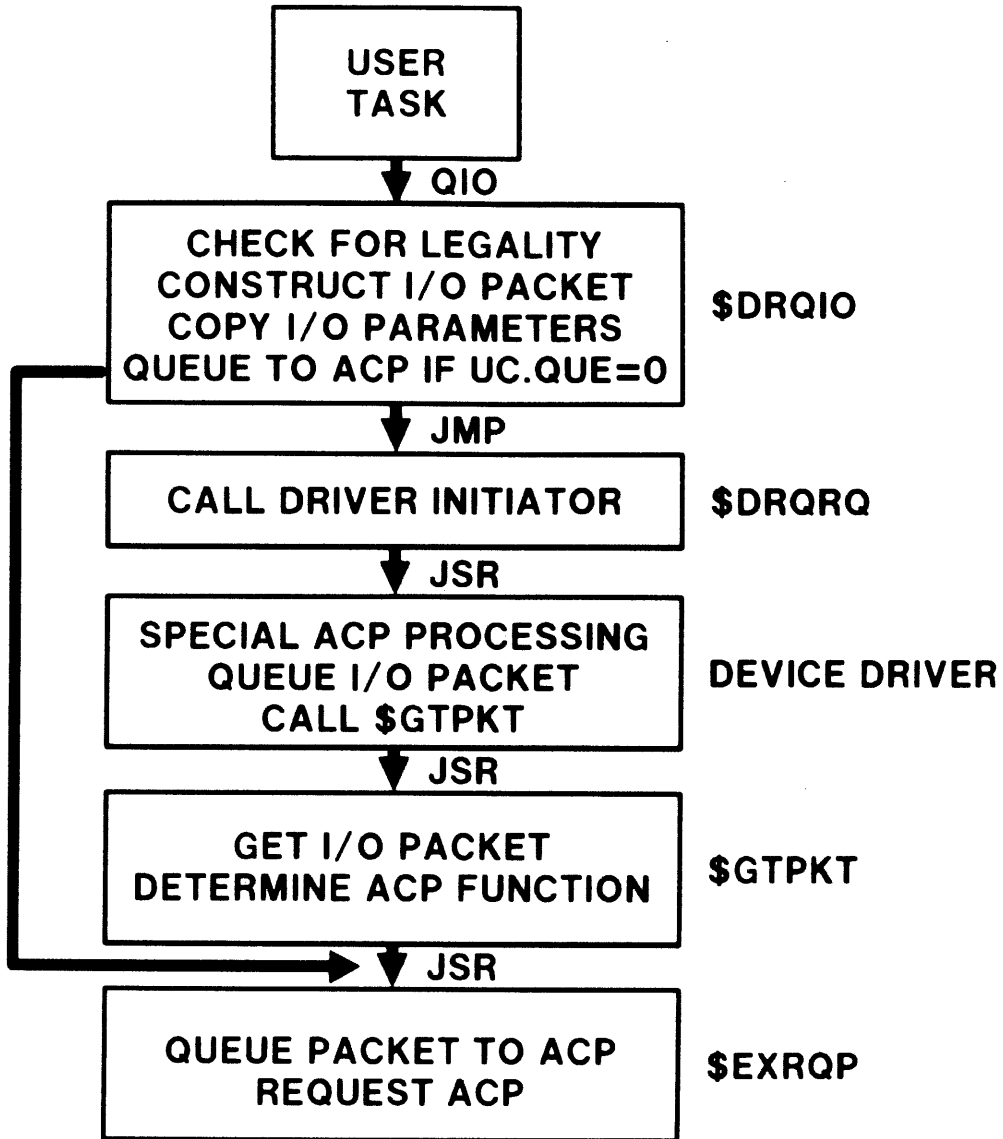


Figure 12-5 Foreign ACP

## The FILES-11 (F11ACP)

- Implements the FILES-11 structure for disks
- Provides needed file primitives (open, close, etc.)
- Converts file primitives to driver primitives

Open file requires several driver operations:

Locating the file which may require several reads of directory records and headers

Creating the FCB from the file header

Creating the window block from the retrieval pointers

## Versions available at SYSGEN

- MINIMUM Version

Not recommended for general use

Runs in 2K words of memory

Heavily overlaid

No internal buffers for storing data

Mapped and unmapped systems

- SMALL Version

Provides limited performance optimization

Requires 10 to 100 times more I/O for directory lookups and file opens than larger ACPs

Heavily overlaid

Runs in 2.5K words of memory

Mapped and unmapped systems

Default version for unmapped systems

## I/O PROCESSING

- MIDDLE Version

Usually provides the best performance without using large amount of memory

Provides buffers for storing directories and the index file bitmap

Runs in 5K words of memory

Mapped and unmapped systems

Default version for mapped systems

- LARGE Version

Provides the maximum performance for F11ACP

Not overlaid

Runs in 10K words of memory

Provides larger buffers for storing directories

Available only on mapped systems

# **DEVICE DRIVER PROCESSING**



## INTRODUCTION

Most tasks receive raw data from external sources and provide results to the user. It is usually necessary to keep large amounts of data available to the processor for instant use. To provide these services, an I/O system is needed. The basic component of this system is the software which handles the activities of the physical devices. Under RSX-11M, this software is called a device driver.

RSX-11M provides drivers for each supported peripheral device. The interface between a driver and the I/O system is simple and standard. The user can write drivers for non-standard devices by adhering to the requirements of this interface.

## OBJECTIVES

1. Diagram the flow of control during device driver processing.
2. Determine the status of a device by examining its data structures.
3. Diagram the process of performing I/O with a DMA UNIBUS device on the PDP-11/44 or 70.

## RESOURCES

1. RSX-11M System Lists and Data Structures
2. RSX-11M Guide to Writing a Device Driver





## OVERVIEW

### Methods of Performing I/O

- Device common
  - Partition in I/O Page
  - Built and used as any other common area
  - Can only perform 'device-poll' device driving
  
- Direct access to I/O page
  - Privileged task has access to I/O page
  - Can only perform 'device-poll' device driving
  
- CINT\$ Directive
  - Task contains essential routines to drive device
  - Very little knowledge of system interface required
  - Easy to debug
  - Interrupt driven
  
- Device Driver
  - Integral part of the Executive
  - Is written to use QIO mechanism
  - Usually interrupt driven but can do 'device-poll'

## DEVICE DRIVER PROCESSING

### Design Philosophy

- One device driver per device type  
Handles multiple controllers
- Common I/O processing done in Executive routines  
Queuing of I/O request in module DRQIO  
I/O completion handled by routine \$IODON in module IOSUB
- Keep interrupt lockout to a minimum  
Run at priority 7, no more than 100 microseconds  
Run at priority of interrupting device, no more than 500 microseconds
- Use a FORK process to access the system data base

## DEVICE DRIVER PROCESSING

### General Flow

- User task issues QIO directive
  - Executive entered as result of EMT instruction
- Executive processes QIO
  - Checks made on data in DPB
  - Mapping adjusted to map to service routine and DPB
- Module DRQIO processes QIO
  - Checks made on I/O request
  - I/O packet created and queued to driver
- Driver called at initiate I/O entry point
  - I/O packet retrieved
  - Data in packet processed
  - I/O device started
- Control returns to user task if asynchronous I/O, Executive otherwise
- When interrupt occurs, driver entered at interrupt entry point

## DRIVER DATA BASE

- Location

In module SYSTB for DEC-supplied drivers

If user-written driver with

Resident data base, in Executive  
Loadable data base, in DSR

## Device Control Block (DCB)

- One per device type

- Describes static characteristics of device

- Linked to device list

Headed by \$DEVHD in Executive module SYSCM

List linked by D.LNK in DCB

- Contains

D.DSP - Address of Driver Dispatch Table

D.MSK - Function masks for filtering QIO requests

D.UCB - Link to first UCB

D.UCBL - Length of UCB for device type

D.NAM - Generic device name in ASCII

D.UNIT - Highest and lowest unit number

- Used by QIO processing, not by driver

## DEVICE DRIVER PROCESSING

### Unit Control Block (UCB)

- One per physical unit
- Contains mostly static data
- Most other data structures can be accessed from UCB
- UCB for unit 0 linked from D.UCB in the DCB for device type
- Other UCBs for device type contiguous with UCB for unit 0
- Contains
  - U.DCB - Pointer back to DCB for device type
  - U.RED - Pointer to UCB of redirect device
  - U.UNIT - Physical unit number
  - U.SCB - Pointer to SCB of controller for this unit
- Used by both driver and Executive

DEVICE DRIVER PROCESSING

Table 13-1 Important Entries in the UCB

Entry	Offset	Length	Contents
U.DCB	0	WORD	Address of DCB for device type
U.SCB	20	WORD	Address of SCB for unit
U.UNIT	6	BYTE	Physical unit number
U.RED	2	WORD	Address of UCB for redirect
U.STS	5	BYTE	Unit status bits
U.ST2	7	BYTE	More unit status bits
U.CTL	4	BYTE	Unit control flags
U.CW1	10	WORD	1st device characteristics word
U.CW2	12	WORD	2nd device characteristics word
U.CW3	14	WORD	3rd device characteristics word
U.CW4	16	WORD	4th device characteristics word
U.CLI	-6	WORD	Default CLI
U.LUIC	-4	WORD	Login UIC
U.OWN	-2	WORD	Owning terminal

- Notes:
1. U.CLI and U.LUIC exist only for terminals
  1. U.LUIC exists if system is multi-user

DEVICE DRIVER PROCESSING

	.DCØ		0	U.DCB
	.LPØ		2	U.RED
U.STS	0	0	4	U.CTL
U.ST2	0	0	6	U.UNIT
	DV.REC ! DV. CCL		10	U.CW1
	140100		12	U.CW2
	0		14	U.CW3
	132.		16	U.CW4
	\$LPØ		20	U.SCB
	0		22	U.ATT
	0		24	U.BUF
	0		26	
	0		30	U.CNT

Figure 13-1 Unit Control Block for LP:

DEVICE DRIVER PROCESSING

	0		-10	U.IOC
U.ERHL	8.	5	-6	U.ERSL
U.ERHC	0	0	-4	U.ERSC
	0		-2	U.OWN
	.DCO		0	U.DCB
	.DKO		2	U.RED
U.STS	UC.ALG!UC.NPR!UC.PWF	US.MNT	4	U.CTL
U.ST2	0	0	6	U.UNIT
	DV.DIR!DV.MNT!DV.F 11!DV.MSD!DV.UMD		10	U.CW1
	0		12	U.CW2
	4800.		14	U.CW3
	512.		16	U.CW4
	\$DKO		20	U.SCB
	0		22	U.ATT
	0		24	U.BUF
	0		26	
	0		30	U.CNT
	0		32	U.ACP
	0		34	U.VCB

Figure 13-2 Unit Control Block for DK:



### **Status Control Block (SCB)**

- One SCB per controller
- Line multiplexers (DH-11, DJ-11, etc.) have one controller per line
- Most information is dynamic
- Linked from U.SCB in the UCB
- One SCB is linked from several UCBs if controller is common to several units
- Contains
  - S.LHD - Device I/O queue listhead
  - S.PKT - Address of current I/O packet
  - S.PRI - Device priority
  - S.CTM - Current time out count
  - S.ITM - Initial time out count
  - S.CSR - Address of Control Status Register
  - S.FRK - The FORK block
- Used by driver and Executive

DEVICE DRIVER PROCESSING

S.ROFF	-7	REGS. TO COPY ON ERROR	OFFSET TO 1ST REG.	-6	S.RCNT
		SAVED I/O ACTIVE BIT MAP		-4	S.BMSV
		DEVICE I/O ACTIVE BIT MASK		-2	S.BMSK
		CONTROLLER I/O		0	S.LHD
		QUEUE LISTHEAD		2	
S.VCT	5	VECTOR ADDR/4	PRIORITY	4	S.PRI
S.ITM	7	INITIAL TIMEOUT COUNT	CURRENT TIMEOUT COUNT	6	S.CTM
S.STS	11	CONTROLLER STATUS	CONTROLLER INDEX	10	S.CON
		ADDRESS OF CSR		12	S.CSR
		ADDRESS OF CURRENT I/O PACKET		14	S.PKT
		FORK BLOCK LINK WORD		16	S.FRK
		FORK - PC		20	
		FORK - R5		22	
		FORK - R4		24	
		FORK-DRIVER RELOCATION BASE		26	
		LINK WORD		30	S.MPR/M.LNK
		ADDRESS OF FIRST ASSIGNED UMR		32	M.UMRA
		NUMBER OF UMR'S ASSIGNED *4		34	M.UMRN
		LOW 16 BITS MAPPED BY 1ST UMR		36	M.UMVL
		HIGH 6 BITS OF BUFFER	HIGH 2 BITS MAPPED	40	M.UMVH
		LOW 16 BITS OF PHYSICAL BUFFER ADDRESS		42	M.VFVL

UMR  
ASSIGNMENT  
BLOCK  
M.UFVF

Figure 13-3 Status Control Block

## DEVICE DRIVER PROCESSING

### I/O Packet

- Used to communicate between Executive and device driver
- Created by Executive in DSR
- One for each I/O request queued to driver
- Each SCB has an I/O queue consisting of pending I/O packets

Linked from listhead S.LHD in the SCB

Linked in order of decreasing task priority

Packet is removed from queue when service begins

- Current I/O packet is linked from S.PKT in the SCB
- Contains

I.PRI - Priority of request

I.EFN - Event flag to use for synchronization

I.TCB - Address of TCB of requesting task

I.FCN - I/O function code

I.IOSB - I/O status block address

I.AST - Address of AST service routine

I.PRM - I/O parameter list

DEVICE DRIVER PROCESSING

I.EFN 3

<b>I/O QUEUE LINK WORD</b>		<b>0</b>	<b>I.LNK</b>
<b>EVENT FLAG NUMBER</b>	<b>REQUEST PRIORITY</b>	<b>2</b>	<b>I.PRI</b>
<b>TCB ADDRESS OF REQUESTER</b>		<b>4</b>	<b>I.TCB</b>
<b>POINTER TO SECOND LUT WORD</b>		<b>6</b>	<b>I.LN2</b>
<b>POINTER TO UNIT CONTROL BLOCK</b>		<b>10</b>	<b>I.UCB</b>
<b>MAIN FUNCTION CODE</b>	<b>MODIFIER</b>	<b>12</b>	<b>I.FCN</b>
<b>VIRTUAL ADDRESS OF I/O STATUS BLOCK</b>		<b>14</b>	<b>I.IOSB</b>
<b>RELOCATION BIAS (32<sub>10</sub>WORD BLOCK ADDRESS)</b>		<b>16</b>	
<b>KERNEL VIRTUAL ADDRESS (140000 + DIB)</b>		<b>20</b>	
<b>VIRTUAL ADDRESS OF AST ROUTINE</b>		<b>22</b>	<b>I.AST</b>
<b>RESERVED FOR MAPPING PARAMETER 1</b>		<b>24</b>	<b>I.PRM</b>
<b>PARAMETERS</b>		<b>26</b>	
_____			
	1-6		<b>30</b>
_____			<b>32</b>
_____			<b>34</b>
_____			<b>36</b>
_____			<b>40</b>

Figure 13-4 I/O Packet

DEVICE DRIVER PROCESSING

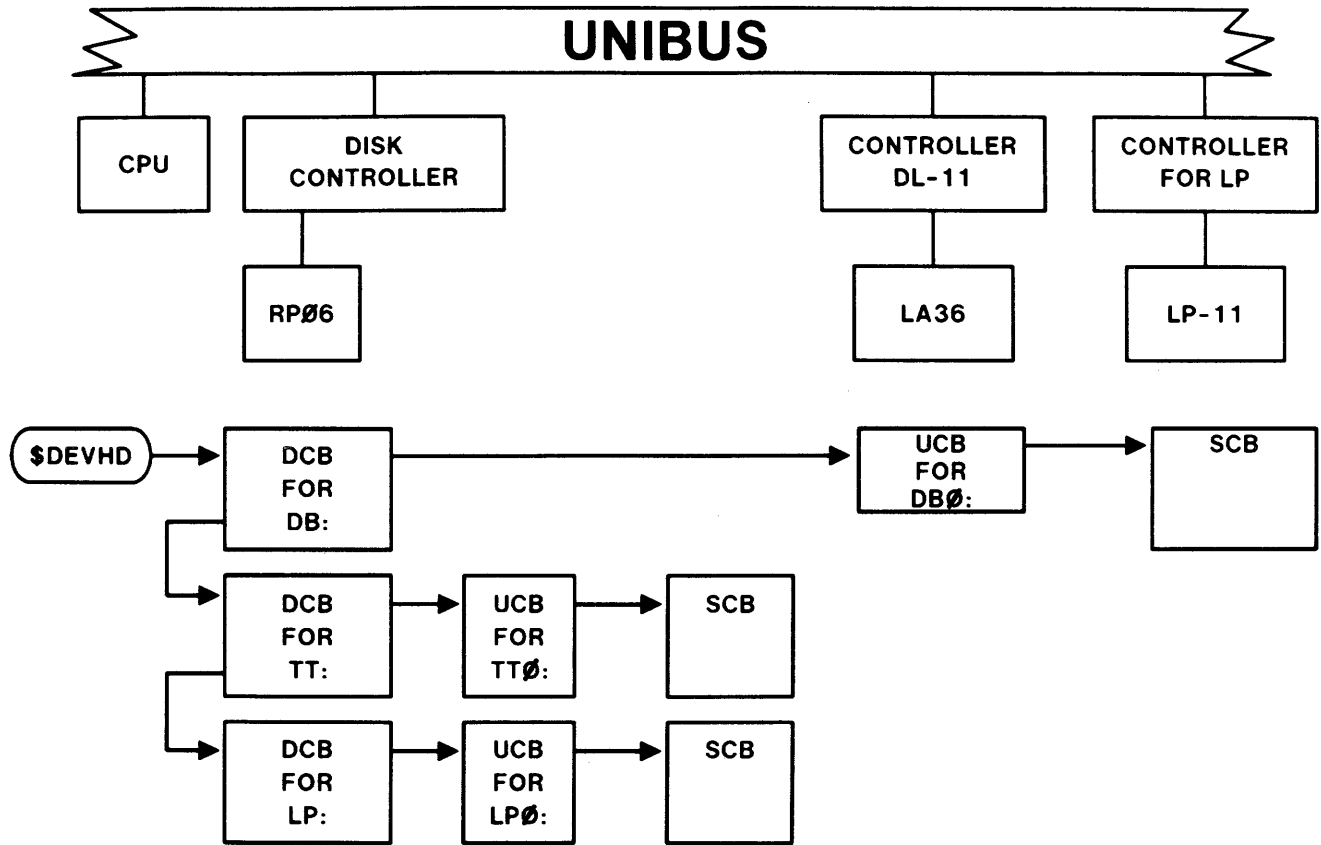


Figure 13-5 A Simple Configuration

DEVICE DRIVER PROCESSING

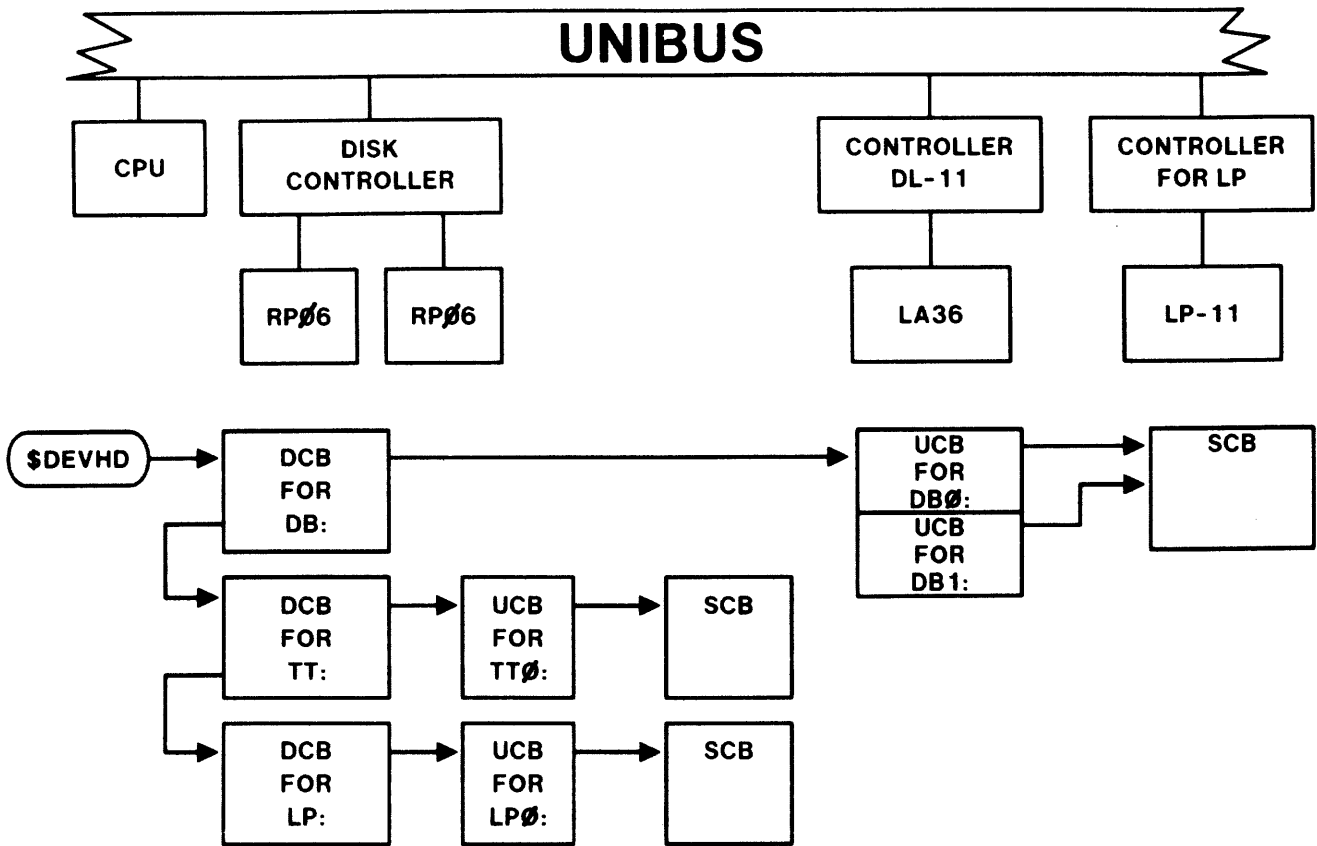


Figure 13-6 A Configuration with Multiple Units

DEVICE DRIVER PROCESSING

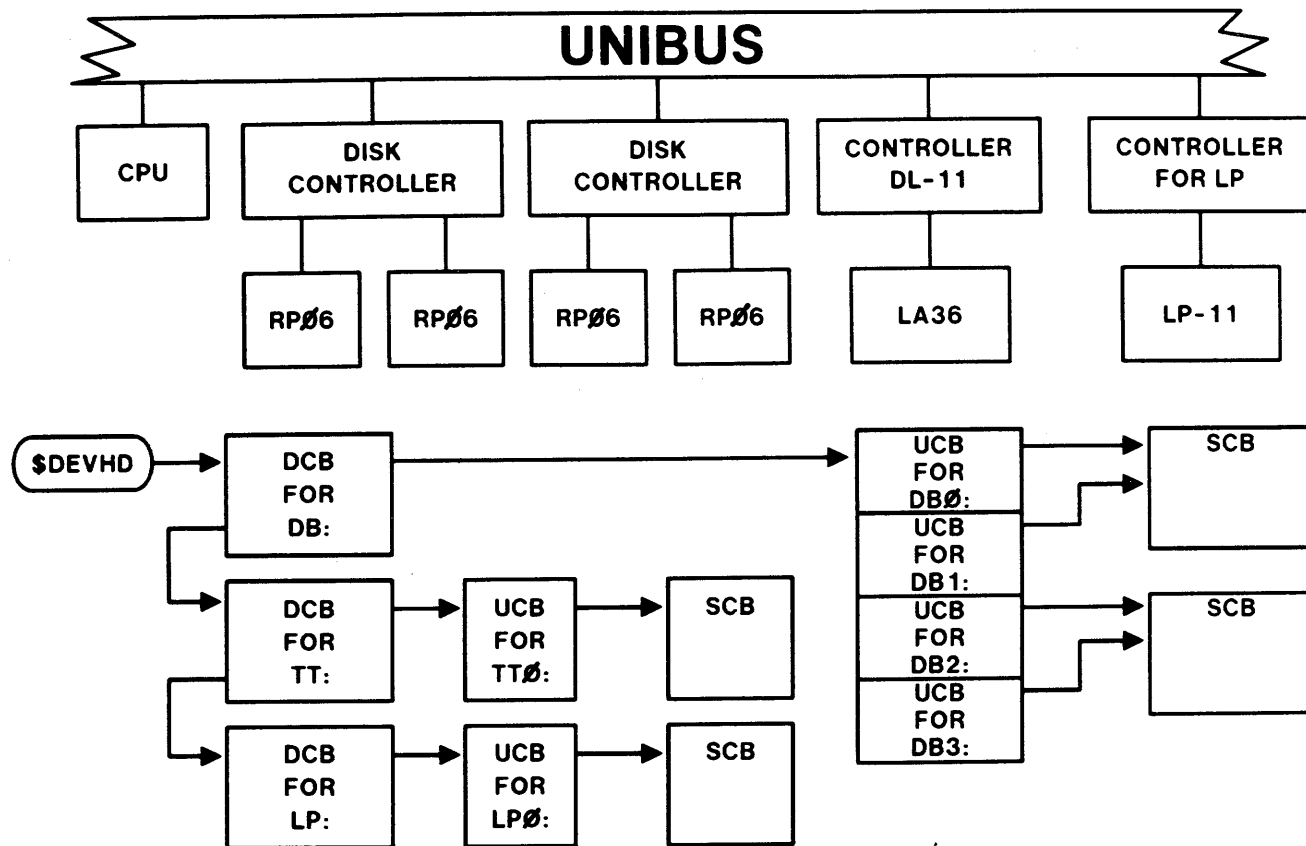


Figure 13-7 A Configuration with Multiple Controllers

## DRIVER STRUCTURE

### Driver Entry Points

- Initiate I/O Entry Point

Used to initiate an I/O operation  
Called from routine \$DRQIO  
Executes at processor priority 0  
Name of entry point: XXINI

- Kill I/O Entry Point

Cancels in-progress requests for non block-addressable devices

Called from routines \$DRQIO and \$DREIF

Executes at device priority

Name of entry point: XXCAN

- Time-out Entry Point

Used when driver does not interrupt within specified time interval after a request

Called from module TDSCH

Executes at device priority

Action: Retry I/O operation

After eight retries, I/O operation is aborted

Name of entry point: XXTMO

- Powerfail Entry Point

Called by module INITL and by SAVE to initialize device  
Reinitializes device after powerfail  
Called from routine POWER after power is restored  
Executes at processor priority 0  
Name of entry point: XXPWF



## DEVICE DRIVER PROCESSING

- Interrupt Entry Point

Services interrupts from device  
Address stored in interrupt vector  
Entered at processor priority 7  
Entry Point Names Critical

XXINT - Single interrupt driver  
XXINP - Input, two interrupt drivers  
XXOUT - Output, two interrupt drivers

### Driver Dispatch Table

- Table containing addresses of service routines for all entry points except the interrupt entry
- Table is in the device driver at location \$XXTBL

```
$XXTBL::  
        .WORD    XXINI    ;Initiate I/O  
        .WORD    XXCAN    ;Cancel I/O  
        .WORD    XXTMO    ;Device Timeout  
        .WORD    XXPWF    ;Powerfail
```

- Pointed to by D.DSP in the DCB
- Entries are local symbols whose order is critical

DEVICE DRIVER PROCESSING

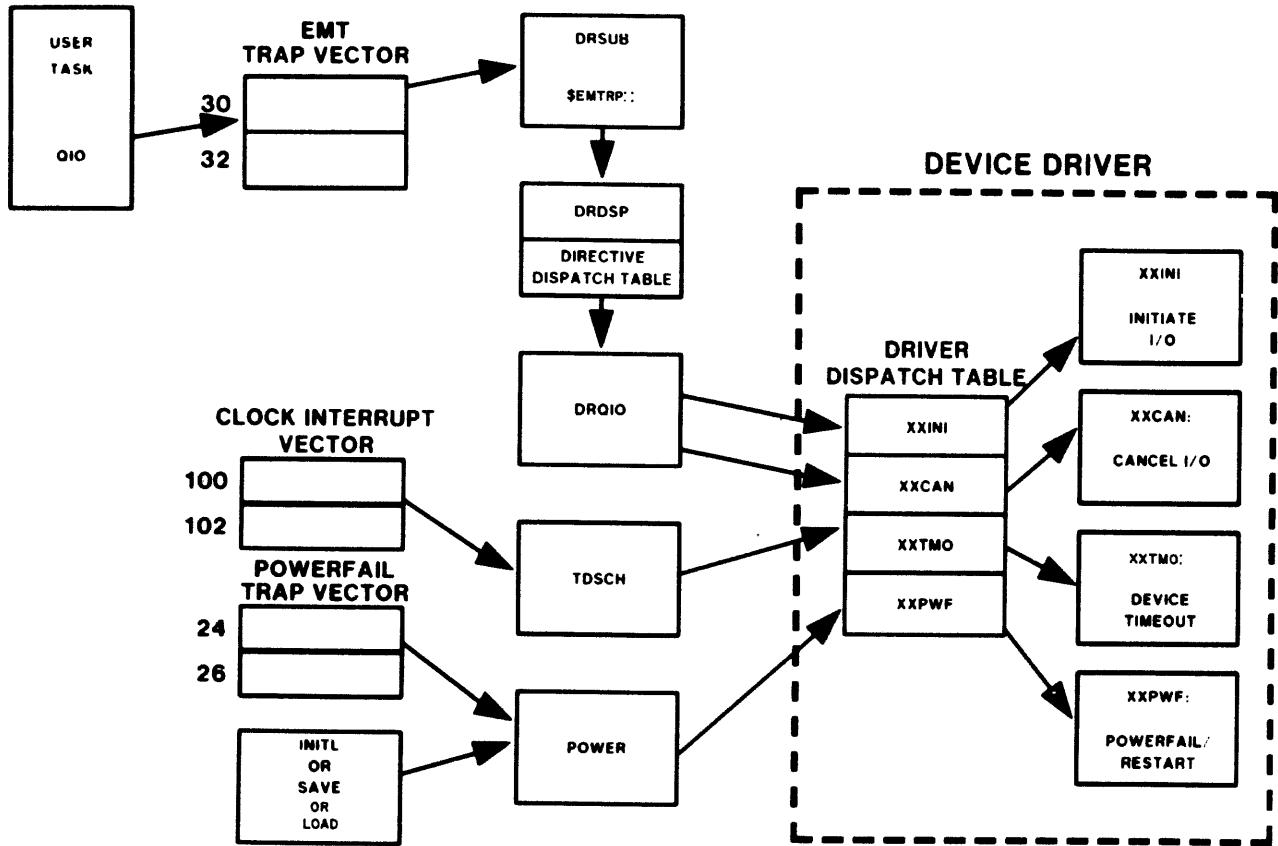


Figure 13-8 Driver Flow

# DEVICE DRIVER PROCESSING

```

        .TITLE   XXDRV
$XXTBL::
        .WORD    XXINI
        .WORD    XXCAN
        .WORD    XXTMO
        .WORD    XXPWF

XXINI:  CALL     $GTFKT
        BCC     .+4
        RETURN
        MOV     #IS.SUC&377,R0
        CLR    R1
        CALL   $IODON

XXCAN:
XXTMO:
XXPWF:
XXINT:: RETURN
        .END

```

Example 13-1 A Skeleton Driver



## DRIVER PROCESSING

### Initiate I/O

- Call \$GTPKT to get an I/O packet

Carry set on return from \$GTPKT

No packet

ACP function

Controller busy

- Registers on return from \$GTPKT

R1 - Address of I/O packet

R2 - Physical unit number

R3 - Controller index (into CNTBL)

R4 - Address of SCB

R5 - Address of UCB

- UCB address saved in CNTBL

- Perform initiation of I/O including

Allocating UMRs if a DMA device on 11/44 or 11/70

Setting up device timeout

If error logging, call \$BMSET

Checking function code

Performing operations on CSR(s)

Mapping UMR(s) if required

Enabling interrupts

## DEVICE DRIVER PROCESSING

### Kill I/O

- Registers when entry point called
  - R5 - Address of UCB
  - R4 - Address of SCB
  - R3 - Controller index
  - R1 - TCB of current task
  - R0 - Active I/O packet
  
- Processor is at device priority when called
- Cancel current I/O operation by
  - Zeroing byte-count or flagging abort
  - Canceling timeout by zeroing S.CTM in the SCB
  
- For DMA devices, current operation may not be canceled

## Device Timeout

- Registers when entry point called
  - R5 - Address of UCB
  - R4 - Address of SCB
  - R3 - Controller index
  - R2 - Address of CSR
  - R0 - I/O status code (IE.DNR)
  
- Processor at device priority when called
- Generate error message by calling \$DVMSG with T.NDNR in R0
- If error logging, call \$DTOER
- Reset timeout count if required
- Retry I/O operation required number of times

## Powerfail

- Registers when entry point is called
  - R5 - Address of UCB
  - R4 - Address of SCB
  - R3 - Controller index
- Processor at processor priority 0 when called
- Uses timeout mechanism for device recovery
  - Special timeout count is used for many devices
  - Performs other initialization tasks (e.g., the KMC-11 for the lineprinter)

## Interrupt Processing

- Registers R4 and R5 saved on entry, others cannot be used except in FORK process code
- Processor priority
  - At call: 7
  - After return from \$INTSV: Device priority
  - During FORK processing: 0



# DEVICE DRIVER PROCESSING

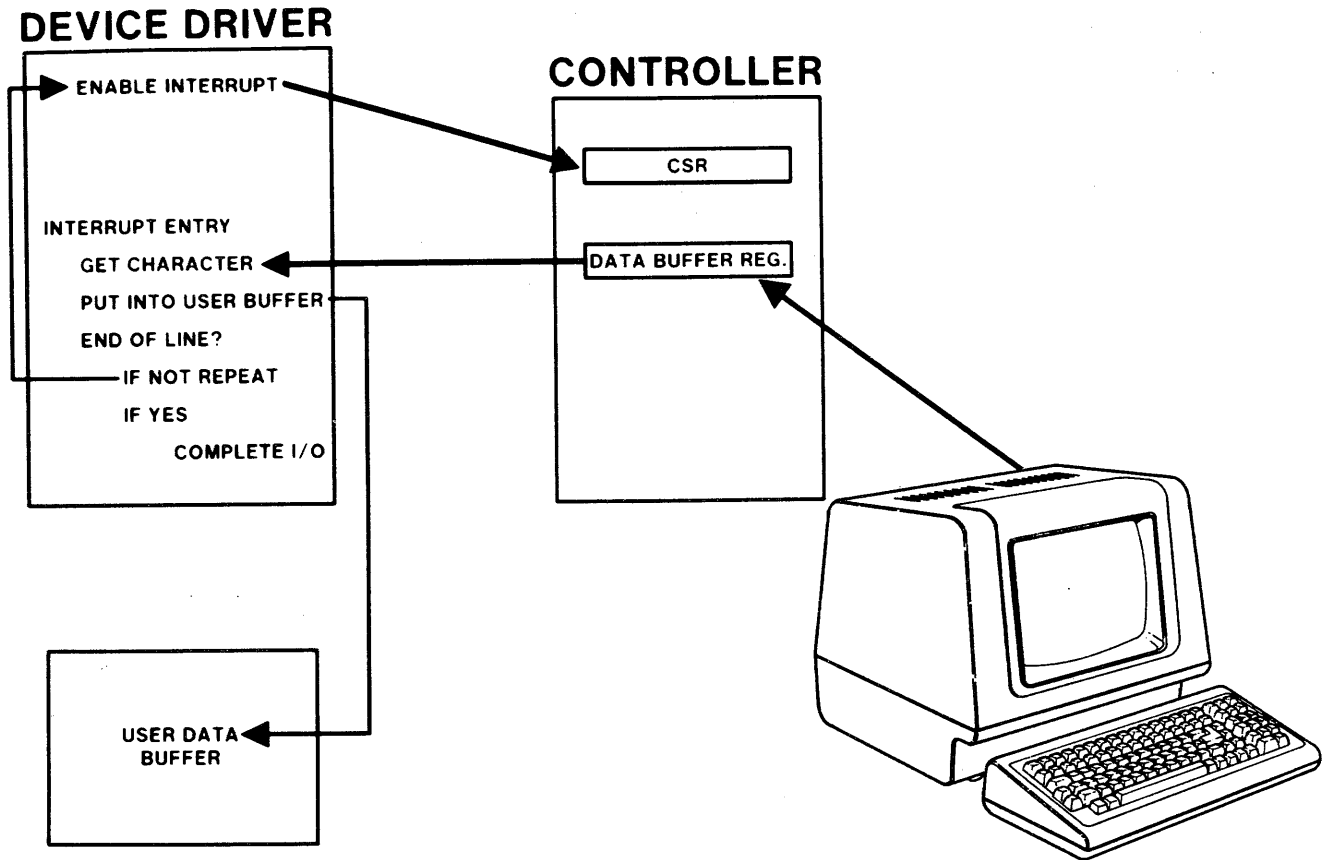


Figure 13-9 Interrupt Processing - Non DMA Device

DEVICE DRIVER PROCESSING

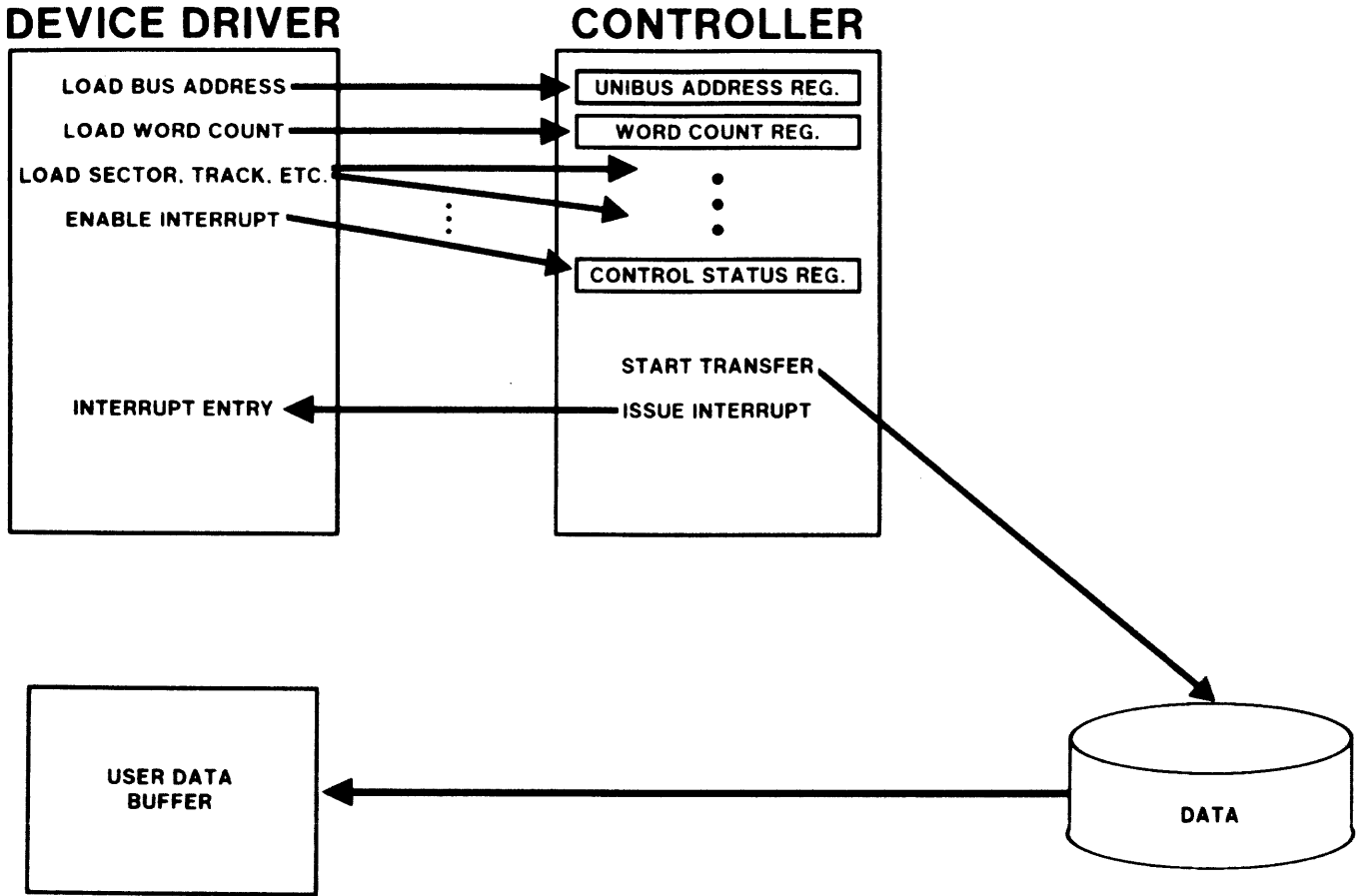


Figure 13-10 Interrupt Processing - DMA Device

## ADVANCED DRIVER FEATURES

### Loadable Drivers

- Not physically within the Executive, but in a user partition
- Frees part of KERNEL address space to be used to map added DSR
- LOAD command brings into memory
- UNLOAD command removes from memory
- Consists of three parts

Interrupt Control Block in DSR

Driver code loaded into driver partition

Driver Data Base loaded in DSR

### The Interrupt Control Block

- Created by LOAD command in DSR
- Contains

Location to which control is transferred by interrupt

Call to interrupt save routine, to save registers

Code to map driver code using KERNEL APR 5

DEVICE DRIVER PROCESSING

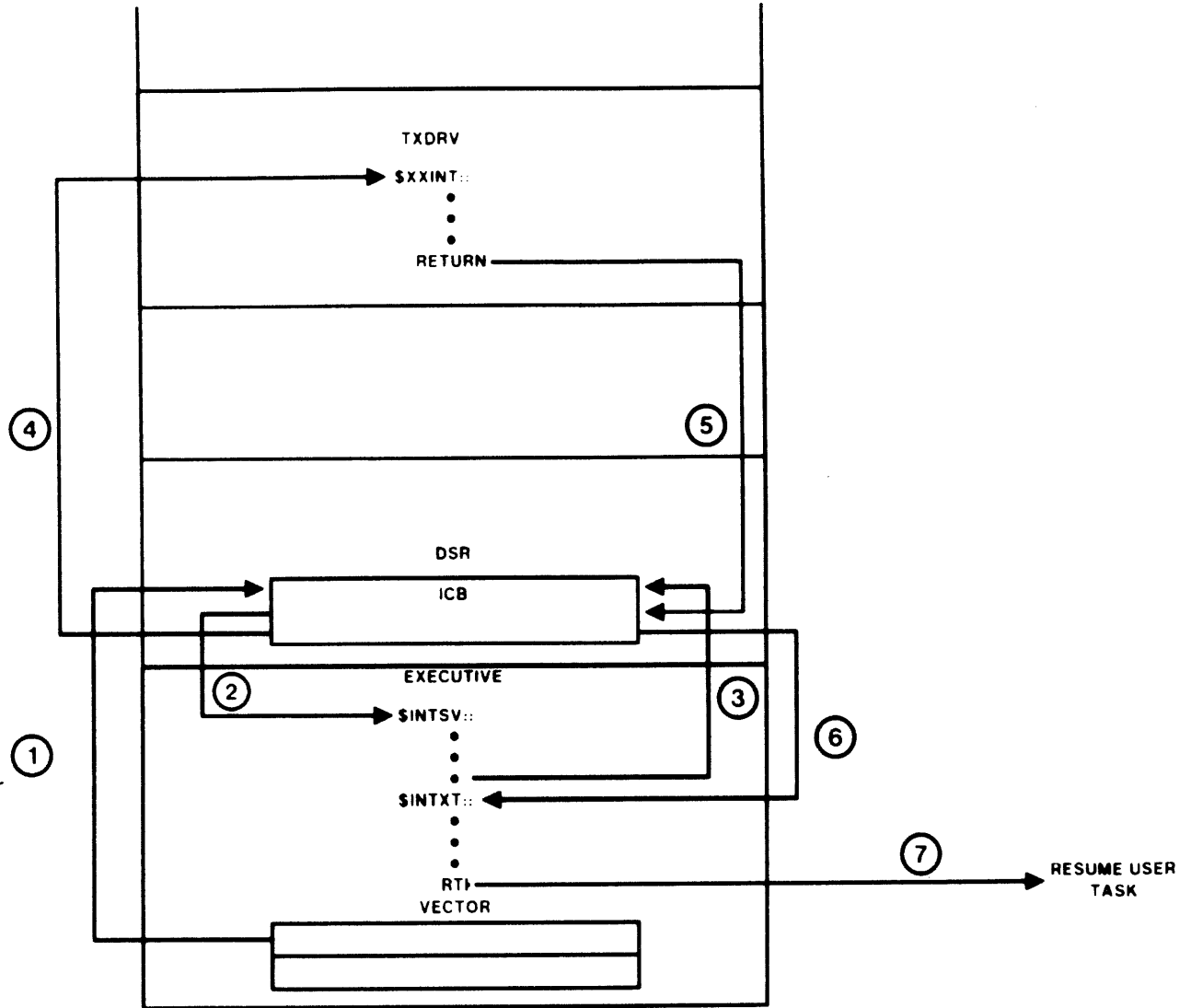


Figure 13-11 A Loadable Driver

DEVICE DRIVER PROCESSING

113767		
177776	MFPS TEMP	
50		
004537	JSR R5, @#\$INTSV	
ADDR OF \$INTSV		
177753(TYPICAL)	.WORD ↑ C <PR1>	
016704	MOV TEMP,R4 <sup>1</sup>	
000036		
043704	BIC↑C<17>,R4 <sup>1</sup>	
177760		
006304	ASL R4 <sup>1</sup>	
013746	MOV @#KISAR5, -(SP)	
172352		
012737		
DRIVER RELOCATION BIAS	MOV # RELBAS,@#KISAR5	
172352		
004737	JSR PC,@#INTSRV	
ADDRESS OF INTERRUPT SERVICE ROUTINE		
012637	MOV (SP)+,@#KISAR5	
172352		
000207	RETURN	
000000	TEMP:.BLKW	1 <sup>1</sup>

1. MULTI-CONTROLLER DRIVERS

Figure 13-12 The Interrupt Control Block

### **Resident and Loadable Data Base**

- Data base for loadable driver can be loadable or resident
- Resident data base created when system is built and included in the Executive
- Loadable data base can be created at any time
  - Loaded in DSR by LOAD command if not already in memory
  - Not unloaded by UNLOAD command

### **UNIBUS Mapping Registers**

#### Problem:

- Direct Memory Access (DMA) devices
  - Transfer data directly between the device and physical memory
  - Require physical address to be passed to UNIBUS
- In some PDP-11s, physical addresses require 22 bits
- UNIBUS accepts only 18-bit addresses

#### Solution:

- 31 UNIBUS Mapping Registers (UMRs) are provided
- Each UMR maps 4K words of physical memory
- 124K words of address space just below the I/O page are relocated using UMRs

# DEVICE DRIVER PROCESSING

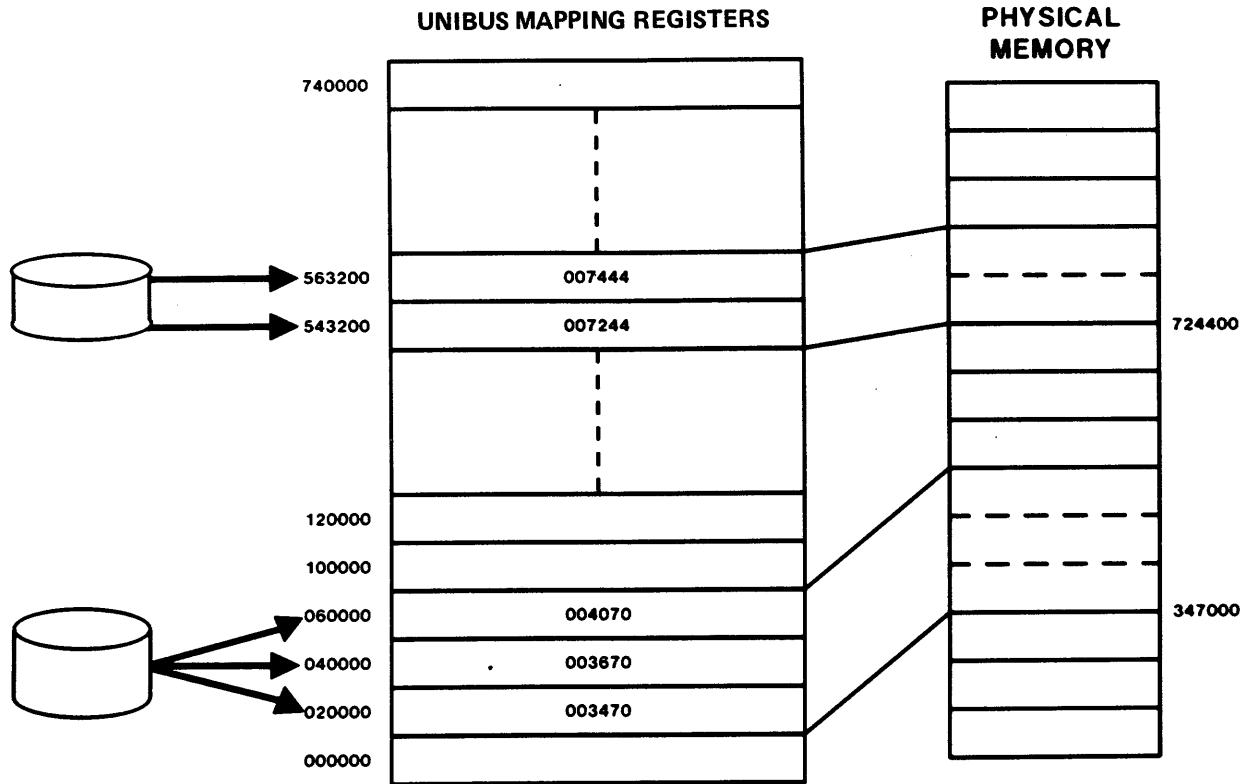


Figure 13-13 UNIBUS Mapping Registers

## DEVICE DRIVER PROCESSING

TRANSFER A BLOCK OF 8K WORDS

USER BUFFER ADDRESS = 1344200

UMR'S 3 AND 4 ARE TO BE USED

UMR STRUCTURE:

    BITS 13-17 = NUMBER OF UMR

    BITS 0 -12 = OFFSET TO BASE ADDRESS IN UMR

THEREFORE:

    UMR 3 = 13442

    UMR 4 = 13642

THE ADDRESS SUPPLIED TO THE UNIBUS IS 060000

Example 13-3 UMR Address Relocation



DEVICE DRIVER PROCESSING

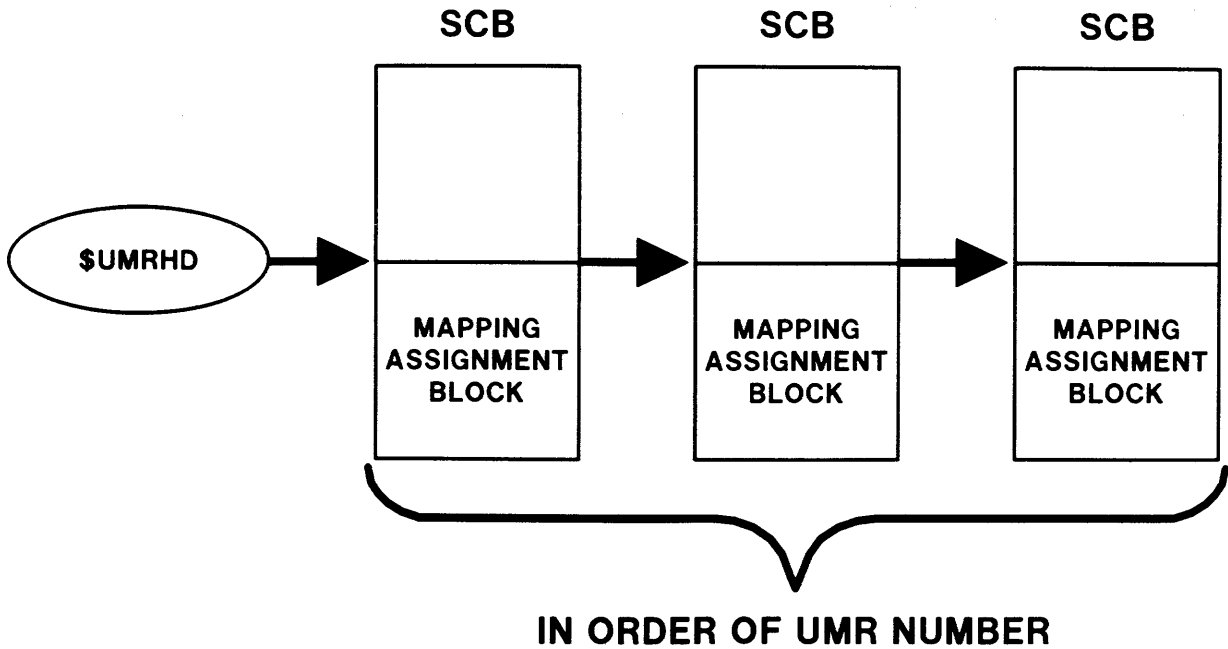


Figure 13-14 Mapping Assignment Block List

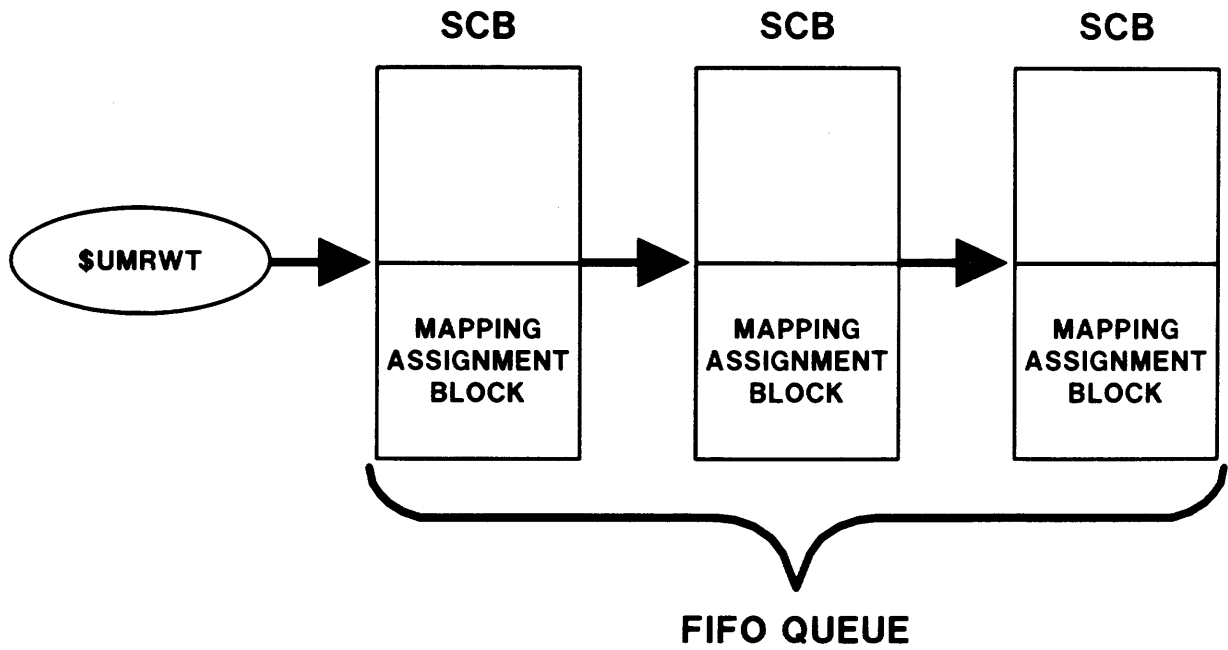


Figure 13-15 UMR Wait Queue

## CONNECT-TO-INTERRUPT

- Privileged task which contains interrupt service routine, ISR  
Task may or may not be mapped to Executive
- Connect-to-interrupt directive (CINT\$) used to set up interrupt service  
Interrupt Transfer Block (ITB) created in pool  
Address X.JSR in ITB loaded into PC of specified vector  
Vector must be greater than 60 and unused  
  
ITB contains code to map the ISR through KERNEL APR 5 and transfer control to it  
  
ITB also contains FORK block for ISR  
  
ITB linked to the ITB list of the task using T.CPCB in the TCB  
  
Task is made noncheckpointable and nonshufflable
- Connect-to-interrupt directive performs disconnect if issued with address of ISR equal to 0  
Task is made checkpointable and shufflable regardless of original status
- Interrupt service routine is limited to 4K words

DEVICE DRIVER PROCESSING

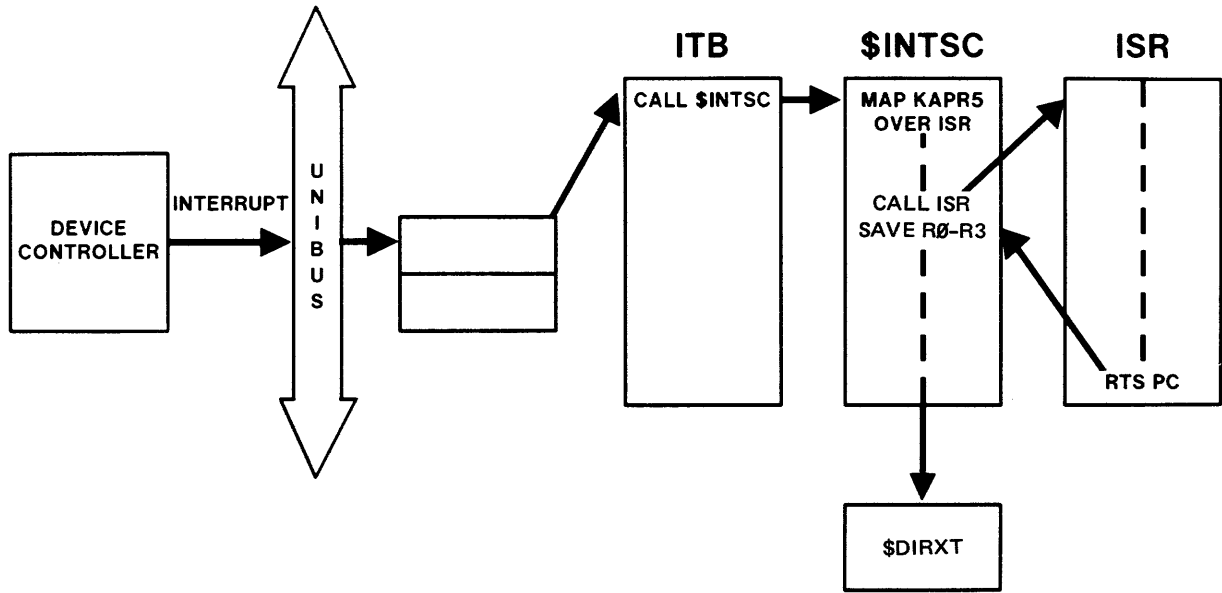
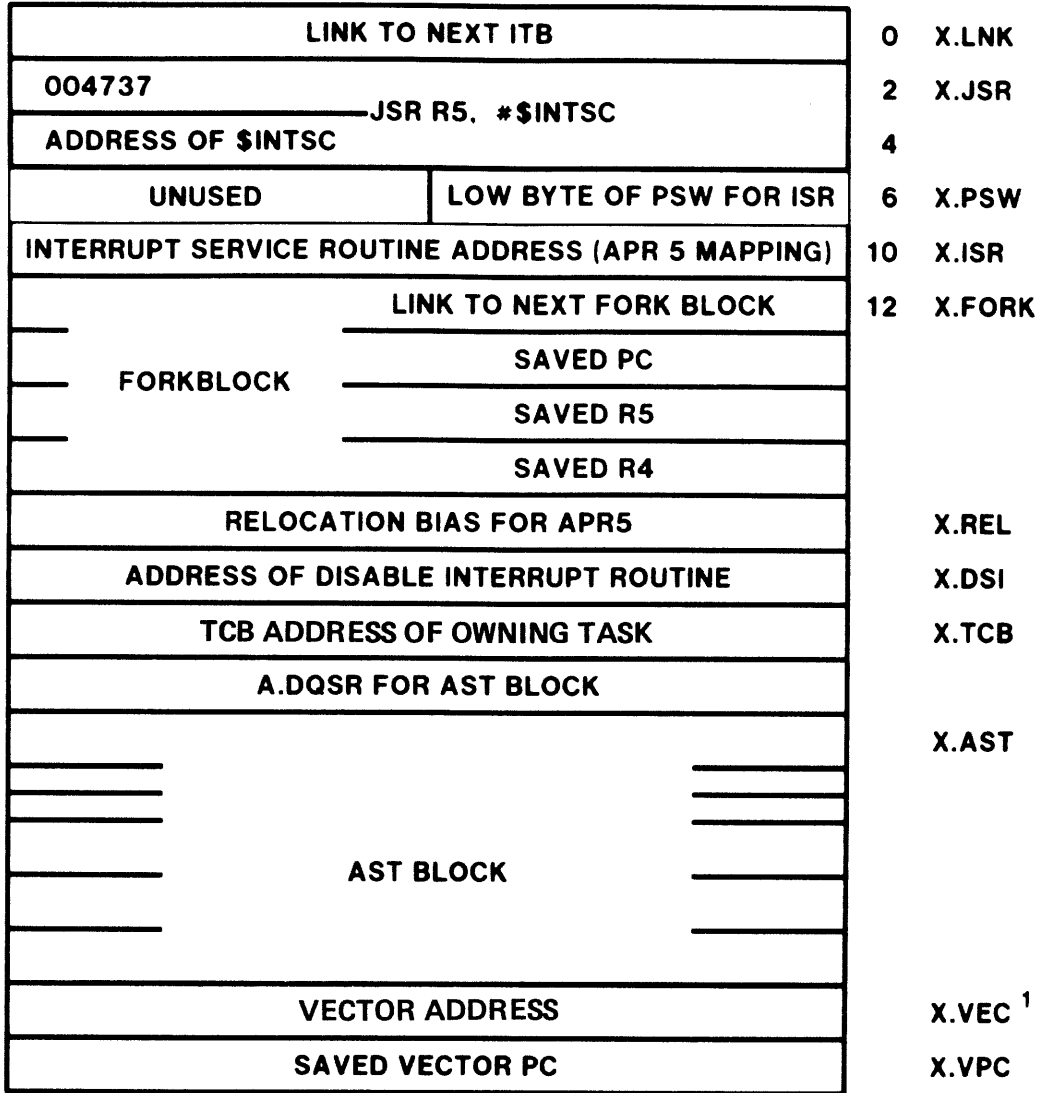


Figure 13-16 Connect-to-Interrupt Processing

DEVICE DRIVER PROCESSING



1. IF AST SUPPORT THIS IS FIRST AND ONLY AST PARAMETER

Figure 13-17 The Interrupt Transfer Block

## DEVICE DRIVER PROCESSING

```

.TITLE CTI
.IDENT /1.0/

$+
$ ** THIS TASK ILLUSTRATES THE CONNECT TO INTERRUPT VECTOR DIRECTIVE
$ THIS PRIVILEGED TASK CONNECTS TO A DR-11K. THERE IS A
$ LOCAL OPERATOR CONSOLE (LOC BOX) ATTACHED TO THE DR-11K
$ WHICH HAS 3 PUSH BUTTONS. THESE 3 SWITCHES WILL CAUSE
$ THE DR-11 TO INTERRUPT AND TO PERFORM THE FOLLOWING
$ OPERATIONS:
$
$ SWITCH 1 - THE INTERRUPT SERVICE ROUTINE
$ WILL SAMPLE THE TIME, AND STORE
$ THE NUMBER OF TICKS TO THE NEXT
$ SECOND IN A BUFFER.
$
$ SWITCH 2 - THE ISR QUEUES AN AST TO THIS TASK
$ WHICH WILL AVERAGE THE VALUES COLLECTED
$ IN THE ISR AND PRINT IT ON 'TI'.
$
$ SWITCH 3 - THE ISR SETS A LOCAL EVENT FLAG WHICH
$ CAUSES THIS TASK TO DISCONNECT FROM
$ THE VECTOR AND EXIT.
$
$--

.MCALL CINT$,EXIT$,QIOW$,ASTX$,WTSE$,DIR$
.NLIST BEX

$
$ DEFINITIONS FOR THE DR-11K
DRVEC = 230 ;VECTOR
DRCSR = 167770 ;CONTROL AND STATUS REGISTER
DRBUF = 167772 ;INPUT BUFFER REGISTER
SWTCH1 = 1 ;SWITCH 1
SWTCH2 = 2 ;SWITCH 2
SWTCH3 = 4 ;SWITCH 3
EF = 2 ;EVENT FLAG FOR TASK
BUFSIZ = 30. ;NUMBER OF SAMPLES TO STORE
$
CINT: CINT$ DRVEC,ISRBAS,DRINT,DREDIR,PR5,DRAST ;CONNECT
DCINT: CINT$ DRVEC ;DISCONNECT
WAIT: WTSE$ EF ;WAIT FOR EF
PRINT: QIOW$ IO.WVB,5,1,,, <MES,0,40> ;PRINT AVERAGE
FORMAT: .ASCIZ /NUMBER OF SAMPLES TAKEN %D. AVERAGE OF THE SAMPLES %D/
ERR: .ASCIZ /FAILED TO CONNECT TO VECTOR. DIRECTIVE STATUS = %D./
.EVEN
MES: .BLKB 100. ;FORMATTED MESSAGE
.ENABL LSB
$
$ MAIN LINE CODE
$ CONNECT TO DR-11K INTERRUPT VECTOR AN PUT TASK TO SLEEP BY
$ WAITING ON LOCAL EVENT FLAG 2
$
START:
CLR COUNT ;INIYIALIZE NUMBER OF SAMPLES
CLR BUFFER ;INITIALIZE SUM
DIR$ #CINT ;CONNECT TO INTERRUPT
BCS 10$ ;FAILED TO CONNECT
DIR$ #WAIT ;PUT TASK TO SLEEP
DIR$ #DCINT ;DISCONNECT
EXIT$S
$
$ CONNECT FAILED - PRINT ERROR MESSAGE
$
10$: MOV #MES,R0 ;OUTPUT BUFFER
MOV #ERR,R1 ;FORMAT SPECIFICATION

```

Example 13-4 Sample Connect-to-Interrupt Routine  
(Sheet 1 of 3)

DEVICE DRIVER PROCESSING

```

MOV     $#DSW,R2           ;VALUE TO BE CONVERTED
CALL    $EDMSG             ;FORMAT MESSAGE
MOV     R1,PRINT+Q,IOPL+2 ;NUMBER OF BYTES IN MESSAGE
DIR$    #PRINT             ;PRINT ERROR MESSAGE
EXIT$S

;
;
;   AST WILL AVERAGE THE TIME SAMPLES AND PRINT ON TI
;
DRAST:
MOV     COUNT,R0           ;NUMBER OF SAMPLES
BEQ     35$                ;SKIP AVERAGING
CLR     R1                 ;ACCUMULATE SUM IN R1
MOV     #BUFFER,R2        ;SAMPLES TO SUM
15$:   MOVB    (R2)+,R3     ;GET SAMPLE
BIC     #177400,R3        ;DON'T SIGN EXTEND
ADD     R3,R1             ;ADD INTO TOTAL
SOB     R0,15$           ;GET NEXT VALUE
DIV     COUNT,R0         ;GET AVERAGE
MOV     R1,BUFFER        ;STORE QUOTIENT
35$:   MOV     #MES,R0     ;OUTPUT STRING
MOV     #FORMAT           ;FORMAT SPECIFICATION
MOV     #COUNT,R2       ;NUMBERS TO CONVERT
CALL    $EDMSG           ;CONVERT MESSAGE
MOV     R1,PRINT+Q,IOPL+2 ;NUMBER OF BYTES TO PRINT
DIR$    #PRINT           ;WRITE SAMPLE AVERAGE
TST     (SP)+            ;POP VECTOR ADDRESS
CLR     BUFFER           ;RE-INITIALIZE SUM
CLR     COUNT           ;AND COUNT OF SAMPLES
ASTX$S                    ;EXIT AST

;
;   ISRBAS DEFINES THE BASE ADDRESS OF A 4K-WORD AREA THE
;   EXECUTIVE WILL MAP WITH KERNEL APR5. THIS AREA MUST
;   CONTAIN THE INTERRUPT SERVICE ROUTINE, THE ENABLE/DISABLE
;   INTERRUPT ROUTINE, AND ANY DATA AREAS THAT THESE ROUTINES
;   WILL REFERENCE.
;
ISRBAS:
;   DATA BUFFERS NEEDED BY ISR
COUNT: .WORD    0           ;NUMBER OF SAMPLES
BUFFER:  .BLKB   BUFSIZ     ;BUFFER FOR INPUTS
        .EVEN

;
;   ENABLE/DISABLE INTERRUPTS ROUTINE
;   AUTOMATICALLY CALLED UNDER 3 CONDITIONS
;   1.  WHEN THE TASK CONNECTS TO AN INTERRUPT VECTOR
;       TO ENABLE INTERRUPTS.
;   2.  WHEN THE TASK DISCONNECTS FROM THE INTERRUPT
;       VECTOR TO DISABLE INTERRUPTS.
;   3.  WHEN THE TASK IS ABORTED TO DISABLE INTERRUPTS.
;
DREDIR: BCS     20$        ;IF CS DISABLE INTERRUPTS
        BIS     #100,@#DRCSR ;ENABLE INTERRUPTS
        RETURN   ;AND OUT
20$:   DIC     #100,@#DRCSR ;DISABLE INTERRUPTS
        RETURN   ;AND OUT

;
;   INTERRUPT SERVICE ROUTINE
;
;   THE ISR IS ENTERED AT PRIORITY 5 (SPECIFIED ON CINT$) WITH
;   R4 = SAVED AND FREE TO BE USED
;   R5 = ADDRESS OF FORK BLOCK IN THE ITB
;
DRINT:  BIT     #SWTCH1,@#DRBUF ;;;INPUT BUFFER REQUEST?

```

Example 13-4 Sample Connect-to-Interrupt Routine  
(Sheet 2 of 3)

DEVICE DRIVER PROCESSING

```

BEQ      30$          ;;;IF EQ, NO
CMP      #BUFSIZ,COUNT ;;;YES, BUFFER FULL?
BEQ      50$          ;;;IF EQ, YES
MOV      COUNT,R4    ;;;IF NE, NO
ADD      PC,R4       ;;;CALCULATE BUFFER
ADD      #BUFFER-,R4 ;;;PIC ADDRESS TO STORE SAMPLE
MOVB    @##TTNS,(R4) ;;;LOW BYTE OF TICKS TILL NEXT SECOND
INC      COUNT       ;;;INCREMENT NUMBER OF SAMPLES
BR       50$         ;;;EXIT FROM INTERRUPT

$
$   INTERRUPT WAS FROM SWITCH 2 OR 3
$
30$:    CALL    @##FORK2      ;;;CREATE A SYSTEM PROCESS
        CLR      (R3)        ;DECLARE THE FORK BLOCK FREE
        BIT      #SWTCH3,@#DRBUF ;DISCONNECT FROM INTERRUPT?
        BNE     40$         ;IF NE, YES

$
$   SWITCH 2 => QUEUE AN AST TO THE TASK
$
        CALL    @##QASTC    ;QUEUE AN AST
        BR      50$         ;EXIT FROM INTERRUPT

$
$   SWITCH 3 => DISCONNECT FROM INTERRUPTS.
$   SET LOCAL EVENT FLAG 2 TO WAKE UP TASK LEVEL CODE TO
$   ISSUE THE DISCONNECT
$
40$:    MOV      #EF,R0      ;EVENT FLAG 2 TO BE SET
        MOV      X.TCB-X.FORK(R5),R5 ;R5 POINTS TO THE TCB OF TASK
        CALL    @##SETF    ;EXEC SUBROUTINE SETF
        RETURN          ;EXIT INTERRUPT

$
$   EXIT FROM INTERRUPT.  TURN INTERRUPT BACK ON.
$
50$:    BIS      #100,@#DRCSR ;TURN ON INTERRUPTS
        RETURN          ;EXIT FROM INTERRUPT

$
$   ENSURE ISR + DATA + ENABLE/DISABLE SURBOUTINES FIT IN 4K
$
        .IIF    .LT,<20000 - <. - ISRBAS>> .ERROR
        .END     START

```

Example 13-4 Sample Connect-to-Interrupt Routine  
(Sheet 3 of 3)

